

## Acknowledgements and Disclaimer

 Slides was developed in the reference with MIT 6.828 Operating system engineering class, 2018 MIT 6.004 Operating system, 2018 Remzi H. Arpaci-Dusseau etl., Operating systems: Three easy pieces. WISC Onur Mutlu, Computer architecture, ece 447, Carnegie Mellon University

## Outline

- Dynamic memory allocation
- Buddy memory allocator
- Slab memory allocator

## Dynamic memory allocation

- How does the OS manage memory of a single process?
  - Each process has contiguous logical address space
- Static (compile-time) allocation is not always a good choice
  - Recursive procedures
    - Data dependencies are hard to predict
  - Complex data structures
    - Link-list, tree, graph (ptr = malloc(x); free(ptr))

### Dynamic allocation

- Stack allocation
- Heap allocation

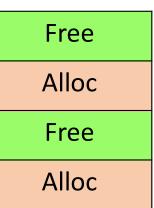
## Stack organization

- Stack grows happens via
  - mremap (): remap a virtual memory address
- When is it useful?
  - Memory allocation and freeing are partially predictable
  - Examples
    - Procedure call frames, tree traversal, recursion
- Advantages
  - Keeps all the free space contiguous
  - Simple and efficient to implement
- Disadvantages
  - Not appropriate for all data structures

alloc(A)
alloc(B)
alloc(C)
free(C)
free(B)
free(A)

## Heap organization

- Allocate from random locations
  - Memory contains allocated areas and free areas
- When is it useful?
  - Allocation and release are unpredictable
  - Arbitrary list structures, complex data organizations
    - E.g. new in C++, malloc() in C
- Advantage: works on arbitrary allocation and free patterns
- Disadvantage: End up with small chunks of free space



# Stack vs heap allocation

Parameter	Stack	Heap		
Basic	Allocated in a contiguous block	Allocated in a random order		
Allocation	Automatic by compiler	Manual by programmer		
Main issue	Storage of memory	Memory fragmentation		
Safety	Thread safe, data only accessed by owner	Not thread-safe, data stored visible to all threads		
Flexibility	Fixed-size	Resizing is possible		
Access time	Fast	Slow		

## Fragmentation

#### Internal fragmentation

Waste space when you round an allocation up

#### External fragmentation

 When you end up with small chunks of free memory that are too small to be useful

#### Not compacted External fragmentation 0KB Operating 8 KB External fragmentation system **16KB** Full of little holes of free space Not in use **24KB** Have a number of segments per process Allocated Each segment might be a different size **32KB** It is difficult to allocate new segments Not in use Compact physical memory Allocated 40KB Rearranging the existing segments **48KB** Not in use Compaction is expansive **56KB** Best-fit, worst-fit, first-fit, buddy algorithm Allocated **64KB**

# External fragmentation (cont.)

### When does external fragmentation occur?

- The free space consists of variable-sized units
- This arises in a user-level memory allocation library (malloc())
- Chops segments into little pieces of different sizes

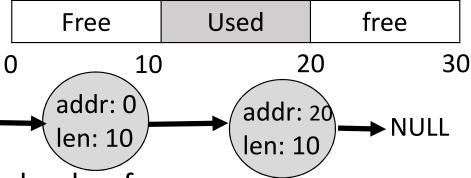
### Problems of the external fragmentation

- No single contiguous space that can satisfy the request
- Even the total amount of free space exceeds the size of requests
- E.g. A request 15 bytes will fail even though there are 20 bytes free

	Free	Used	free	
0		10	20 3	0

10

# Splitting and Coalescing



#### Free list

Contains reference to all of the free chunks of space

### Splitting in the memory allocator

Find a free chunk of memory that can satisfy the request and split it into two

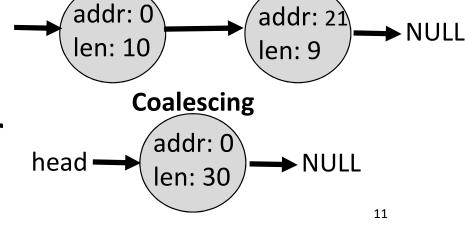
Splitting

head

 E.g. the allocator assigns 1 bytes from the second region to satisfy the request

## Coalescing in the memory allocator

 Merge free space in a large one when a chunk of memory is free, free(10)



## Memory allocation strategies

#### Best fit

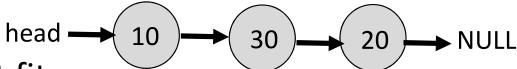
- Return a block that is close to what the user asks
- Try to reduce wasted space
- Perform an exhaustive search for the correct free block penalty

#### First fit

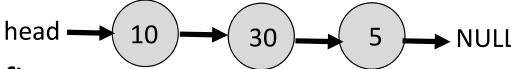
- Find the first block that is big enough and returns the requested amount to the user
- Has the advantage of speed no exhaustive search
- How the allocator manages the free list's order becomes an issue?

# Case study: memory block fitting

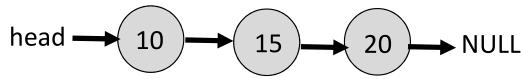
- Envision a free list with three elements on it
  - Assume an allocation request of size 15



- Best fit
  - Search the entire list and find that 20 was the best fit



- First fit
  - Find the first free block that can satisfy the request



## Designing memory allocator issues

- How to keep track of the size of a block?
- How to keep track of which blocks are in use and free?
- How to align memory space if a block is smaller than the free block we find?
- How to pick a block to use for allocation ?
- How do re-insert freed block?

## Segregated lists

#### Segregated lists

- A particular application has one or a few popular-sized request
- Keep a separate list to manage objects of that size
- All other requests are forwarded to a more general MEM allocator
- Dedicated for one particular size of requests, fragmentation is much less of a concern
- Allocation and free requests can be served quite quickly, no complicated search of a list is required

## **Buddy allocator**

- Fast, simple allocation for blocks that are 2<sup>n</sup> bytes
- Allocation restrictions
  - Block sizes: 2<sup>n</sup>
- Allocation strategy for k bytes
  - Raise allocation request to nearest 2<sup>n</sup>
  - Search free list for appropriate size
    - Recursively divide large blocks until reach block of correct size
  - Free strategy
    - Recursively coalesce block with buddy if buddy free
    - May coalesce lazily to avoid overhead

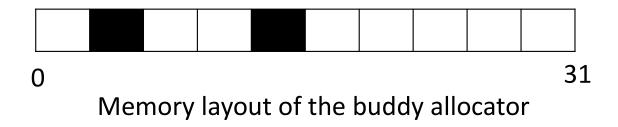
## Buddy allocator issues

### Memory fragmentation

 Buddy allocator still leads to few reserved pages that prevent the allocation of larger contiguous blocks

#### Performance

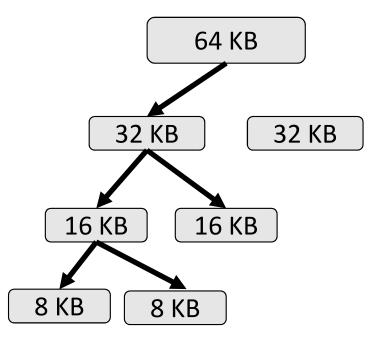
Very fast, since the simple binary shift or bit change arithmetic



## **Buddy allocation**

### Binary buddy allocator

- Free memory as one big space of size 2<sup>N</sup>
- Recursive search by dividing free space by two until a block that is big enough to accommodate the request is found
- Internal fragmentation as only allowed to power-of-two-sized block
- Check whether the "buddy" 8KB is free when returning the 8KB block to the free list
- Keep coalescing when the buddy is still free
- Making coalescing simple



## Case study: buddy allocation

#### **Memory blocks**

0	1	2	3	4	5	6	7

- In a memory
  - Block 0, 4, 5, 6, 7 is used
  - Will buddy allocator merges block 1 and 2 if both of them are free?
    - No!! Block 1 and 2 are not buddy

```
static inline unsigned long _find_buddy_pfn
(unsigned long page_pfn, unsigned int order)
{
    return page_pfn ^ (1 << order);
}
```

# How to allocate memory?

#### Virtual address apce

```
Code (.text)

n

Heap

free 

stack libc.so

0 x ffffffff

int main () {

struct foo *x = malloc(sizeof(struct foo));

....
}

void* malloc (ssize_t n) {

if(heap empty)

mmap(); // add pages to heap and find a free block of size n
}
```

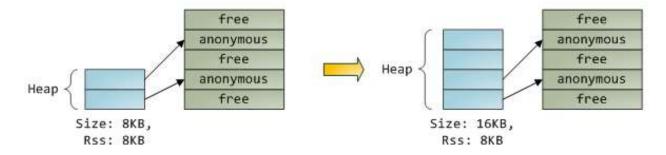
# malloc() issues

- How to implement malloc() or new ?
  - Calls sbrk() to request more contiguous memory from OS
  - Add small header to each block of memory
    - Pointer to next free block
  - Separate free list for each popular size
    - Allocation is fast
    - Inefficient if some are empty while others have lots of free blocks
  - First in on list of irregular free blocks
    - Combine blocks and shuffle blocks between lists

# Enlarge VMA

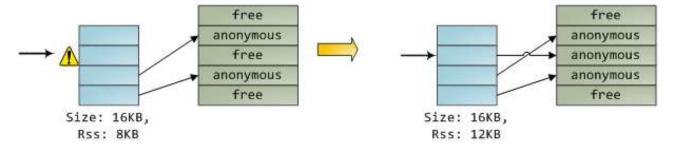


brk() enlarges heap VMA.
 New pages are not mapped onto physical memory.



Program tries to access new memory.Processor page faults.

4. Kernel assigns page frame to process, creates PTE, resumes execution. Program is unaware anything happened.



Source: http://duartes.org/gustavo/blog/post/how-the-kernel-manages-your-memory/

# Reclaiming free memory

- When can dynamically-allocated memory be freed?
  - Explicitly call free()
  - Hard, can't be recycled until all sharers are finished
    - Sharing is indicated by the presence of pointers to the data
- Two possible problems
  - Dangling pointers
    - Recycle storage while it's still being used
  - Memory leaks
    - Forget to free storage even when can't be used again
    - Not a problem for short-lived user processes
    - Issue for operating systems and long-running applications

# Garbage collection

#### • Idea

- No free() operation
- Storage freed implicitly when no longer referenced

## Approach

• When system needs storage, examine and collect free memory

### Advantages

Makes life easier on the application programmer

## Mark and sweep

#### Requirements

- Must be able to find all objects
- Must be able to find all pointers to objects
- Compiler must cooperate by marking type of data in memory

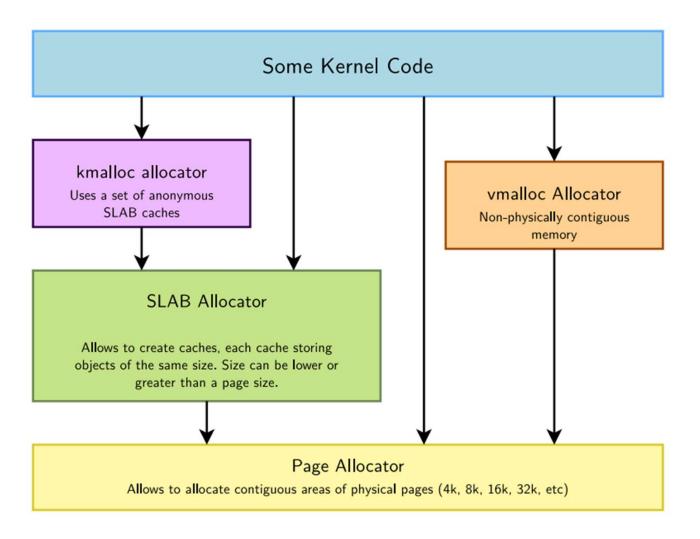
#### Two passes

- Pass 1: Mark
  - Start with all statically-allocated and procedure-local variables (on stack)
  - Mark each object
  - Recursively mark all objects can reach with a pointer
- Pass 2: Sweep
  - Go through all objects, free those that aren't marked

# Garbage collection in practice

- Disadvantages
  - Expansive: 20% or more of CPU
  - Difficult to implement
    - Execute program during garbage collection (incremental)
- Languages with garbage collection
  - LISP
  - Java

## Linux kernel allocators



## Page allocator

- Appropriate for medium-size allocations
- A page is usually 4KB that is dependent to the hardware
- Buddy allocator strategy
  - Only allocations of power of two numbers of pages such as 1, 2, 4,
    8, 16 pages, etc.
  - Typical maximum size is 8192 KB
  - The allocated area is contiguous in the kernel virtual address space
  - Maps to physically contiguous pages
  - The large areas may not be available due to physical memory fragmentation

## Motivation of the slab allocator

#### The kernel needs

- Many different temporary objects
- Such as the mm\_struct, inode, files\_struct structures

### Temporary kernel objects

- Very small and very large size
- They are often allocated and freed
- Require to perform object allocation efficiently

### Drawbacks of the buddy allocator

- Its free areas are composed of entire frames of memory (too large for various object size)
- Align objects with power of two size has a negative impact on the use of the process cache

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## Principle of the slab allocator

- The allocation of small memory blocks
  - Eliminate internal fragmentation caused by a binary buddy allocator
  - Two caches of small memory buffers (32 131072 bytes)
  - kmalloc() is provided for allocate objects in these small cache buffers
- The caching of commonly used objects
  - The system doesn't waste time allocating, initializing and destroying objects
- The better utilization of hardware cache
  - aligning objects to the L1 or L2 caches

## What is slab?

Cache chain

Slab state

Slabs\_full

Slabs\_partial

Slabs\_free

Slabs slabs

Slabs pages

#### Slab

- a chunk of contiguous pages
- A container of objects
- Allocates a number of objects to the slabs associated with that cache

#### Cache chain

https://www.kernel.org/doc/gorman/html/understand/understand011.html

object

object

• A variable number of caches linked on a doubly linked circular list

object

object

Kmem\_cache\_s manages objects such as mm\_struct or fs\_cache

object

object

# What is slab? (cont.)

- The slab allocator manages the objects in a cache
  - A slab contains one or more pages, divided into equal-sized objects
  - When cached created, allocate a slab, divided the slab into free objects
  - If a slab is full of used objects, next object comes from an empty/new slab

#### Benefits

- No fragmentation and fast memory allocation
- Some of the object fields may be reusable; no need to initialize again

## Alternative slab allocators

#### SLOB allocator

- Designed for small systems
- As compact as possible

#### SLAB allocator

As cache friendly as possible

#### SLUB allocator

- Designed for large systems
- Minimize memory overhead
- Execution time friendly

## The slab allocator

#### The slab allocator

- The default cache allocator (at least as of early Linux kernel 2.6, Solaris)
- A given cache allocates a specific type of object
  - E.g. a cache for file descriptors, a cache for inodes

#### Motivation

- The kernel often spends much of its time on allocating, initializing and freeing the same object
- Reduce the number of references to the buddy allocator

#### • Basic idea

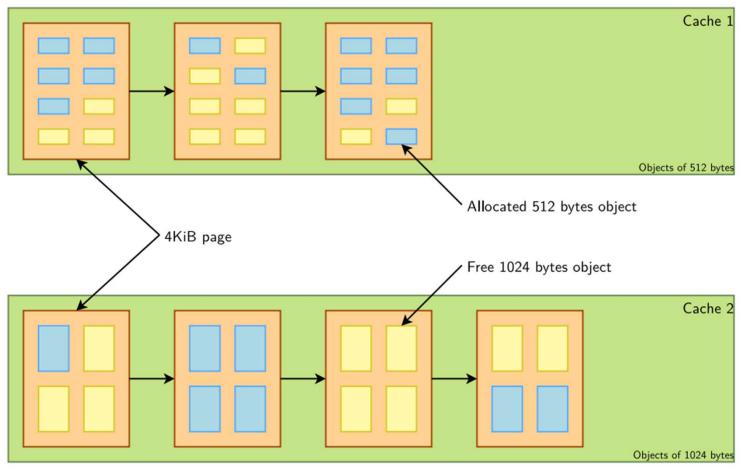
 Have caches of commonly used objects kept in an initialized state for use by the kernel

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# The slab allocator (cont.)

- The SLAB allocator
  - Allow to create caches, which contain a set of objects of the same size
  - The object size can be smaller or greater than the page size
  - Takes care of growing or reducing the size of cache as needed
  - Uses the page allocator to allocate and free pages
  - SLAB caches are used for data structures that are present in kernel instances
    - Directory entries, file objects, network packet descriptors etc..
    - See /proc/slabinfo

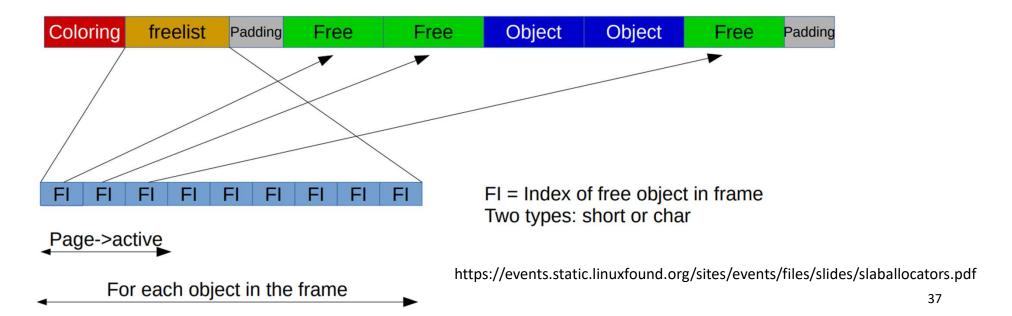
# The slab allocator(cont.)



# SLAB per frame freelist management

 Multiple requests for free objects can be satisfied from the same cache line without touching the object contents

#### Page Frame Content:



## SLAB allocator — data structure

#### Red zone

Used to detect writes after the object

#### Poisoning

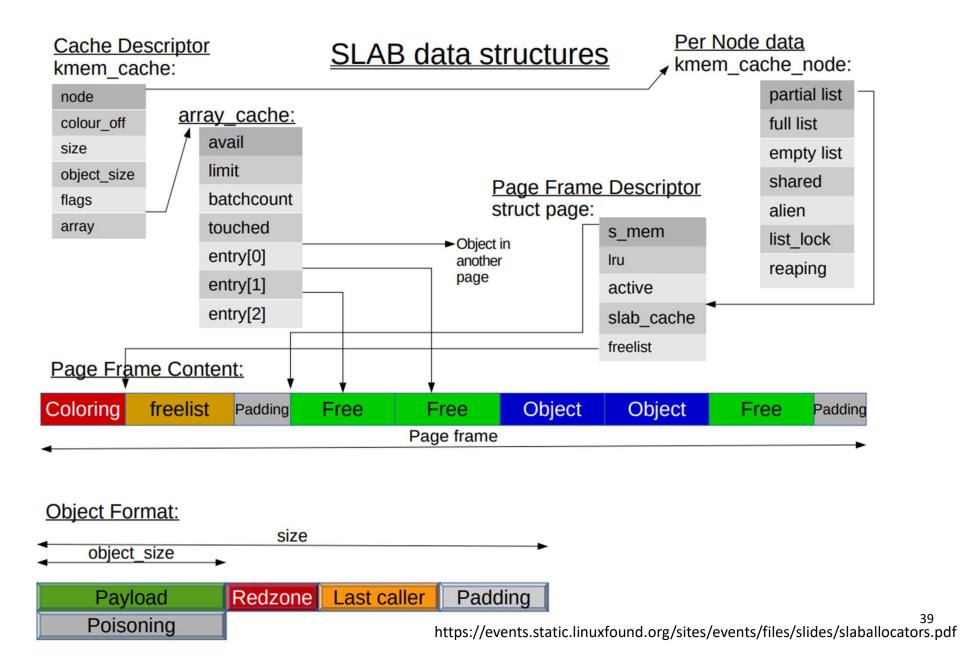
If the object is inactive then the bytes contain poison values

#### Padding

 An unused data to fill up the space to get the next object properly aligned

#### Coloring

- A scheme that attempts to have objects in different slabs use different lines in the cache
- Objects use different cache lines ensure objects from the same slab cache will be unlikely to flush each other



## SLOB allocator

#### Small systems

 The bookkeeping overheads become critical on tiny memory system such as embedded systems

### Simple list of blocks (SLOB)

- Just keep a free list of each available chunk and its size
- Currently uses a first-fit algorithm
- Grab the first one big enough to work
- Split block if leftover bytes
- No internal fragmentation
- External fragmentation? Yes. Trade for low overheads

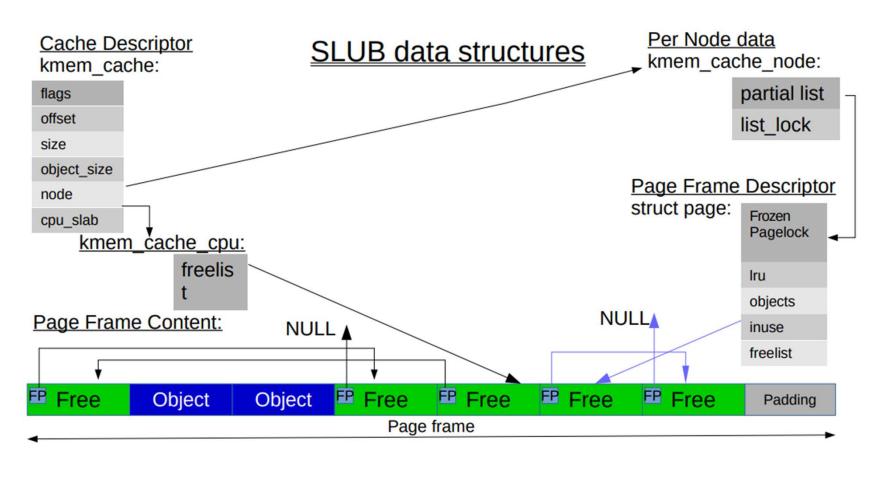
## SLUB allocator

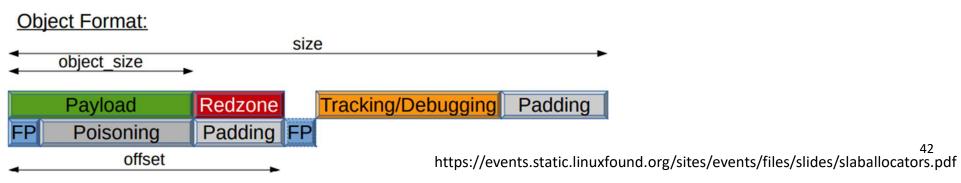
#### Large system

 The number of SLAB queues can make allocation fast but add complexity and storage overhead in large systems

### The unqueue slab allocator (SLUB)

- All objects of same size from same slab
- Simple free list per slab no per-slab metadata
- Add new fields in struct page to guide the search of free objects
  - void \*freelist; // points to the first free object within a slab
  - short unsigned int inuse; // the number of objects allocated from the slab
  - short unsigned int offset; // tells the allocator where to find the pointer to the next free object





## kmalloc allocator

### kmalloc()

- Allocate memory for the kernel from general purpose caches
- For small sizes, it relies on generic SLAB caches (see /proc/slabinfo)
- For large sizes, it relies on the page allocator
- The allocated area is guaranteed to be physical contiguous
- The allocated area size is rounded up to the size of the smallest SLAB cache in which it can fit

## kmalloc API

- #include linux/slab.h>
- void \*kmaloc(size\_t size, int flags);
  - Allocate size bytes and return a pointer to the area (virtual address)
  - Size: number of bytes to allocate
  - Flags: same flags as the page allocator (GFP\_KERNEL, GFP\_ATOMIC,

GFP\_DMA, etc.)

- void kfree(const void \*objp);
  - Free an allocated area

```
struct ib_port_attr *tprops;
tprops = kmalloc(sizeof *tprops, GFP_KERNEL);
...
kfree(tprops);
```

drivers/infiniband/core/cache.c

## vmalloc allocator

- The **vmalloc()** allocator
  - Used to obtain memory zones that are contiguous in the virtual addressing space, but not made out of physically contiguous pages
  - The allocated area is in the kernel space part of the address space
  - Allocations of fairly large areas is possible
  - Physical memory fragmentation is not an issue
  - Areas cannot be used for DMA, since DMA usually requires physically contiguous buffers
  - API in include/linux/vmalloc.h
  - void \*vmalloc(unsigned long size); // return a virtual address

## Summary

- Dynamic memory allocation
  - Fit for arbitrary complex data structure
- Buddy memory allocation
  - Simple, fast for power of two blocks
  - Fragmentation
- Slab memory allocator
  - Caching the commonly used objects