Öperating System Design and Implementation Lecture 21: Block device driver Tsung Tai Yeh Tuesday: 3:30 – 5:20 pm Classroom: ED-302

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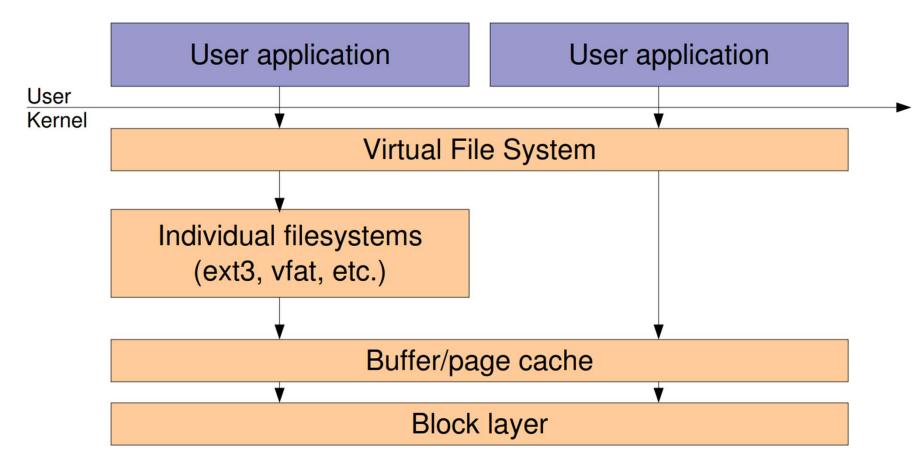
# Acknowledgements and Disclaimer

- Slides was developed in the reference with MIT 6.828 Operating system engineering class, 2018
   MIT 6.004 Operating system, 2018
   Remzi H. Arpaci-Dusseau etl., Operating systems: Three easy pieces. WISC Onur Mutlu, Computer architecture, ece 447, Carnegie Mellon University
- CSE 506, operating system, 2016, https://www.cs.unc.edu/~porter/courses/cse506/s16/slides/sync.pdf

# Outline

- Block device abstraction
  - Block layer
    - I/O scheduler
    - Block driver
- The implementation of a block driver

## Block device abstraction

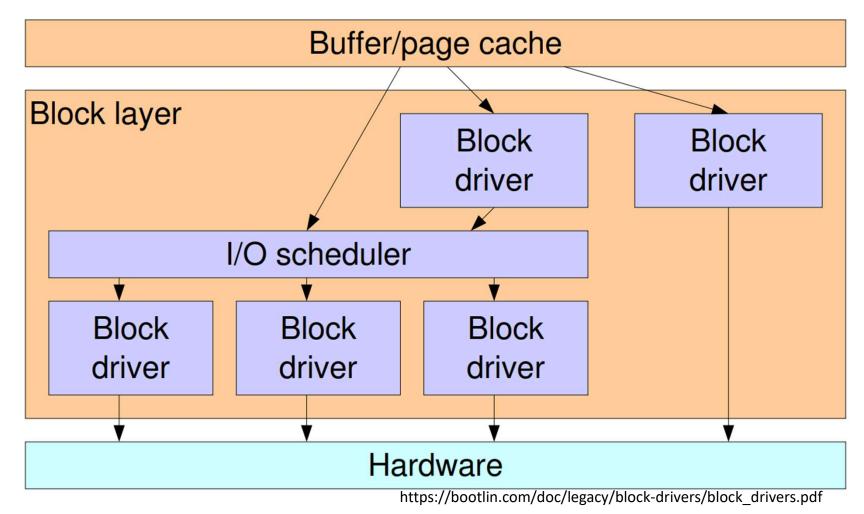


https://bootlin.com/doc/legacy/block-drivers/block\_drivers.pdf

# Block device abstraction

- An user application can use a block device
  - Through a file system -> reading, writing or mapping files
  - **Directly** -> reading, writing or mapping **a device file** (e.g. '/dev')
- The VFS subsystem in the kernel is the entry point for all accesses
  - A file system driver is involved if a normal file is accessed
- The buffer/page cache of the kernel stores recently read and written portions of block devices

### Inside the block layer



## Inside the block layer

#### The block layer allows

- Block device drivers to receive I/O requests
- In charge of I/O scheduling

#### I/O scheduling allows

- Merge requests so that they are of greater size
- Re-order requests to optimize disk head movement
- Linux has several I/O schedulers with different policies

# I/O schedulers

#### • Four I/O scheduler in current kernels

- Noop
  - For non-disk based block devices
- Anticipatory
  - Tries to anticipate what could be the next accesses
- Deadline
  - Tries to guarantee that an I/O will be served within a deadline
- CFQ (Complete Fairness Queuing): The default scheduler
  - Tries to guarantee fairness between users of a block device
- The current scheduler for a device
  - /sys/block/<dev>/queue/scheduler

# Types of drivers

#### Most of the block device drivers

- Implemented below the I/O scheduler to use the I/O scheduling
- Hard disk drivers, CD-ROM drivers, etc.

#### Some drivers don't use the I/O scheduler

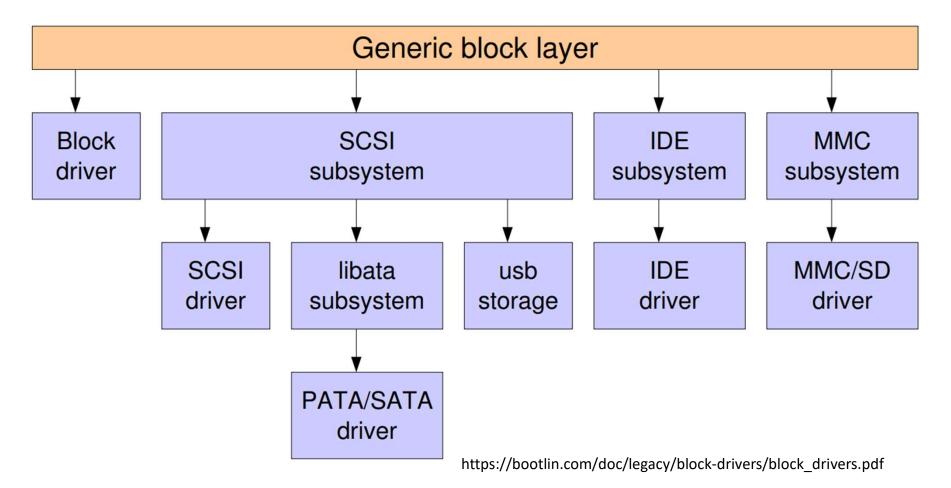
• RAID and volume manager, like md

# How to implement a block device driver ?

#### • A block device driver

- Implement a set of operations
- These operations must **be registered in the block layer** and receive request from the kernel
- Sub-systems have been created to factorize common code of drivers for devices
  - SCSI devices
  - SATA devices
  - MMC/SD devices

### How to implement a block device driver ?



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# Block device layer

#### The block device layer

- Implemented in the 'block/' directory of the kernel source tree
- The I/O scheduler code in \*-iosched.c files

#### • A few simple block device drivers

- See drivers/block/
- loop.c: the loop driver that allows to see a regular file as a block device
- brd.c: a ramdisk driver
- nbd.c: a network-based block device driver

# Step 1: Registering the major

#### The first step in the initialization of a block device driver is

- The registration of the major number
- int register\_blkdev(unsigned int major, const char \*name);
- Major (device number) can be 0 which is dynamically allocated
- E.g. register\_blkdev(sbull\_major, "sbull");
- Once registered, the driver appears in '/proc/devices'

#### Unregistered

void unregister\_blkdev (unsigned int major, const char \*name);

### Step 2: kmalloc

- Create the data structure of this block device
  - E.g. devices = kmalloc (ndevices \* sizeof (struct sbull\_dev), GFP\_KERNEL);

# Step 3: setup\_device ()

### Setup\_device ()

- Add a new block device to block layer in the system
- Step 3.1: initialize a spin lock
  - spin\_lock\_init (&dev->lock);
- Step 3.2: allocate a request queue and use spin lock to control the operation in the queue
  - dev->queue = blk\_init\_queue (sbull\_full\_request, &dev->lock);
- Step 3.3: allocate and initialize struct gendisk
  - dev->gd = alloc\_disk (SBULL\_MINORS);
  - Set\_capacity (dev->gd, nsectors \* (hardset\_size/KERNEL\_SECTOR\_SIZE));

# Initializing a disk

#### struct gendisk

• **Represents a single block device**, defined in <linux/genhd.h>

#### Allocate a gendisk structure

- struct gendisk \*alloc\_disk(int minors);
- Minors tells the number of minors to be allocated in the disk
- 1 for non-partitionable devices

#### Allocate a request queue

 struct request\_queue \*blk\_init\_queue (request\_fn\_proc, spinlock\_t \*lock)

# Initializing a disk

- Initialize the gendisk structure
- Set the capacity
  - void **set\_capacity** (struct gendisk \*disk, sector\_t size);
  - size: a number of 512-bytes sectors
  - sector\_t is 64 bits wide on 64 bits architectures

#### Add the disk to the system

- void add\_disk (struct gendisk \*disk);
- The driver must be fully ready to handle I/O requests before calling add\_disk()
- Afterward, the block device can be accessed by the system

Unregistering a disk

#### Unregister the disk

- void del\_gendisk (struct gendisk \*gp);
- Free the request queue
  - void blk\_cleanup\_queue (struct request\_queue \*);

#### Drop the reference taken in alloc\_disk()

void put\_disk (struct gendisk \*disk);

# struct block\_dev\_operations

<pre>static struct block_device_operations sbull_ops = {</pre>		
.owner	=	THIS_MODULE,
.open	=	sbull_open,
.release	=	sbull_release,
.media_change	=	sbull_release,
.revalidate_disk	=	sbull_revalidate,
.ioctl	=	sbull_ioctll
};		

# Block device operations

- open () and release ()
  - Called when a device handled by the driver is opened and closed
- ioctl ()
  - Manipulates the underlying device parameters of special files
  - E.g. ioctl(sockfd,SIOCGIFADDR,&ifr)
- direct\_access ()
  - required for XIP support
- media\_changed (), revalidate ()
  - required for removable media support
- getgeo()
  - provides geometry information to userspace

# request () operations

#### • struct request ()

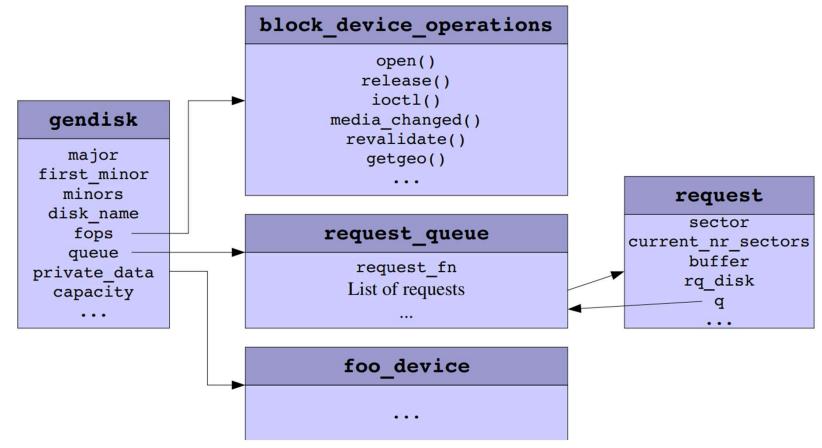
- Make a request to the underlying devices
- sector: the position in the device where the transfer should be made
- current\_nr\_sectors: the number of sector to transfer
- buffer: the location in memory where the data should be read or written to
- rq\_data\_dir (): the type of transfer, either READ or WRITE
- \_blk\_end\_request () or blk\_end\_request () notify the completion of a request

```
A simple request() example
```

```
static void foo_request (struct request_queue *q) {
    struct request *req;
    // elv_next_request: obtain the first non-completed request
    while ((req = elv_next_request(q)) != NULL) {
        if ( ! blk_fs_request (req) ) {
            __blk_end_request (req, 1, req->nr_sectors << 9);
            continue;
        }
        /*Do the transfer here*/
    }
}</pre>
```

\_blk\_end\_request (req, 0, req->nr\_sectors << 9);

### Data structure of a block device driver



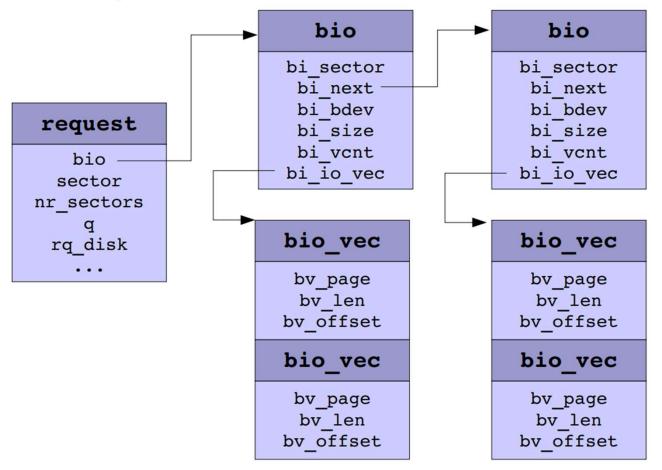
https://bootlin.com/doc/legacy/block-drivers/block\_drivers.pdf

# Inside a request

#### • A request contains several segments

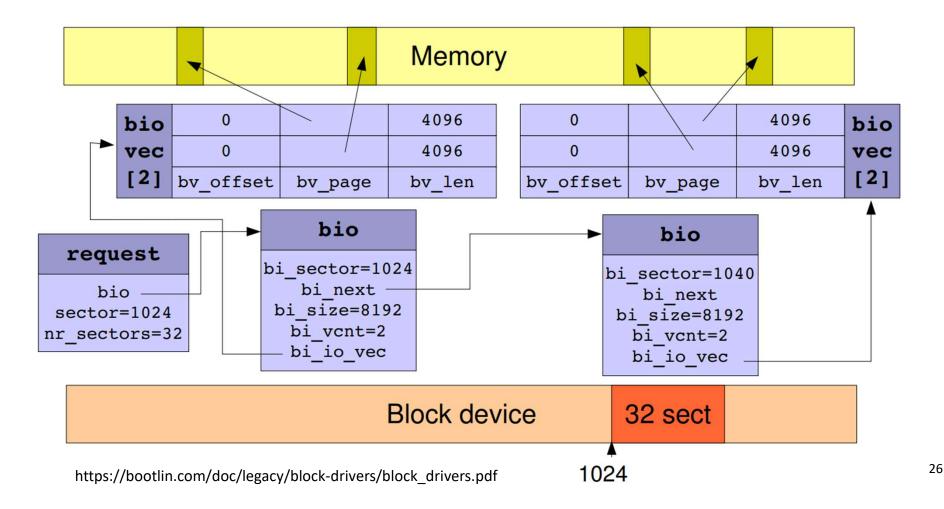
- These segments are contiguous on the block device
- Not necessarily contiguous in physical memory
- A struct request is in fact a list of struct bio
- A bio
  - The descriptor of an I/O request submitted to the block layer
  - The bio(s) are merged together in a struct request by the I/O scheduler
  - Might represent several pages of data (several struct bio\_vec)
  - Each of struct bio\_vec is a page of memory

### Inside a request



https://bootlin.com/doc/legacy/block-drivers/block\_drivers.pdf

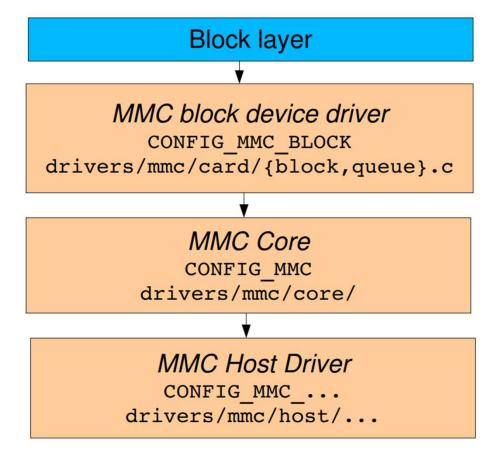
### Request example



# Asynchronous operations

- Asynchronous operations
  - Occurs when handling several requests at the same time
  - Dequeue the requests from the queue
  - void blkdev\_dequeue\_request (struct request \*req);
- Put a request back in the queue
  - void elv\_requeue\_request (struct request\_queue \*queue, struct request \*req);

# MMC/SD



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# MMC host driver

#### For each host

- struct mmc\_host \*mmc\_alloc\_host (int extra, struct device \*dev)
- Initialize struct mmc\_host fields
  - Caps, ops, max\_phys\_segs, max\_hw\_segs, max\_blk\_size, max\_blk\_count, max\_req\_size
- int mmc\_add\_host (struct mmc\_host \*host)
- Unregistration
  - void mmc\_remove\_host (struct mmc\_host \*host)
  - void mmc\_free\_host (struct mmc\_host \*host)

# MMC host driver

- The mmc\_host->ops field points to a mmc\_host\_ops structure
  - Handle an I/O request
    - void (\*request) (struct mmc\_host \*host, struct mmc\_request \*req);
  - Set configuration settings
    - void (\*set\_ios) (struct mmc\_host \*host, struct mmc\_ios \*ios);
  - Get read-only status
    - int (\*get\_ro) (struct mmc\_host \*host);
  - Get the card presence status
    - int (\*get\_cd) (struct mmc\_host \*host);

## Summary

- Block layer is a middleware
  - Fetches items from the buffer cache
  - Includes block drivers and I/O scheduler
- The implementation of a block device driver
  - Step 1: registers the block device
  - Step 2: Create and allocate data structure for that device
  - Step 3: Setup device: initialize disk, allocate request queue ...
- Request () operations and struct bio