Introduction to Algorithms

Mong-Jen Kao (高孟駿)

Tuesday 10:10 – 12:00

Thursday 15:30 – 16:20

Graph Algorithms

Graph problem pervades computer science, and
 Algorithms for graphs are fundamental to the field.

Applications of the DFS Algorithm

Let's examine graph problems that are solved by DFS-like algorithms.

Example 1.

Topological Sort

Produce a consistent linear ordering of the vertices for a directed acyclic graph (DAG).

Topological Sort

- Let G = (V, E) be a directed acyclic graph (DAG).
 - i.e., G contains no cycle.
- The topological sort problem is to produce a linear ordering $\pi: V \mapsto \{1, 2, ..., n\}$ of the vertices, where n = |V|, such that
 - $\pi_u \neq \pi_v$ for any $u, v \in V$ with $u \neq v$, and
 - for any directed edge $(u, v) \in E$, we have $\pi_u < \pi_v$.
- In other words, produce an ordering of the vertices such that no edge points backwards in the ordering.

Topological Sort

- The topological sort problem can be solved by the DFS algorithm.
 - Topological-Sort(G) G = (V, E) is directed acyclic.
 - A. Let *Q* be an empty list.
 - B. Call DFS(G).

As each vertex is finished in the DFS-Visit call, insert the vertex in the front of Q.

C. Return Q.

 $//\ Q$ stores the vertices in the descending order of their finish times.

Analysis of the Algorithm

- It is clear that this algorithm runs in O(|V| + |E|) time.
- To prove the correctness, let us verify the 4 types of edges in the DFS-forest.
 - By the parenthesis theorem, tree edges <u>point to vertices</u>
 with earlier finish times.
 - By the definition, forward edges and cross edges point to black vertices which are already finished.

These vertices come after in the linear ordering.

Analysis of the Algorithm

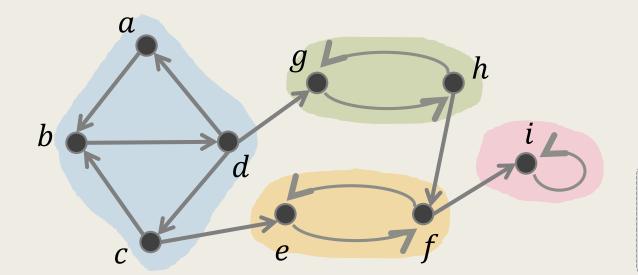
- It is clear that this algorithm runs in O(|V| + |E|) time.
- To prove the correctness, let us verify the 4 types of edges in the DFS-forest.
 - There is no back edge in the resulting DFS-forest.
 - Any back edge forms at least one cycle in the graph.
- Hence, none of these edges point backward in the ordering produced by the algorithm.

Example 2.

Strongly Connected Components

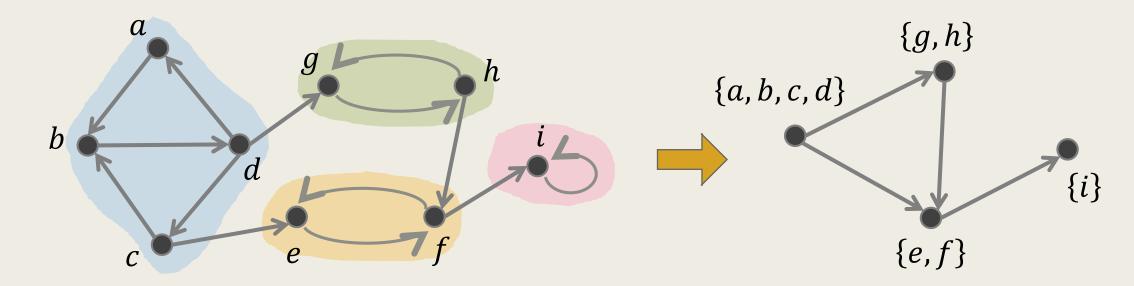
Partition the vertices into maximal components such that <u>every vertex pair</u> within one component is <u>reachable from both directions</u>.

- Let G = (V, E) be a directed graph (digraph).
 - A <u>strongly connected component</u> (SCC) is a <u>maximal vertex</u> **subset** $C \subseteq V$ such that for any $u, v \in C$, vertices u and v are <u>reachable from each other</u>.

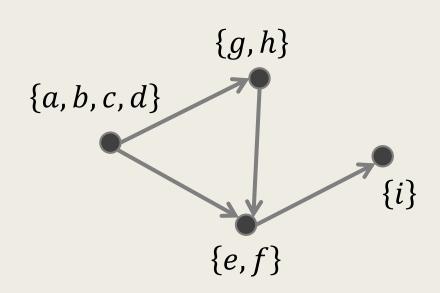


Note that, $\{a, b, d\}$ is not an SCC since it is not maximal in size.

- Let G = (V, E) be a directed graph (digraph).
 - Let $C = \{C_1, C_2, ..., C_k\}$ be a partition of V into SCCs.
 - Consider the set E_C of edges in E that connects components in C.
 - Then, $G_C = (\mathcal{C}, E_C)$ is **acyclic**.



- Define $E^T := \{ (v, u) : (u, v) \in E \}$ be the edges in E with their directions reversed.
 - Define $G^T = (V, E^T)$ to be the transpose of G.
- Then, $C \subseteq V$ is an SCC for G if and only if C is an SCC for G^T .
- Furthermore, if $C, C' \subseteq V$ are SCCs such that C' is reachable from C in G_C , then C' is not reachable from C in G_C^T .



- With the information computed by the DFS algorithm, we can compute the set of SCCs in O(|V| + |E|) time.
 - Strongly-Connected-Components(G) G = (V, E) is directed.
 - A. Call DFS(G), and use a queue to maintain the vertices in decreasing order of their finish times.
 - B. Call DFS(G^T), but in the main loop of the algorithm, consider the vertices in decreasing order of their finish times.
 - C. Report each tree in the DFS forest created by DFS(G^T) as an SCC.

Example 3.

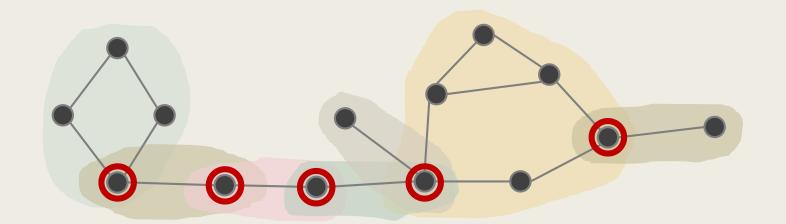
Bi-connected Components and Articulation Points

Computing the cut vertices and

2-vertex connected components for an undirected graph.

Articulation Points / Cut Vertices

- Let G = (V, E) be a connected undirected graph.
 - A vertex v ∈ V is a <u>cut vertex</u> / <u>articulation point</u> for G
 if G {v} is disconnected.
 - A <u>biconnected component</u> is a maximal vertex subset $B \subseteq V$ that induces a connected subgraph with no cut vertex.



Articulation Points / Cut Vertices

- We can use the DFS algorithm to compute the set of bi-connected components and also the set of articulation points in O(|V| + |E|) time.
- Consider the DFS tree G_{π} computed by the DFS algorithm.
 - We have the following properties.

Lemma 1.

Let r be the root of G_{π} . Then r is an articulation point *if and only if* it has at least two children nodes in G_{π} .

Articulation Points / Cut Vertices

- Consider the DFS tree G_{π} computed by the DFS algorithm.
 - We have the following properties.

Lemma 2.

Let $v \in G_{\pi}$ be a non-root vertex.

Then v is an articulation point *if and only if* it has a child s such that there is *no back edge* from s or any descendant of s to a proper ancestor of v.

- We can use the DFS algorithm to compute the set of bi-connected components and also the set of articulation points in O(|V| + |E|) time.
 - Get-Articulation-Points (v, ℓ) $v \in V$ the current vertex with depth ℓ .

A. // Initializations

```
Set visited[v] \leftarrow \text{true}, depth[v] \leftarrow \ell,
```

 $low[v] \leftarrow \ell$, // Highest depth reachable from any descendant of v <u>via back edges</u>.

childCount \leftarrow 0, and

 $isCutVertex \leftarrow false.$

■ Get-Articulation-Points (v, ℓ) - $v \in V$ the current vertex with depth ℓ .

A. // Initializations

- B. For each $u \in N(v)$, do the following.
 - If visited [u] = false then
 - 1. Set $\pi[u] \leftarrow v$ and childCount \leftarrow childCount + 1.
 - 2. Get-Articulation-Points $(u, \ell + 1)$.
 - 3. If $low[u] \ge depth[v]$, // by Lemma 2 then set is CutVertex \leftarrow true.
 - 4. Set $low[v] \leftarrow min(low[v], low[u])$.

else if $u \neq \pi[v]$, then //(v,u) is a back edge

1. Set $low[v] \leftarrow min(low[v], depth[u])$.

■ Get-Articulation-Points (v, ℓ) - $v \in V$ the current vertex with depth ℓ .

```
A. // Initializations
```

B. For each $u \in N(v)$, do the following.

- ...

Output v as an articulation point.

With an extra stack, this algorithm can be modified to output all biconnected components in O(|V| + |E|) time as well.