## Discrete Mathematics (2009 Spring) Graphs (Chapter 9, 5 hours)

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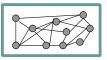
└─Chapter 9 Graphs └─§9.1 Graphs and Graph Models

## What are Graphs?

 General meaning in everyday math: A plot or chart of numerical data using a coordinate system.



 Technical meaning in discrete mathematics: A particular class of discrete structures (to be defined) that is useful for representing relations and has a convenient webby-looking graphical representation.



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• Correspond to symmetric binary relations *R*.



Visual Representation of a Simple Graph

- A simple graph G = (V, E) consists of:
  - A set V of vertices or nodes (V corresponds to the universe of the relation R).
  - 2 A set *E* of edges / arcs / links: unordered pairs of [distinct?] elements  $u, v \in V$ , such that uRv.

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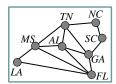
## Example of a Simple Graph

• Let V be the set of states in the far-southeastern U.S.:

$$V = \{FL,GA,AL,MS,LA,SC,TN,NC\}.$$

Let

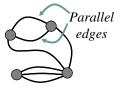
$$E = \{\{u, v\} \mid u \text{ adjoins } v\} \\ = \begin{cases} \{FL,GA\}, \{FL,AL\}, \{FL,MS\}, \{FL,LA\}, \{GA,AL\}, \\ \{AL,MS\}, \{MS,LA\}, \{GA,SC\}, \{GA,TN\}, \{SC,NC\}, \\ \{NC,TN\}, \{MS,TN\}, \{MS,AL\} \end{cases}$$



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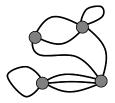
## Multigraphs

- Like simple graphs, but there may be more than one edge connecting two given nodes.
- A multigraph G = (V, E, f) consists of a set V of vertices, a set E of edges (as primitive objects), and a function f : E → {{u, v} | u, v ∈ V ∧ u ≠ v}}.
- E.g., nodes are cities, edges are segments of major highways.



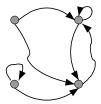
## Pseudographs

- Like a multigraph, but edges connecting a node to itself are allowed.
- A pseudograph G = (V, E, f) where  $f : E \rightarrow \{\{u, v\} \mid u, v \in V\}$ . Edge  $e \in E$  is a loop if  $f(e) = \{u, u\} = \{u\}$ .
- E.g., nodes are campsites in a state park, edges are hiking trails through the woods.



## **Directed Graphs**

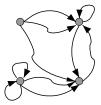
- Correspond to arbitrary binary relations R, which need not be symmetric.
- A directed graph (V, E) consists of a set of vertices V and a binary relation E on V.
- E.g.:  $V = \text{people}, E = \{(x, y) \mid x \text{ loves } y\}.$



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## Directed Multigraphs

- Like directed graphs, but there may be more than one arc from a node to another.
- A directed multigraph G = (V, E, f) consists of a set V of vertices, a set E of edges, and a function f : E → V × V.
- E.g., V = web pages, E = hyperlinks. The WWW is a directed multigraph.



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## Types of Graphs: Summary

- Summary of the book's definitions.
- Keep in mind this terminology is not fully standardized...

Term	Edge type	Multiple edges?	Self-loops?
Simple graph	Undir.	No	No
Multigraph	Undir.	Yes	No
Pseudograph	Undir.	Yes	Yes
Directed graph	Directed	No	Yes
Directed multigraph	Directed	Yes	Yes

Chapter 9 Graphs

└§9.2 Graph Terminology and Special Types of Graphs



 Adjacent, connects, endpoints, degree, initial, terminal, in-degree, out-degree, complete, cycles, wheels, n-cubes, bipartite, subgraph, union.

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Chapter 9 Graphs

└§9.2 Graph Terminology and Special Types of Graphs

## Adjacency

- In an undirected graph G, if u and v are two nodes and
   e = {u, v} is an edge in G, then we may say
  - The vertices *u* and *v* are *adjacent* (or *neighbors*).
  - The vertices *u* and *v* are *endpoints* of the edge *e*.
  - The edge *e* is *incident* with the vertices *u* and *v*.

The edge *e connects* the vertices *u* and *v*.

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#### Degree of a Vertex

- Let G be an undirected graph,  $v \in V$  a vertex.
- The degree of v, denoted by deg(v), is its number of incident edges. (Except that any self-loops are counted twice.)

- A vertex with degree 0 is *isolated*.
- A vertex of degree 1 is *pendant*.

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#### Handshaking Theorem

Let G be an undirected (simple, multi-, or pseudo-) graph with vertex set V and edge set E. Then

$$\sum_{v \in V} \deg(v) = 2 |E|.$$

Corollary Any undirected graph has an even number of vertices of odd degree.

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#### **Directed Adjacency**

Let G be a directed (possibly multi-) graph, and e = (u, v) be an edge of G. Then we say:

- *u* is adjacent to *v*; *v* is adjacent from *u*.
- e comes from u; e goes to v.
- e connects u to v; e goes from u to v.
- The *initial vertex* of *e* is *u*.
- The *terminal vertex* of *e* is *v*.

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#### **Directed Degree**

• Let G be a directed graph, and v a vertex of G.

- The *in-degree* of v, denoted by deg<sup>-</sup>(v), is the number of edges going to v.
- The out-degree of v, denoted by deg<sup>+</sup>(v), is the number of edges coming from v.
- The degree of v, deg(v) = deg<sup>-</sup>(v) + deg<sup>+</sup>(v), is the sum of v's in-degree and out-degree.

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### Directed Handshaking Theorem

Let G be a directed (possibly multi-) graph with vertex set V and edge set E. Then:

$$\sum_{v \in V} \mathsf{deg}^{-}\left(v\right) = \sum_{v \in V} \mathsf{deg}^{+}\left(v\right) = \frac{1}{2} \sum_{v \in V} \mathsf{deg}\left(v\right) = \left|E\right|.$$

Note that the degree of a node is unchanged by whether we consider its edges to be directed or undirected.

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### Special Graph Structures

Special cases of undirected graph structures:

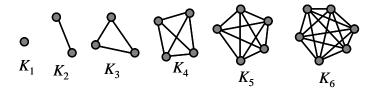
- Complete graphs  $K_n$ .
- Cycles  $C_n$ .
- Wheels  $W_n$ .
- *n*-Cubes Q<sub>n</sub>.
- Bipartite graphs.
- Complete bipartite graphs  $K_{m,n}$ .

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## Complete Graphs

■ For any n ∈ N, a complete graph on n vertices, K<sub>n</sub>, is a simple graph with n nodes in which every node is adjacent to every other node:

$$\forall u, v \in V : u \neq v \leftrightarrow \{u, v\} \in E.$$



• Note that  $K_n$  has  $\sum_{i=1}^{n-1} i = \frac{n(n-1)}{2}$  edges.

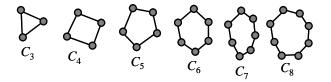
**Discrete Mathematics** 

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### Cycles

• For any  $n \ge 3$ , a cycle on *n* vertices,  $C_n$ , is a simple graph where  $V = \{v_1, v_2, \dots, v_n\}$  and  $E = \{\{v_1, v_2\}, \{v_2, v_3\}, \dots, \{v_{n-1}, v_n\}, \{v_n, v_1\}\}$ .



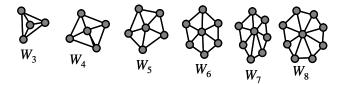
• How many edges are there in  $C_n$ ?

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#### Wheels

■ For any n ≥ 3, a wheel W<sub>n</sub>, is a simple graph obtained by taking the cycle C<sub>n</sub> and adding one extra vertex v<sub>hub</sub> and n extra edges {{v<sub>hub</sub>, v<sub>1</sub>}, {v<sub>hub</sub>, v<sub>2</sub>}, ..., {v<sub>hub</sub>, v<sub>n</sub>}}.



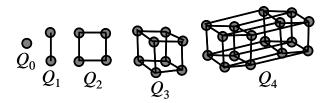
■ How many edges are there in W<sub>n</sub>?

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## n-Cubes (hypercubes)

■ For any n ∈ N, the hypercube Q<sub>n</sub> is a simple graph consisting of two copies of Q<sub>n-1</sub> connected together at corresponding nodes. Q<sub>0</sub> has 1 node.



- Number of vertices:  $2^n$ .
- Number of edges: Exercise to try!

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## n-Cubes (hypercubes) Cont.

■ For any *n* ∈ *N*, the hypercube *Q<sub>n</sub>* can be defined recursively as follows:

• 
$$Q_0 = \{\{v_0\}, \emptyset\}$$
 (one node and no edges).  
• For any  $n \in N$ , if  $Q_n = (V, E)$ , where  $V = \{v_1, \dots, v_a\}$  and  $E = \{e_1, \dots, e_b\}$ , then  $Q_{n+1} = (V_{Q_{n+1}}, E_{Q_{n+1}})$  is given by  
•  $V_{Q_{n+1}} = V \cup \{v'_1, \dots, v'_a\}$  where  $v'_1, \dots, v'_a$  are new vertices.  
•  $E_{Q_{n+1}} = E \cup \{e'_1, \dots, e'_b\} \cup \{\{v_1, v'_1\}, \{v_2, v'_2\}, \dots, \{v_a, v'_a\}\}$   
where if  $e_i = \{v_j, v_k\}$  then  $e'_i = \{v'_j, v'_k\}$ .

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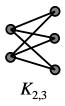
How many edges are there in an n-cube?

└─§9.2 Graph Terminology and Special Types of Graphs

# Bipartite Graphs

- A simple graph *G* = (*V*, *E*) is called *bipartite* if *V* can be partitiovned into two disjoint sets *V*<sub>1</sub> and *V*<sub>2</sub> such tht every edge in the graph connects a vertex in *V*<sub>1</sub> and a vertex in *V*<sub>2</sub>.
- Complete bipartite graphs



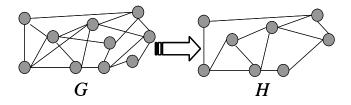


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## Subgraphs

A subgraph of a graph G = (V, E) is a graph H = (W, F)where  $W \subseteq V$  and  $F \subseteq E$ .



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└§9.2 Graph Terminology and Special Types of Graphs



The union  $G_1 \cup G_2$  of two simple graphs  $G_1 = (V_1, E_1)$  and  $G_2 = (V_2, E_2)$  is the simple graph  $(V_1 \cup V_2, E_1 \cup E_2)$ .

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Chapter 9 Graphs

└\_§9.3 Representing Graphs and Graph Isomorphism

#### What Will Be Given?

- Graph representations
  - Adjacency lists.
  - Adjacency matrices.
  - Incidence matrices.
- Graph isomorphism
  - Two graphs are isomorphic iff they are identical except for their node names.

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Chapter 9 Graphs

└\_§9.3 Representing Graphs and Graph Isomorphism

## Adjacency Lists

 Adjacency Lists: A table with 1 row per vertex, listing its adjacent vertices.

	Vertex	Adjacent Vertices
	а	Ь, с
	Ь	a, c, e, f a, b, f
	с	a, b, f
	d	
e	е	b
$\mathbf{V} \mathbf{f}$	f	b, c

 Directed Adjacency Lists: listing the terminal nodes of each edge incident from that node. Chapter 9 Graphs

└\_§9.3 Representing Graphs and Graph Isomorphism

#### Represented by Matrices

- Adjacency Matrices: Matrix  $\mathbf{A} = [a_{ij}]$ , where  $a_{ij}$  is 1 if  $\{v_i, v_j\}$  is an edge of G, 0 otherwise.
- Incidence Matrices: Matrix  $\mathbf{M} = [m_{ij}]$ , where  $m_{ij}$  is 1 if edge  $e_i$  is incident with  $v_i$ , 0 otherwise.

$$\mathbf{M} = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \end{bmatrix} \mathbf{M} = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Chapter 9 Graphs

└\_§9.3 Representing Graphs and Graph Isomorphism

## Graph Isomorphism

#### Definition

Simple graphs  $G_1 = (V_1, E_1)$  and  $G_2 = (V_2, E_2)$  are *isomorphic* if and only if  $\exists$  a bijection  $f : V_1 \to V_2$  such that  $\forall a, b \in V_1$ , a and b are adjacent in  $G_1$  iff f(a) and f(b) are adjacent in  $G_2$ .

- f is the "renaming" function that makes the two graphs identical.
- The definition can easily be extended to other types of graphs.

Chapter 9 Graphs

└\_§9.3 Representing Graphs and Graph Isomorphism

## Graph Invariants under Isomorphism

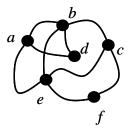
- *Necessary* but not *sufficient* conditions for *G*<sub>1</sub> = (*V*<sub>1</sub>, *E*<sub>1</sub>) to be isomorphic to *G*<sub>2</sub> = (*V*<sub>2</sub>, *E*<sub>2</sub>).
  - $|V_1| = |V_2|, |E_1| = |E_2|.$
  - The number of vertices with degree n is the same in both graphs.
  - For every proper subgraph *H* of one graph, there is a proper subgraph of the other graph that is isomorphic to *H*.

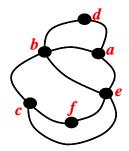
Chapter 9 Graphs

└\_§9.3 Representing Graphs and Graph Isomorphism

#### Examples of Isomorphism

 If isomorphic, label the 2nd graph to show the isomorphism, else identify difference.



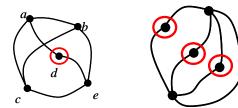


Chapter 9 Graphs

└\_§9.3 Representing Graphs and Graph Isomorphism

### Are These Isomorphic?

 If isomorphic, label the 2nd graph to show the isomorphism, else identify difference.



- Same # of vertices.
- Same # of edges.
- Different # of vertices of degree 2! (1 vs 3)

Chapter 9 Graphs

### Paths

#### Paths in undirected graphs

- In an undirected graph, a path of length n from u to v is a sequence of adjacent edges going from vertex u to vertex v.
- A path is a *circuit* if u = v.
- A path *traverses* the vertices along it.
- A path is *simple* if it contains no edge more than once.
- Paths in directed graphs
  - Same as in undirected graphs, but the path must go in the direction of the arrows.



- An undirected graph is *connected* iff there is a path between every pair of distinct vertices in the graph.
- Connected component: connected subgraph
- A cut vertex or cut edge separates 1 connected component into 2 if removed.

#### Theorem

There is a simple path between any pair of vertices in a connected undirected graph.

└─ Chapter 9 Graphs └─§9.4 Connectivity

## Directed Connectedness

- A directed graph is *strongly connected* iff there is a directed path from *a* to *b* for any two vertices *a* and *b*.
- It is weakly connected iff the underlying undirected graph (i.e., with edge directions removed) is connected.

Note strongly implies weakly but not vice-versa.

Chapter 9 Graphs

## Paths & Isomorphism

 Note that connectedness, and the existence of a circuit or simple circuit of length k are graph invariants with respect to isomorphism.

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└─ Chapter 9 Graphs └─ §9.4 Connectivity

# Counting Paths Using Adjacency Matrices

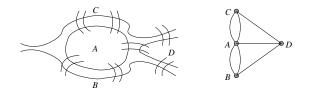
- Let **A** be the adjacency matrix of graph *G*.
- The number of paths of length k from  $v_i$  to  $v_j$  is equal to  $(\mathbf{A}^k)_{ij}$ . (The notation  $(\mathbf{M})_{ij}$  denotes  $m_{ij}$  where  $[m_{ij}] = \mathbf{M}$ .)

Chapter 9 Graphs

└-§9.5 Euler and Hamilton Paths

#### Euler Paths and Circuits

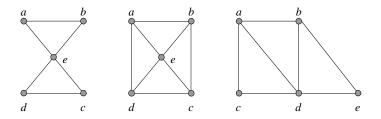
- An Euler path in G is a simple path containing every edge of G.
- An *Euler circuit* in a graph G is a simple circuit containing every edge of G.



Chapter 9 Graphs

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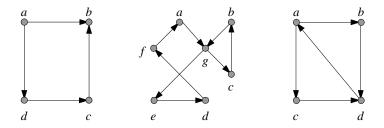




Chapter 9 Graphs

└\_§9.5 Euler and Hamilton Paths





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Chapter 9 Graphs

└\_§9.5 Euler and Hamilton Paths

# Necessary and Sufficient Conditions for Euler Circuits and Paths

Theorem

A connected multigraph has an Euler circuit iff each vertex has even degree.

#### Theorem

A connected multigraph has an Euler path (but not an Euler circuit) iff it has exactly 2 vertices of odd degree.

Chapter 9 Graphs

└\_§9.5 Euler and Hamilton Paths

# Constructing Euler Circuits

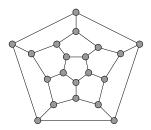
**procedure** Euler(G: connected multigraph with all vertices of even degree) *circuit* := a circuit in GH := G with the edges of this circuit removed while *H* has edges begin subcircuit := a circuit in H H := H with the edges of *subcircuit* removed circuit := circuit with subcircuit inserted at the appropriate vertex

end {circuit is an Euler circuit}

└─ Chapter 9 Graphs └─ §9.5 Euler and Hamilton Paths

## Hamilton Paths and Circuits

- A *Hamilton path* is a path that traverses each vertex in *G* exactly once.
- A *Hamilton circuit* is a circuit that traverses each vertex in *G* exactly once.

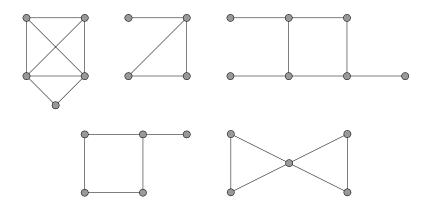


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Chapter 9 Graphs

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## Examples



Chapter 9 Graphs

└\_§9.5 Euler and Hamilton Paths

#### Some Useful Theorems

#### Theorem (Dirac's Theorem)

If (but not only if) G is connected, simple, has  $n \ge 3$  vertices, and  $\forall v : deg(v) \ge n/2$ , then G has a Hamilton circuit.

#### Theorem (Ore's Theorem)

If G is a simple graph with n vertices with  $n \ge 3$  such that  $\deg(u) + \deg(v) \ge n$  for every pair of nonadjacent vertices u and v in G, then G has a Hamilton circuit.

Chapter 9 Graphs

└§9.6 Shortest-Path Problems

## Shortest-Path Problems

#### • Weighted graphs G(V, E, w)

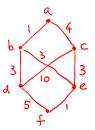
- V: a vertex set.
- E: an edge set.
- w: a weighting function on E.
- The length of a path, e.g.

$$w(\{a, b\}, \{b, d\}, \{d, f\})$$

$$= w(\{a, b\}) + w(\{b, d\}) + w(\{d, f\})$$

$$= 1 + 3 + 5$$

$$= 9.$$



The shortest path

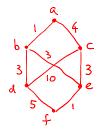
Chapter 9 Graphs

└\_§9.6 Shortest-Path Problems

#### An Example of the Shortest Path

Some paths between a and f.

- Path ({a,b},{b,d},{d,f}): length of ({a,b},{b,d},{d,f}) = w({a,b})+w({b,d})+w({d,f}) = 1+3+5 = 9
- Path ({a,b},{b,e},{e,f}): length of ({a,b},{b,e},{e,f}) = w({a,b})+w({b,e})+w({e,f}) = 1+3+1 = 5
- Path ({a,c},{c,e},{e,f}): length of ({a,c},{c,e},{e,f}) = w({a,c})+w({c,e})+w({e,f}) = 4+3+1 = 8



└─Chapter 9 Graphs └─§9.6 Shortest-Path Problems

# Dijkstra's Algorithm

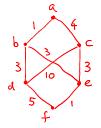
**procedure** Dijkstra(G: a weighted connected simple graph with all weights positive, a is the source, z is the destination) // there exists a path from a to z for i := 1 to n  $L(v_i) := \infty$ L(a) := 0 $S := \emptyset$ while  $z \notin S$ begin u := a vertex not in S with L(u) minimal  $S := S \cup \{u\}$ for all vertices v not in S if L(u) + w(u, v) < L(v) then L(v) := L(u) + w(u, v) $\{L(z) = \text{length of a shortest path from } a \text{ to } z.\}$ end

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## Example of Dijkstra's Algorithm

- Find the shortest path between a and f.
- Find the shortest path between *d* and *c*.



└─ Chapter 9 Graphs └─ §9.6 Shortest-Path Problems

# Traveling Salesman Problem

- The traveling salesman problem asks for the circuit of minimum total weight in a weighted, complete, undirected graph that visit each vertex exactly once and returns to its starting point.
- No algorithm with polynomial worst-case time complexity is known.

- *c*-approximation algorithms:  $W \leq W' \leq cW$ .
  - W: the total length of an exact solution.
  - W': the total weight of a Hamilton circuit.
  - c: a constant.

└─ Chapter 9 Graphs └─§9.7 Planar Graphs (optional)

## Planar Graphs

- A graph is called planar if it can be drawn in the plane without any edges crossing. Such a drawing is called a planar representation of the graph.
- Example:





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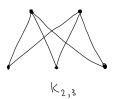
└\_§9.7 Planar Graphs (optional)

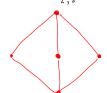
#### More Examples











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└─Chapter 9 Graphs └─§9.7 Planar Graphs (optional)

## Euler's Formula

• Let G be a connected planar simple graph with e edges and v vertices. Let r be the number of regions in a planar representation of G. Then r = e - v + 2.

#### Corollary

If G is a connected planar simple graph with e edges and v vertices, where  $v \ge 3$ , then  $e \le 3v - 6$ .

#### Proof.

(1) 
$$2e \ge 3r$$
. (2)  $r = e - v + 2$ .

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└\_§9.7 Planar Graphs (optional)

# Euler's Formula (Cont.)

#### Corollary

If G is a connected planar simple graph, then G has a vertex of degree not exceeding five.

- Show that K<sub>5</sub> is nonplanar using above corollary.
- Exercise: If a connected planar simple graph has e edges and v vertices with  $v \ge 3$  and no circuits of length three, then  $e \le 2v 4$ .

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## Kuratowski's Theorem

- If a graph is planar, any graph is obtained by removing an edge {u, v} and adding a new vertex w together with edges {u, w} and {w, v}. Such an operation is called an elementary subdivision.
- The graphs  $G_1 = (V_1, E_1)$  and  $G_2 = (V_2, E_2)$  are called *homeomorphic* if they can be obtained from the same graph by a sequence of elementary subdivision.

#### Theorem (Kuratowski's Theorem)

A graph is nonplanar if and if it contains a subgraph homeomorphic to  $K_{3,3}$  or  $K_5$ .

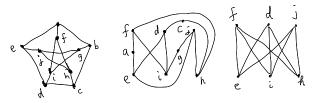
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#### Examples

Some examples

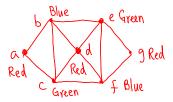


Is the Petersen graph planar?



# Graph Coloring

- A coloring of a simple graph is the assignment of a color to each vertex of the graph so that no two adjacent vertices are assigned the same color.
- The chromatic number of a graph G, denoted by χ(G), is the least number of colors needed for a coloring of this graph.



└─Chapter 9 Graphs └─§9.8 Graph Coloring (optional)

# Coloring of Maps

- Color a map such that two adjacent regions don't have the same color.
- Each map in the plane can be represented by dual planar graph.
  - Ex,



#### Theorem (The Four Color Theorem)

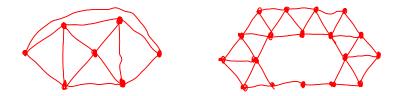
The chromatic number of a planar graph is no greater than four.

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└§9.8 Graph Coloring (optional)



What is the chromatic number of the graphs?



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- What is the chromatic number of  $K_n$ ?
- What is the chromatic number of  $K_{m,n}$ ?

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└§9.8 Graph Coloring (optional)

## Frequency Assignment

- Broadcast radio system
  - Two radio stations can't have the same channel if their receiving regions are with some overlapping area.
  - Broadcast stations are represented by vertices.
  - Tow vertices have an edge if their receiving regions are with some overlapping area.
  - Frequency assignment problems is to find the smallest number of channels.