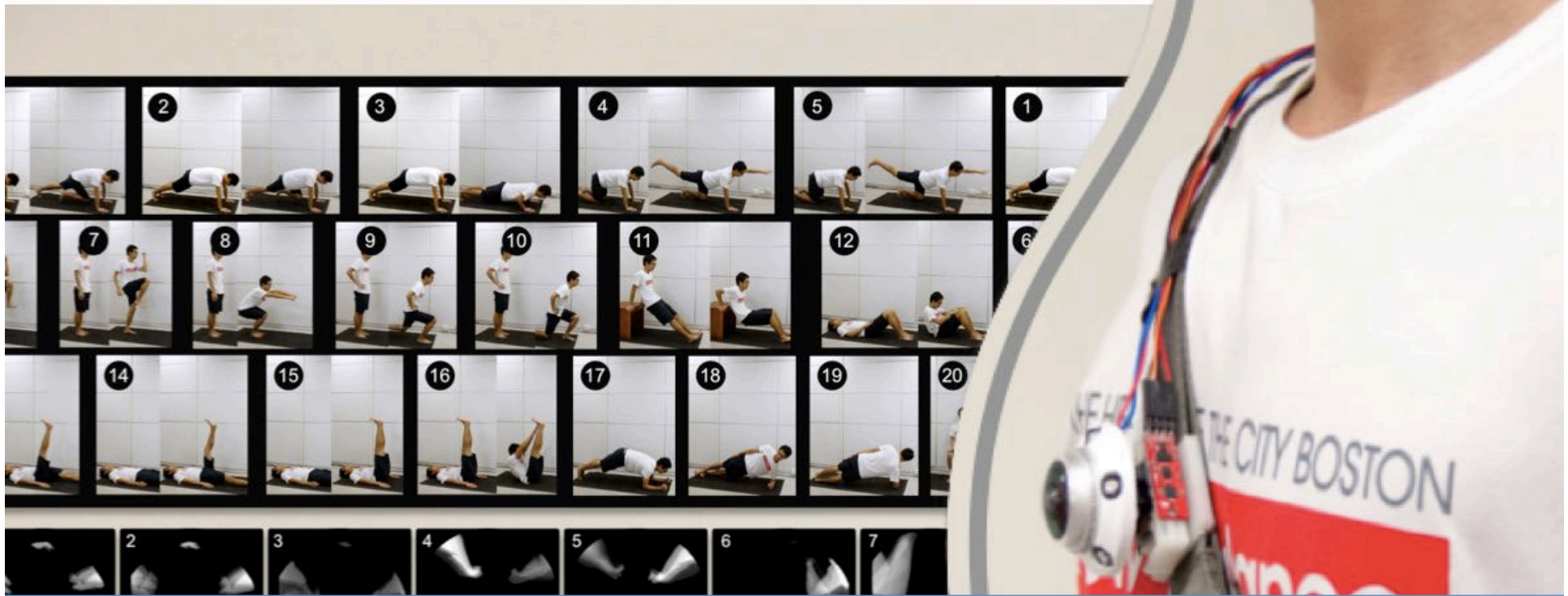


Cyclops

CHI 2015

Wearable and Single-Piece
Full-Body Gesture Input Devices



Liwei Chan

Chi-Hao Hsieh
Da-Yuan Huang

Yi-Ling Chen
Rong-Hao Liang

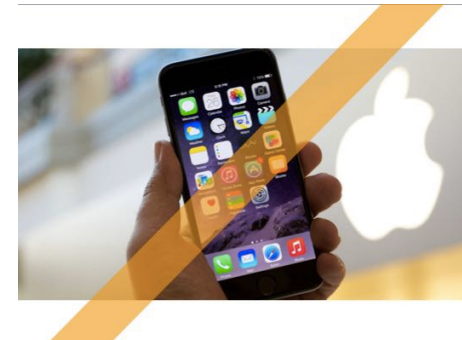
Shuo Yang
Bing-Yu Chen

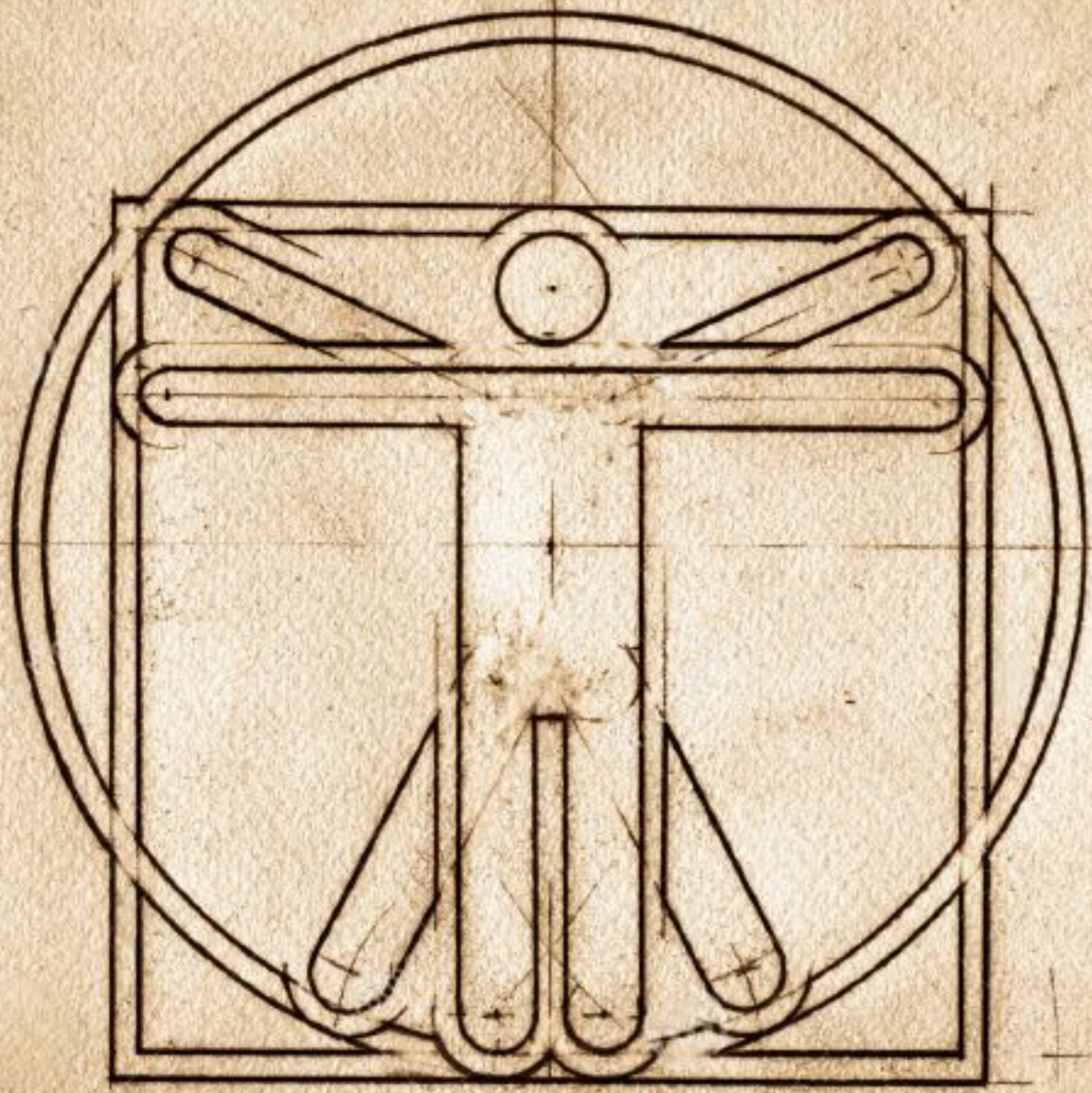
National Taiwan University

most effective
interface:

most effective
interface:

interface that we are
trained to use
at the **longest**







NEILA REY WORKOUT

neilarey.com

1

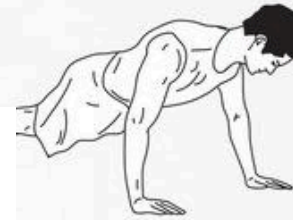


10 jumping lunge

2

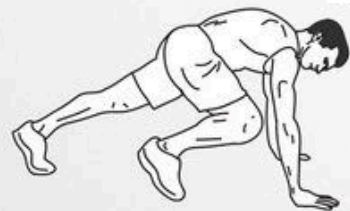
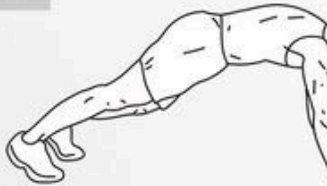


3



wide grip push-ups

4



20 climbers



10 planks w/ rotations

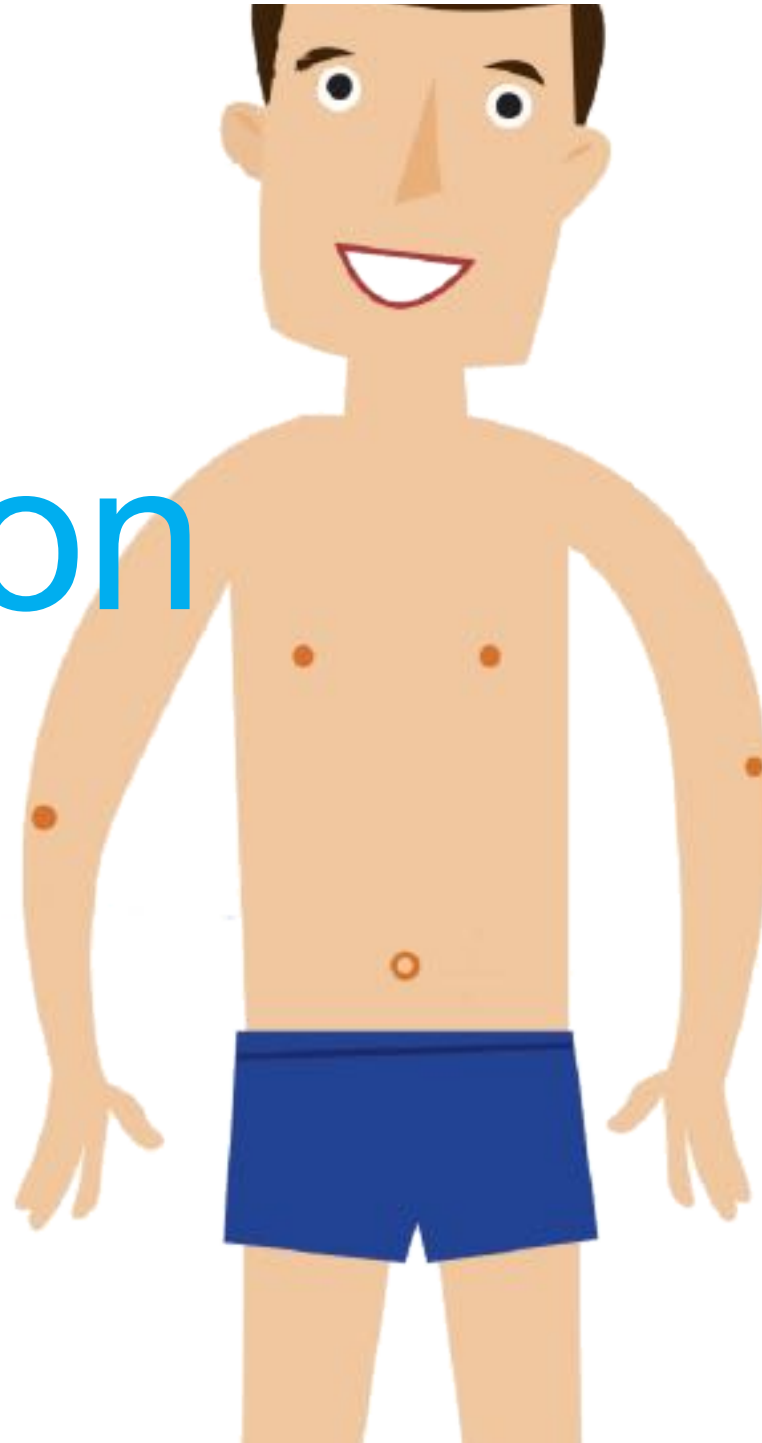


10 plank leg raises

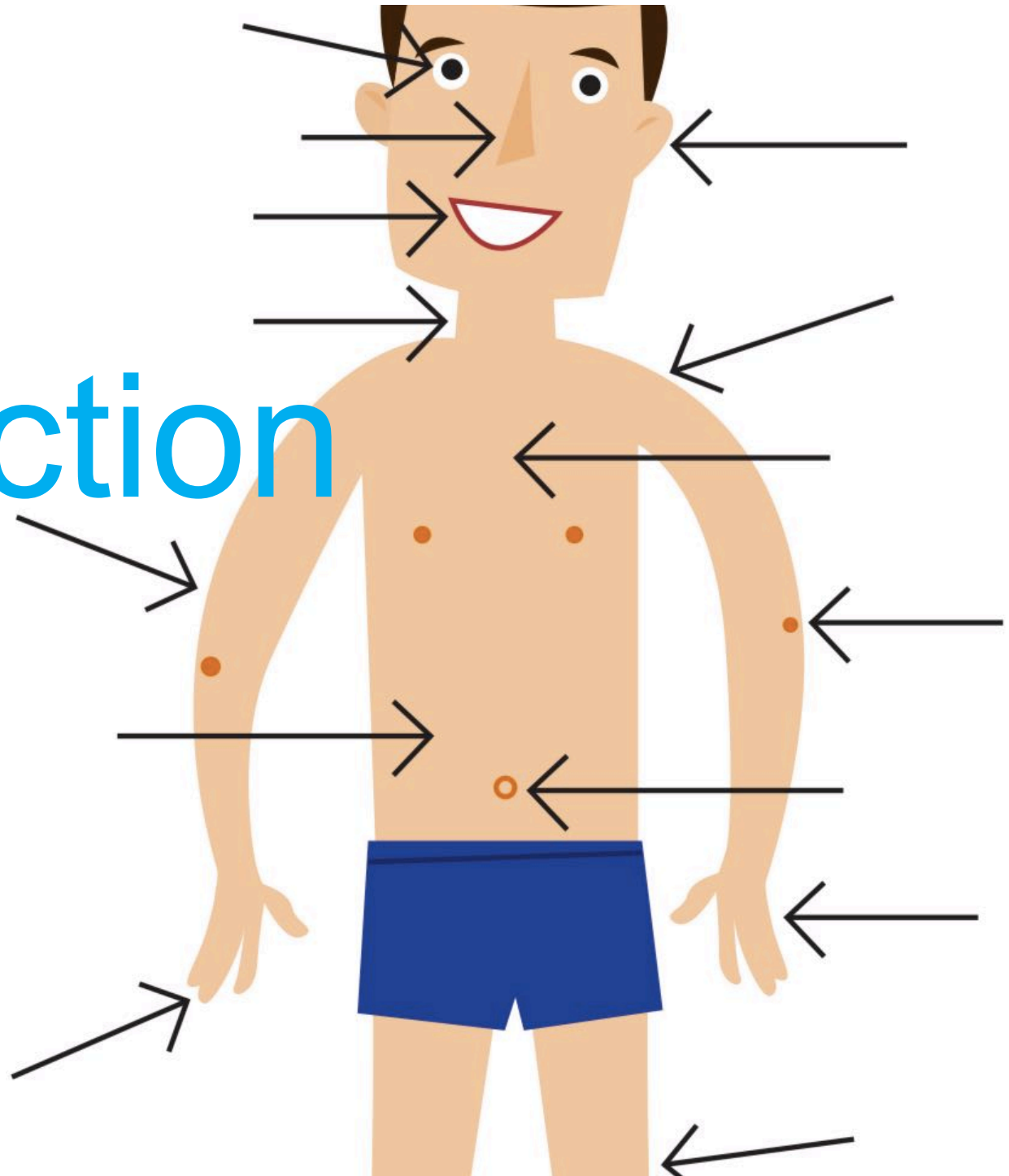
Cyclops



Full Body Interaction



Full Body Interaction



Related Work

Kinect



Kinect

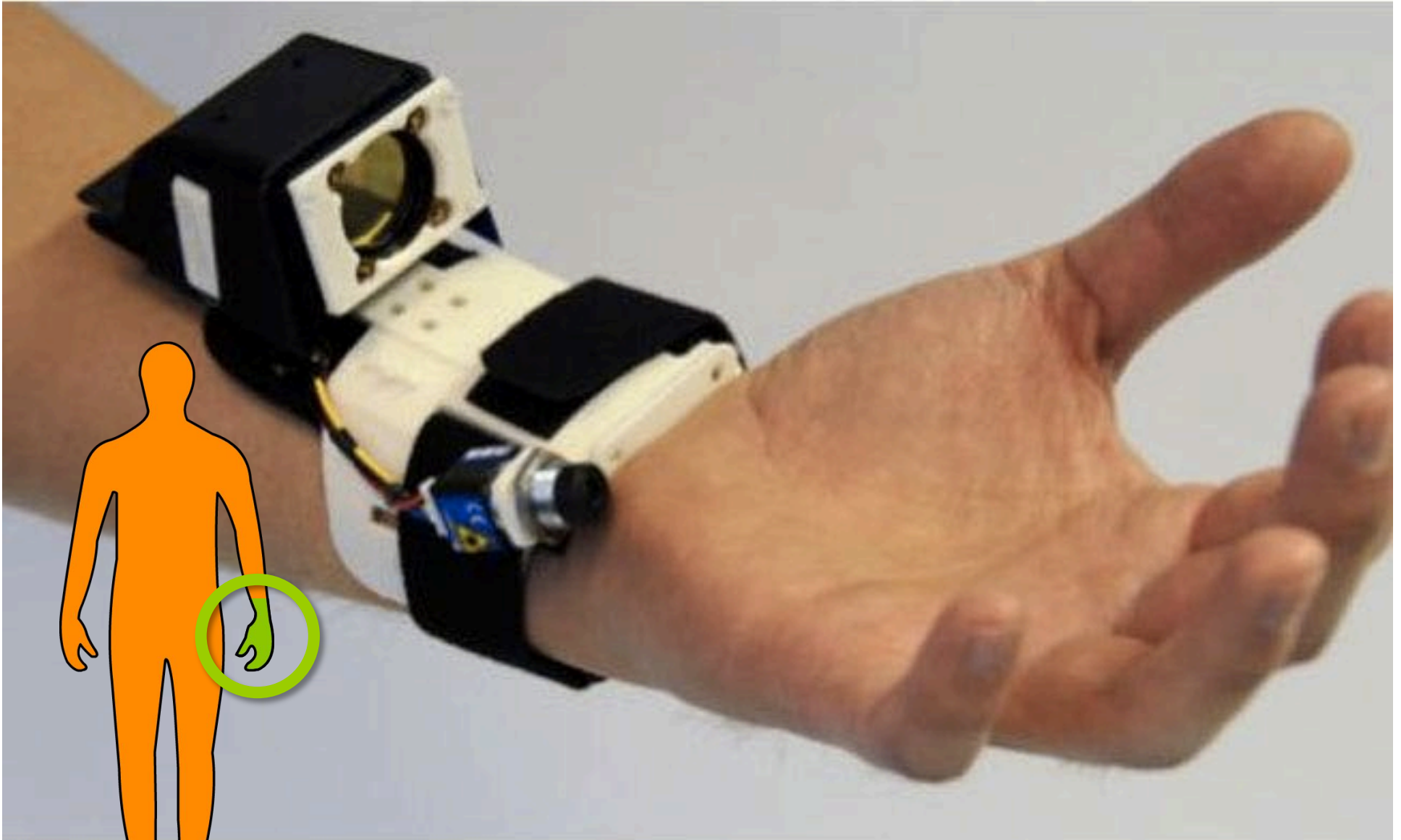


Interaction
zone

On-body
camera

.....

wearable
interaction
zone



[Digits, UIST '12]



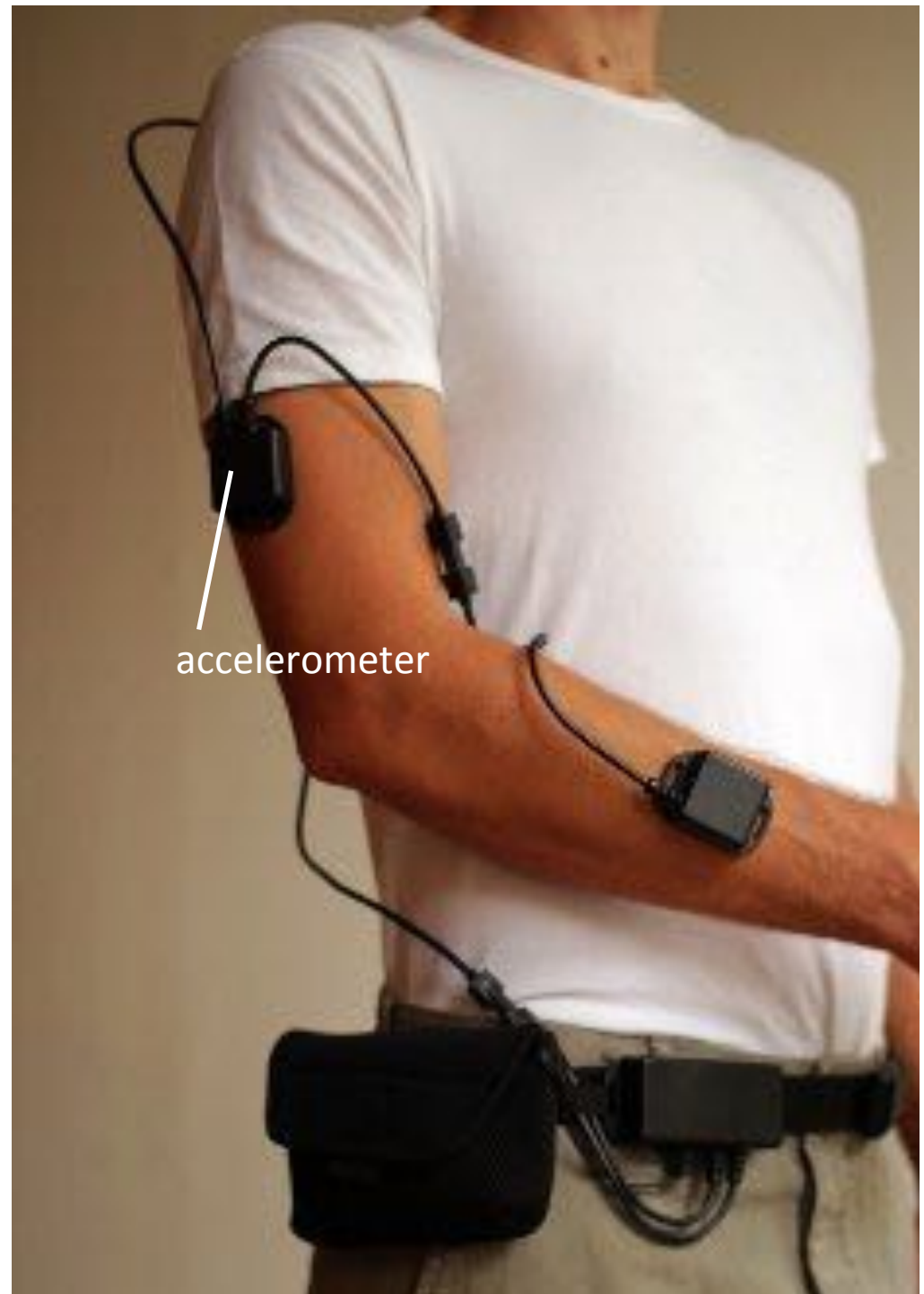
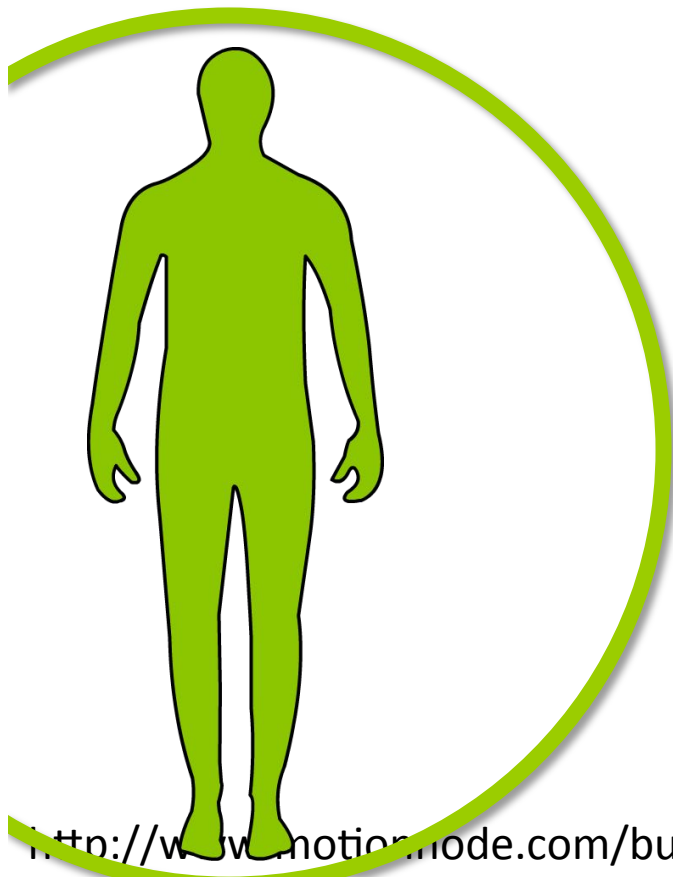
[OmniTouch, UIST '11]



[ShoeSense, CHI'12]

MotionNode

a wearable network of 3-DOF inertial measurement units (**IMU**) for use in motion capture applications

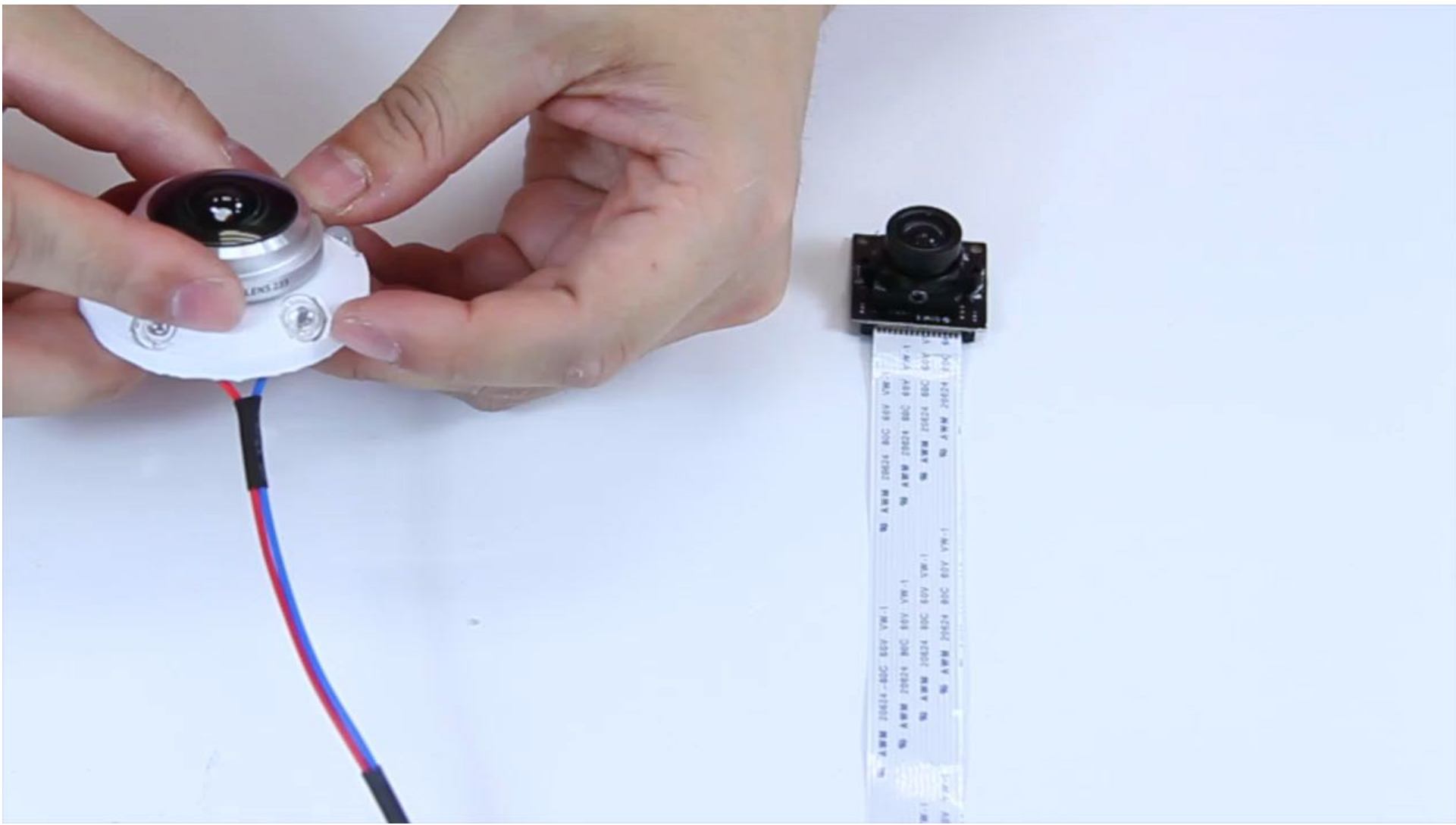


Motion Capture Suit



Motion Capture Suit





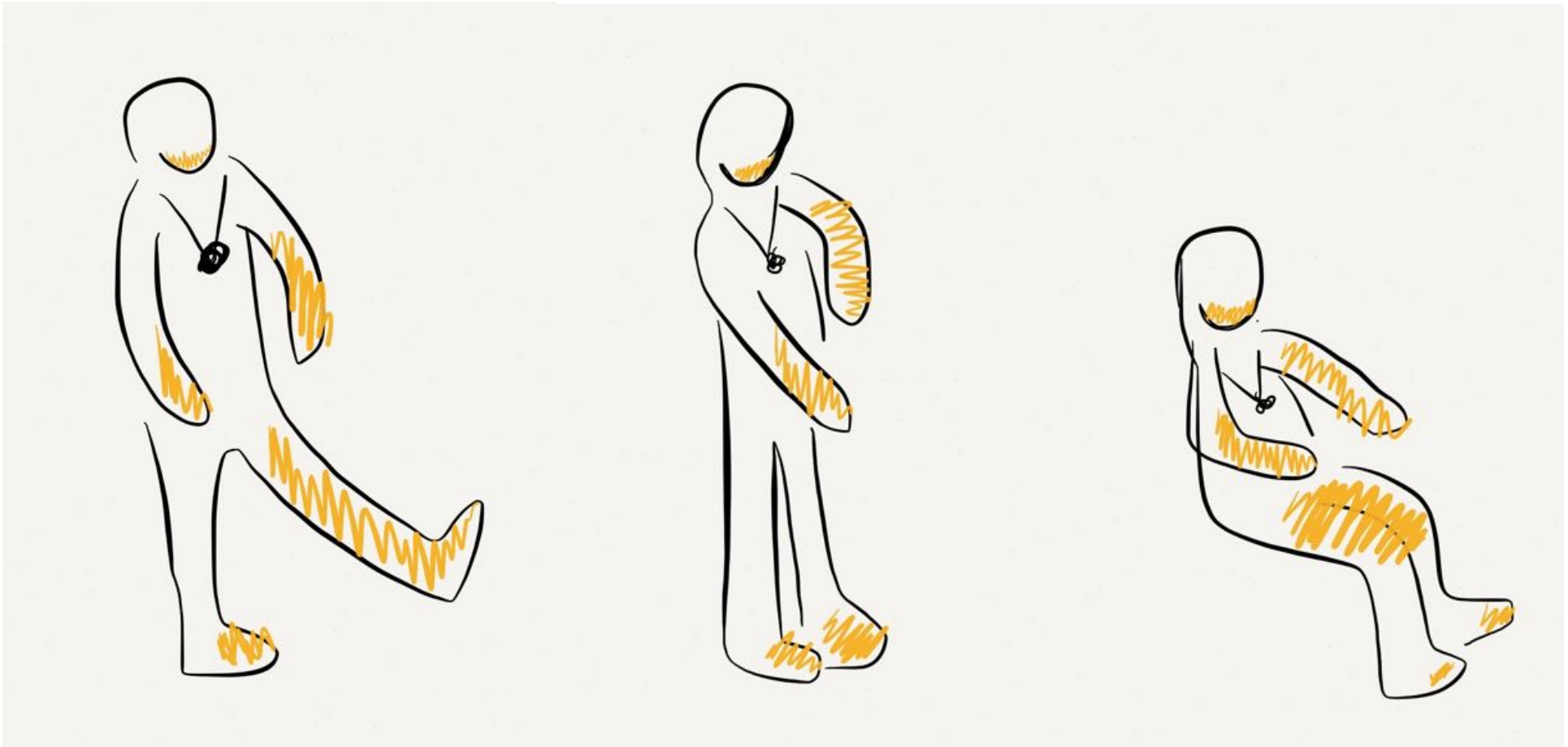
Cyclops

:: a single-piece wearable device that sees all.



Cyclops

:: a single-piece wearable device that sees all.



How wide the field-of-view
of the lens is required to see
the full body from users' chest?

GOPRO





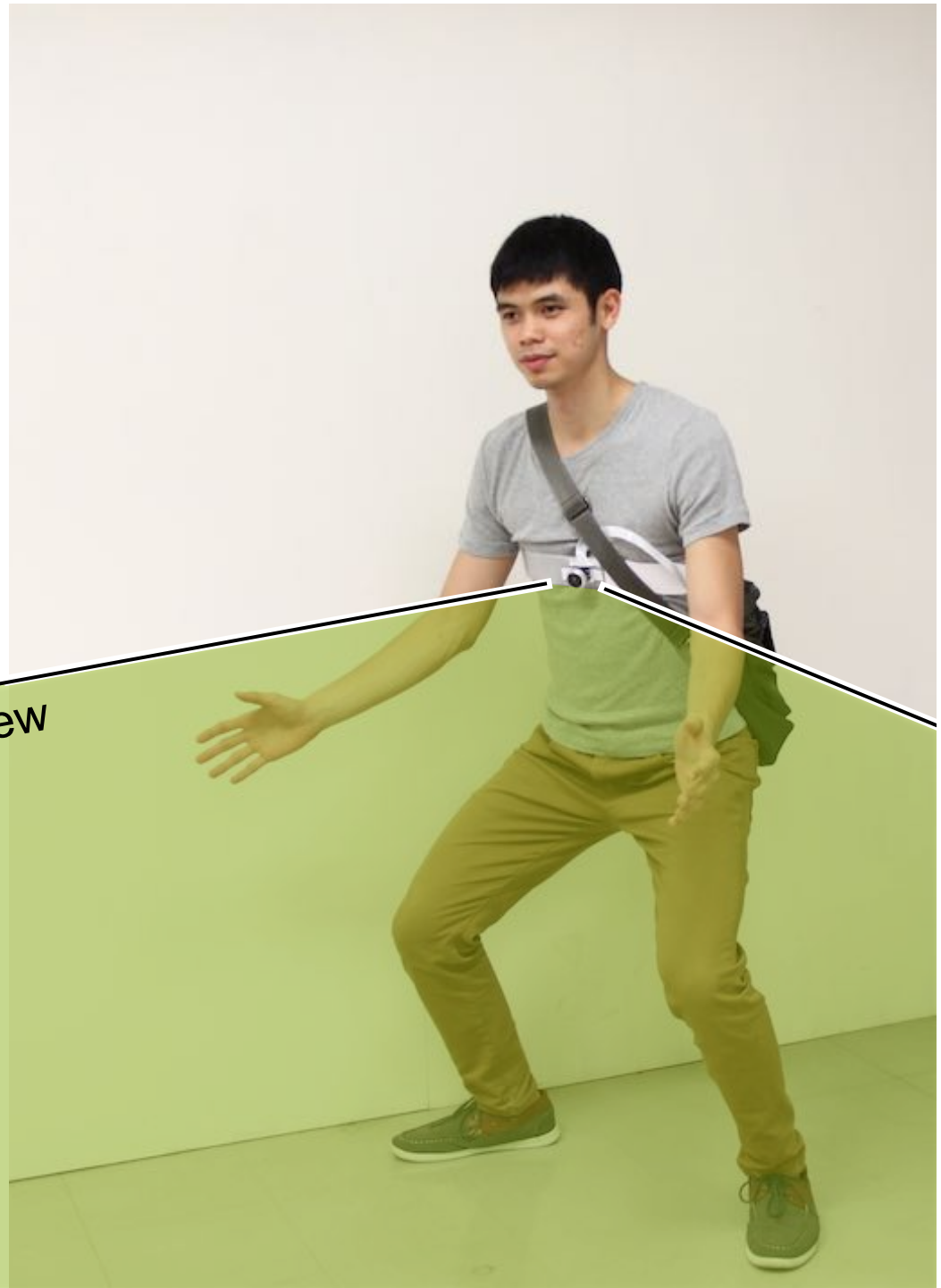
GOPRO

Feet?



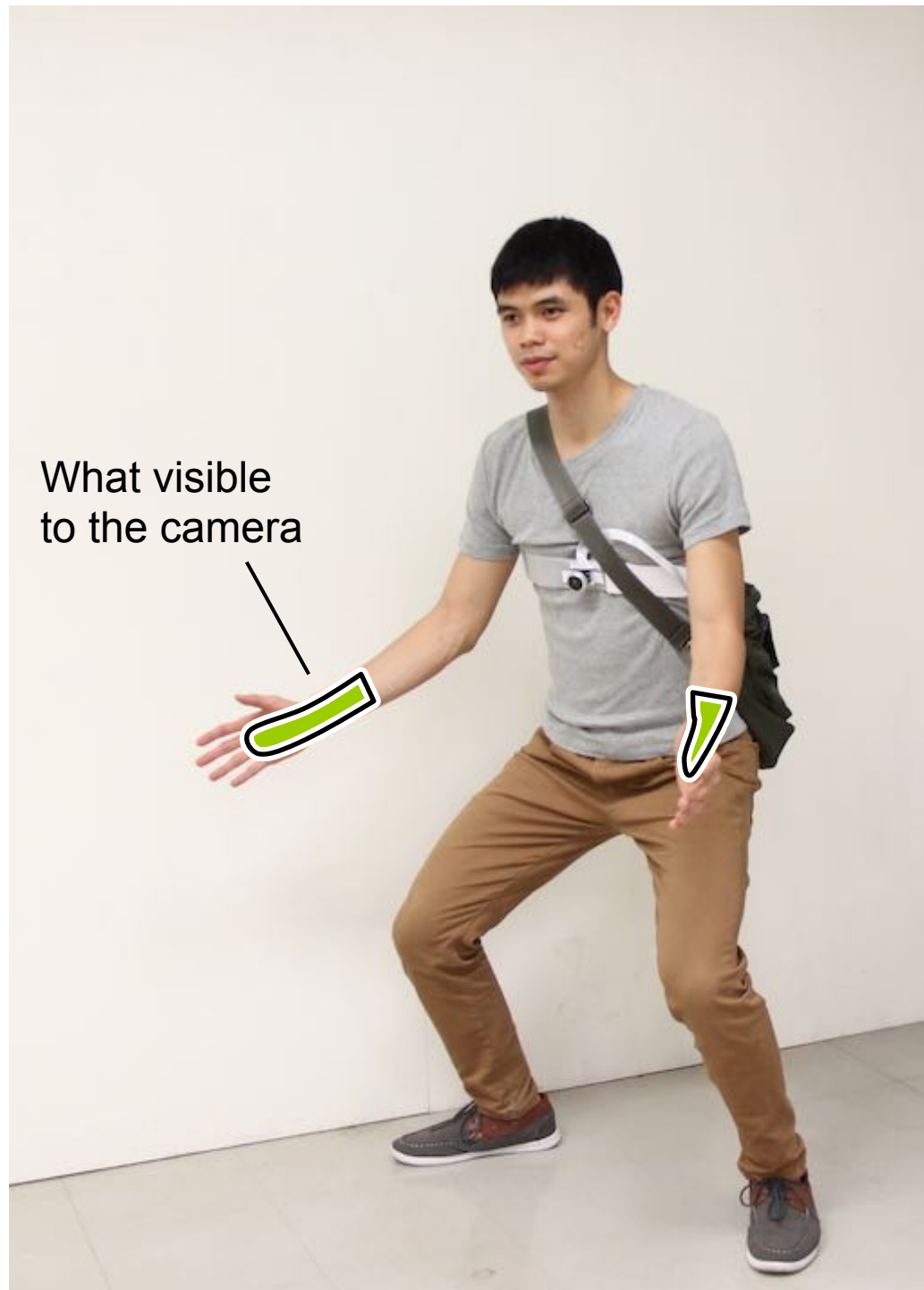
How wide is wide enough?

Camera's field-of-view



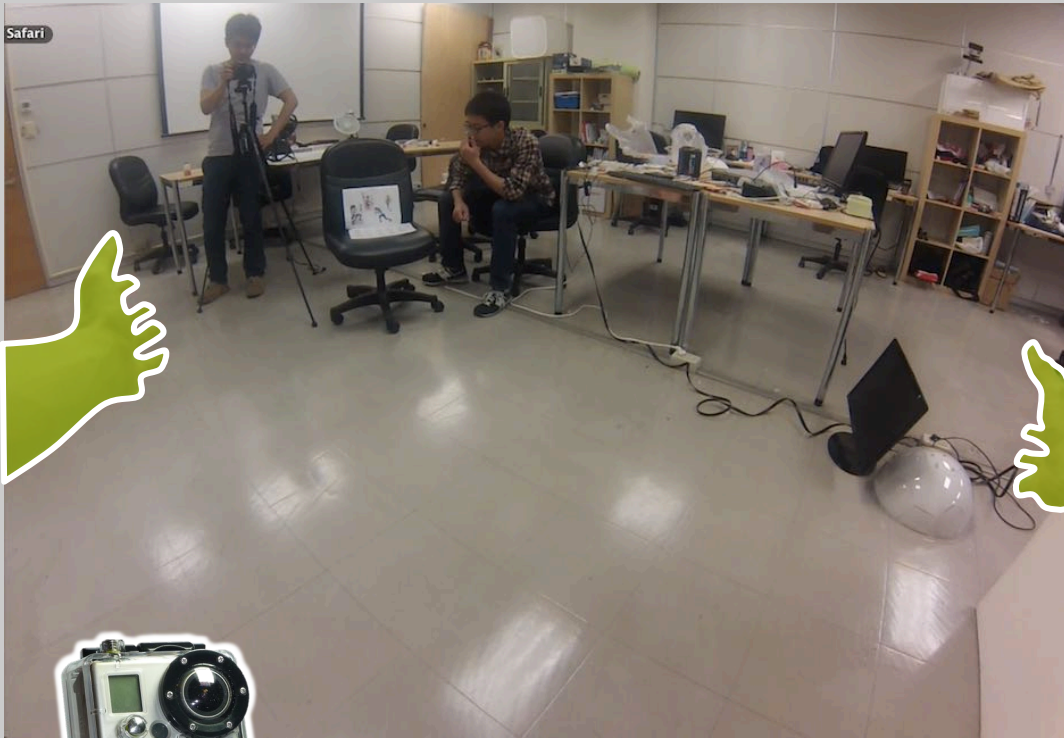
How wide is wide enough?

What visible
to the camera



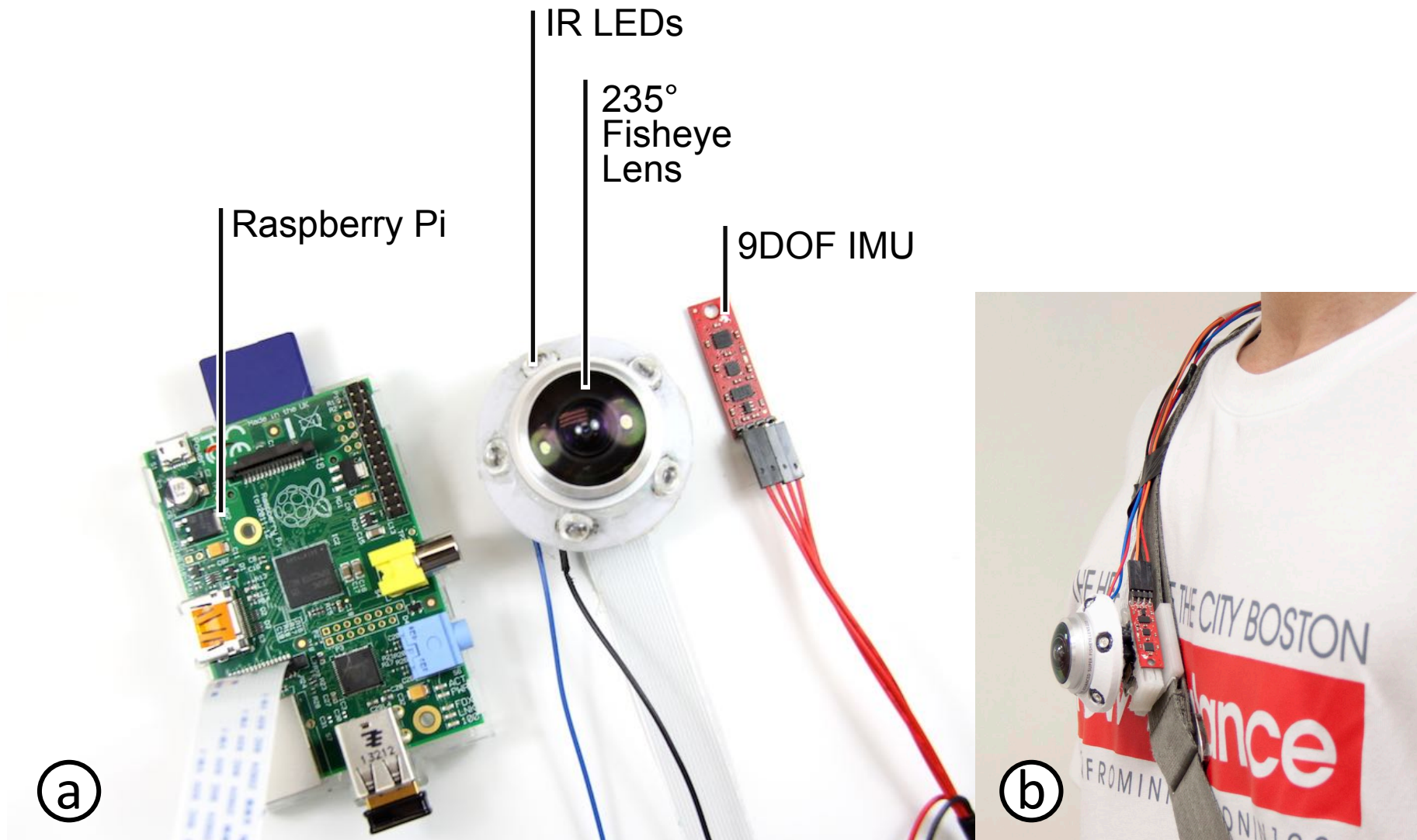
How wide is wide enough to see the body like this?



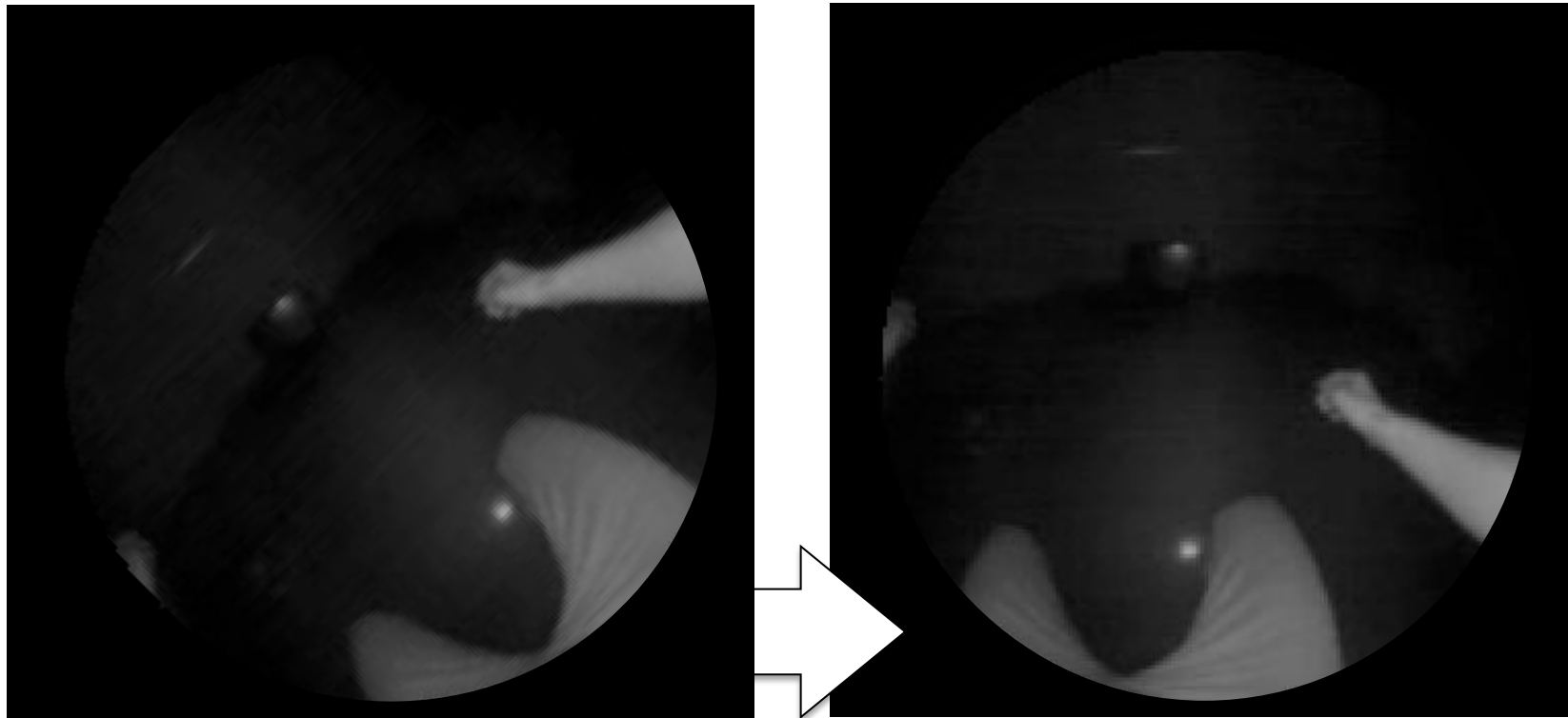




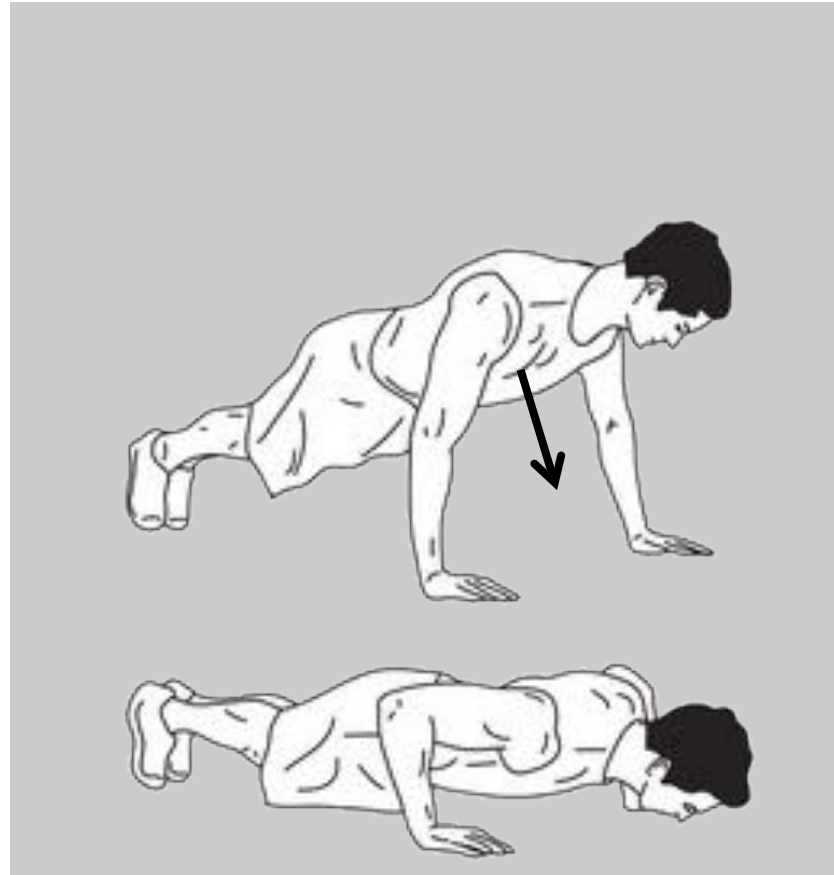
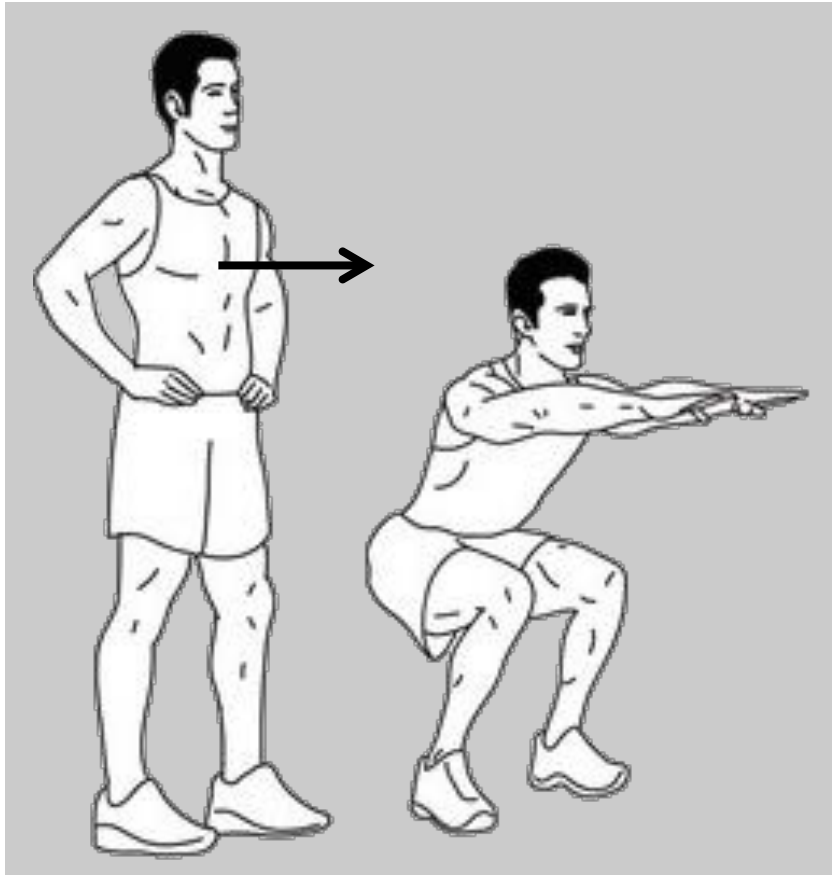
Proof-of-concept Prototype



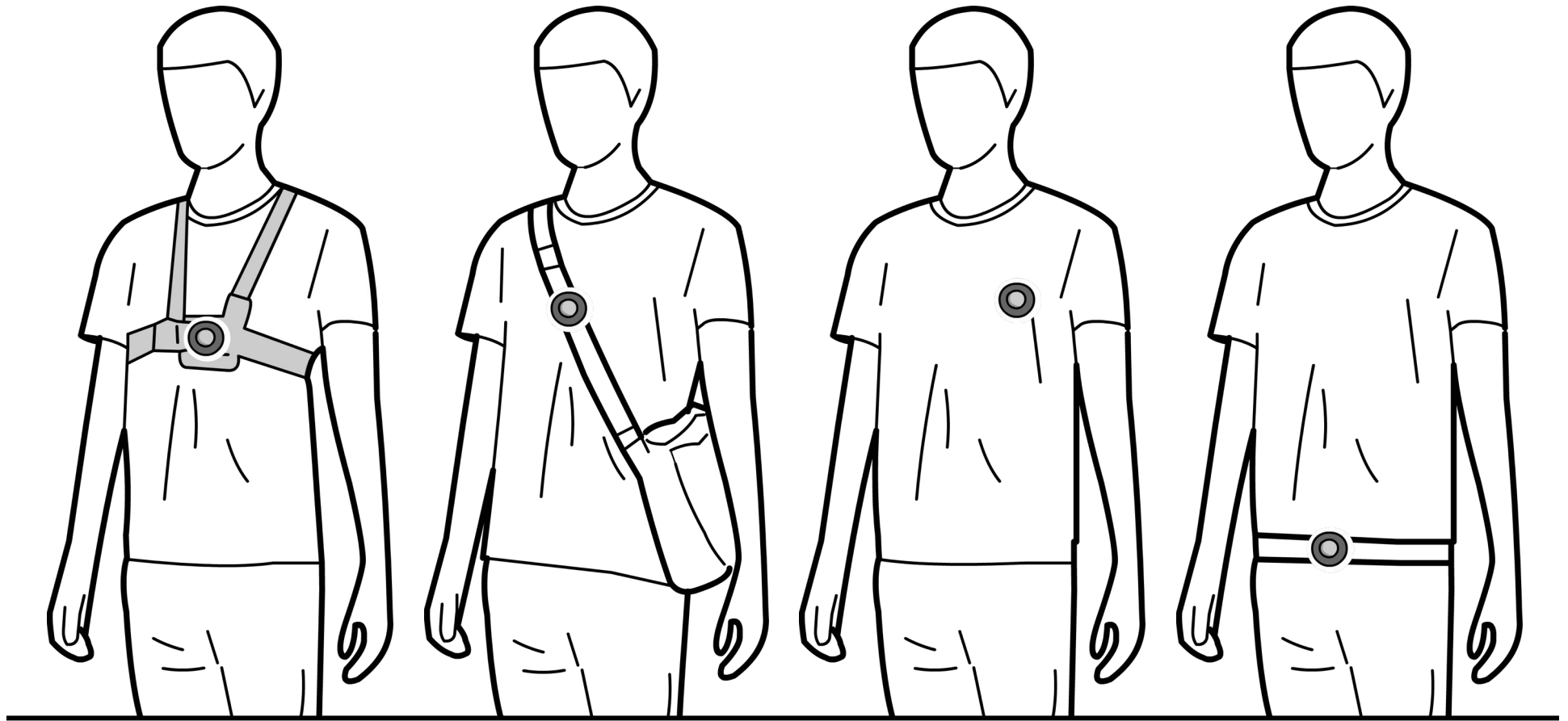
1. Reorient the image to up right



2. Differentiate gesture types

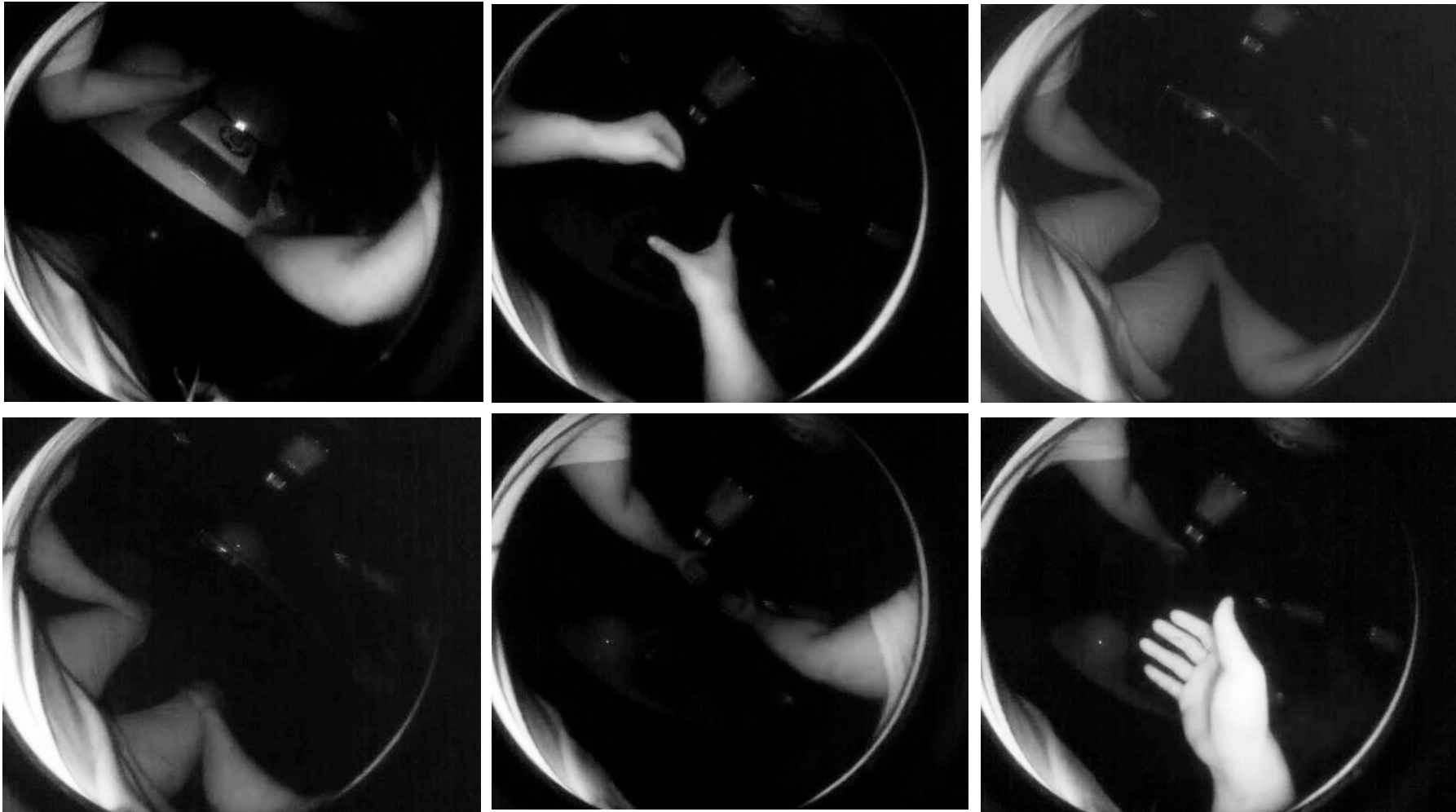


Wearable Forms

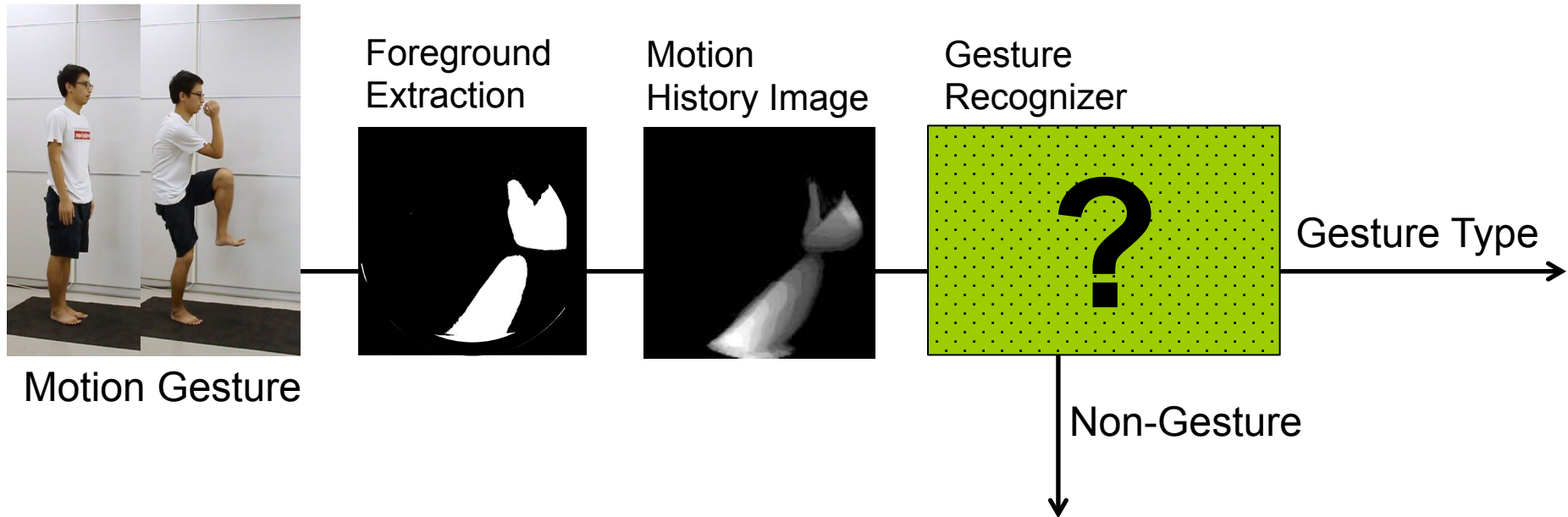




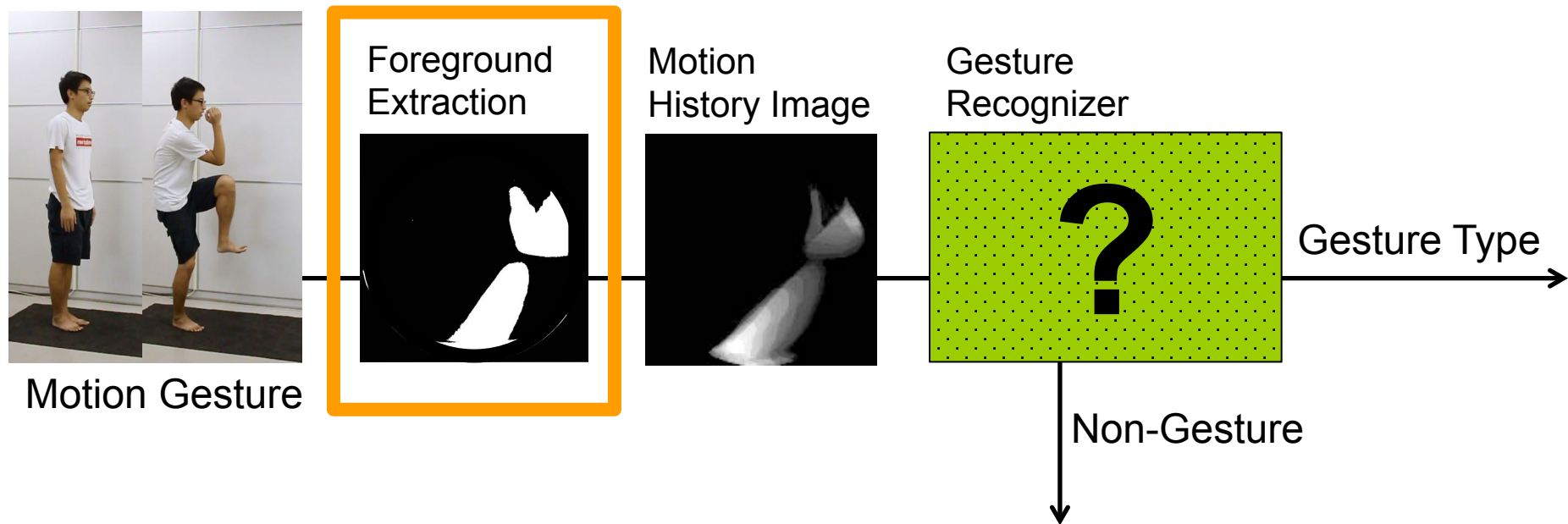
Eco-Centric View of Body Gestures



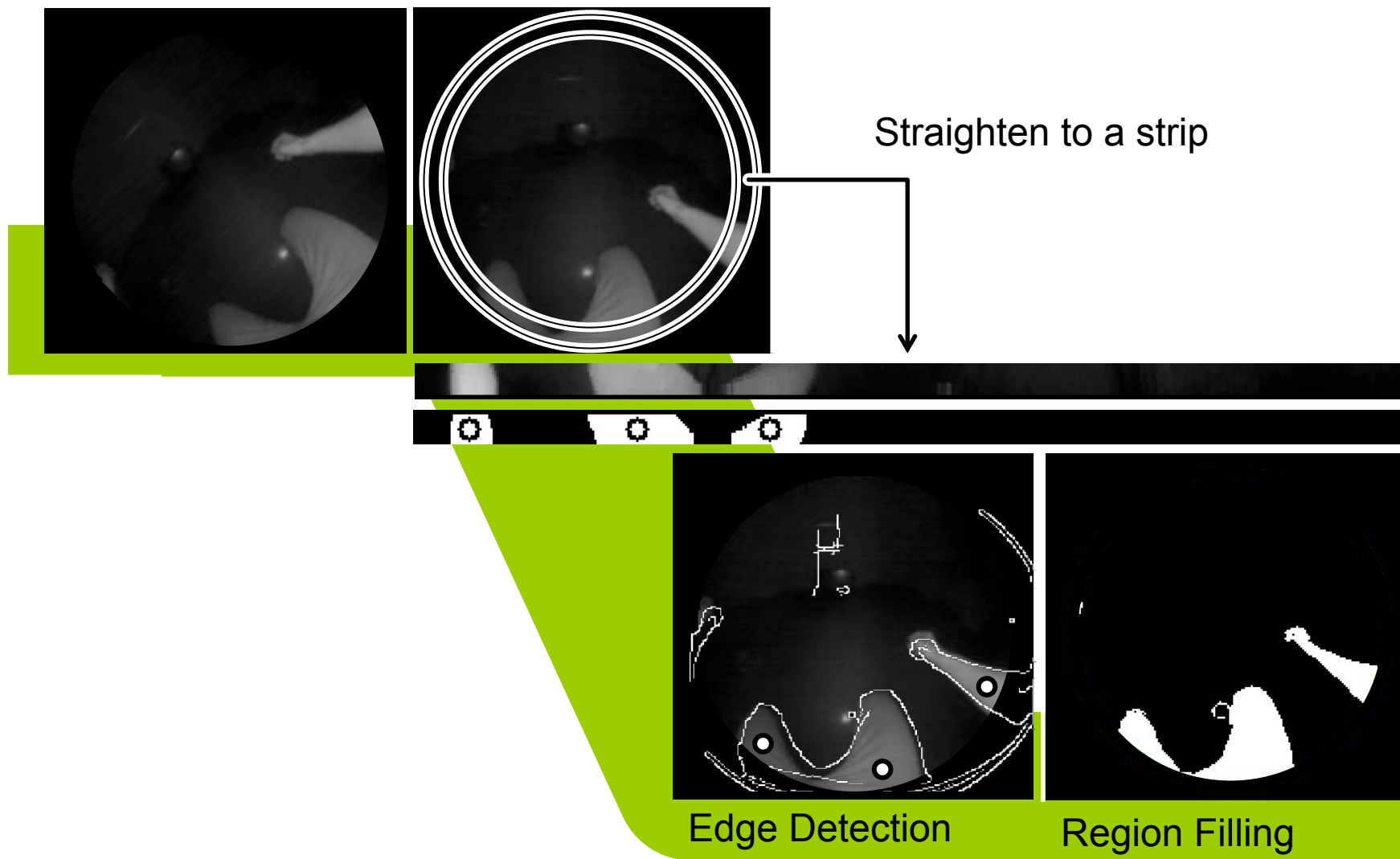
Pipeline of Body Gesture Recognition



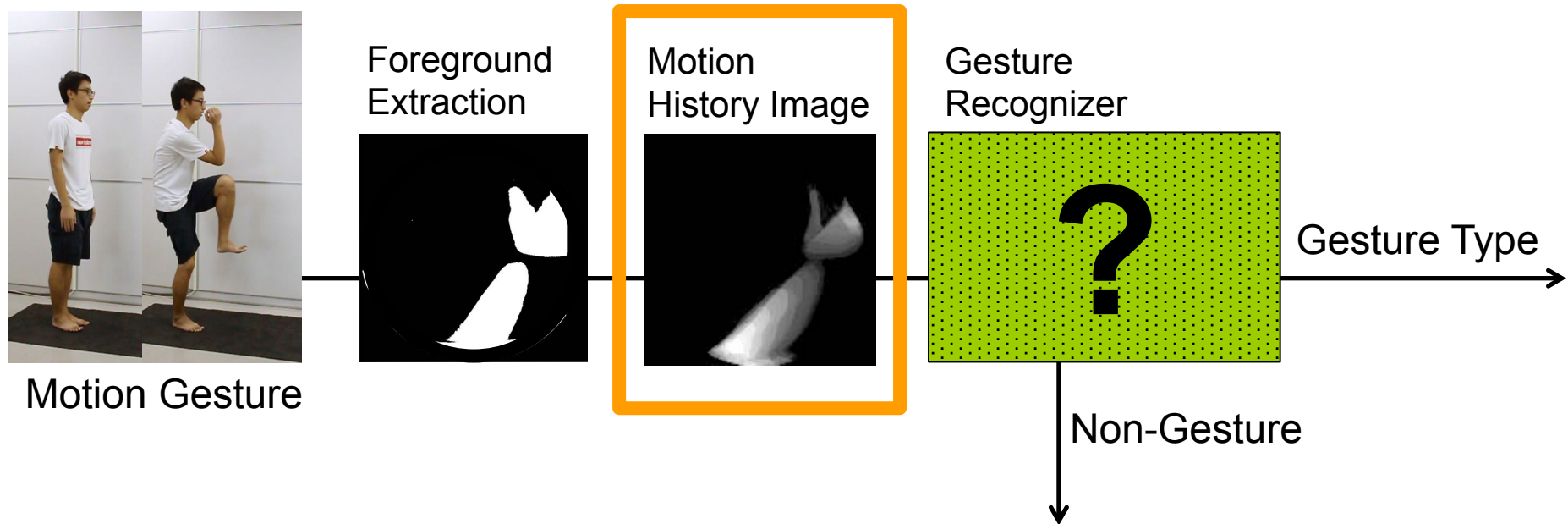
Pipeline of Body Gesture Recognition



Foreground Extraction



Pipeline of Body Gesture Recognition

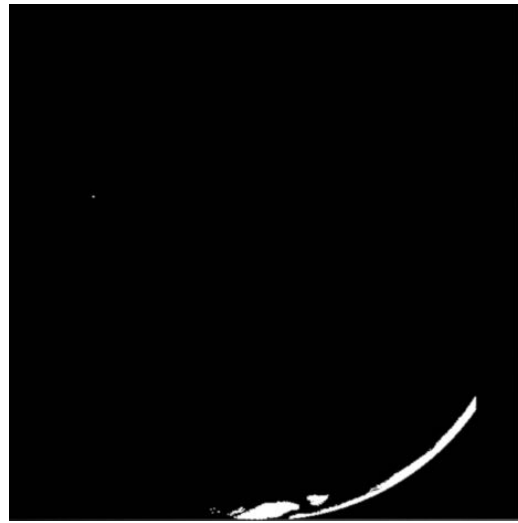
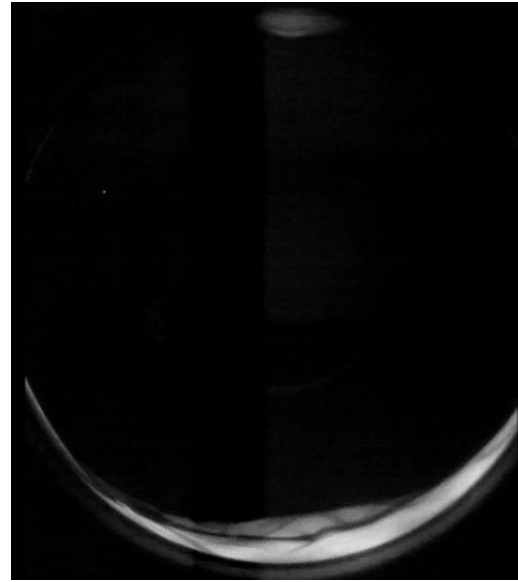


Motion History Image

:: an image template in which non-zero pixels simultaneously record the **spatial** and **temporal** aspects of motion.



Motion History Image

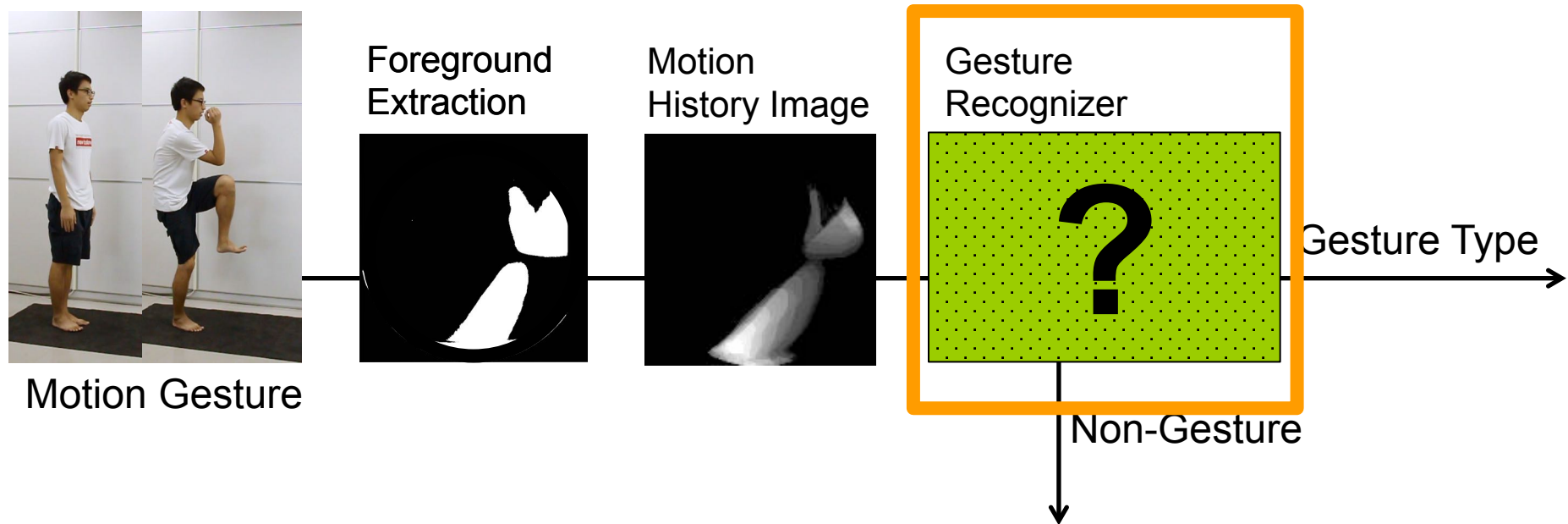


Foreground

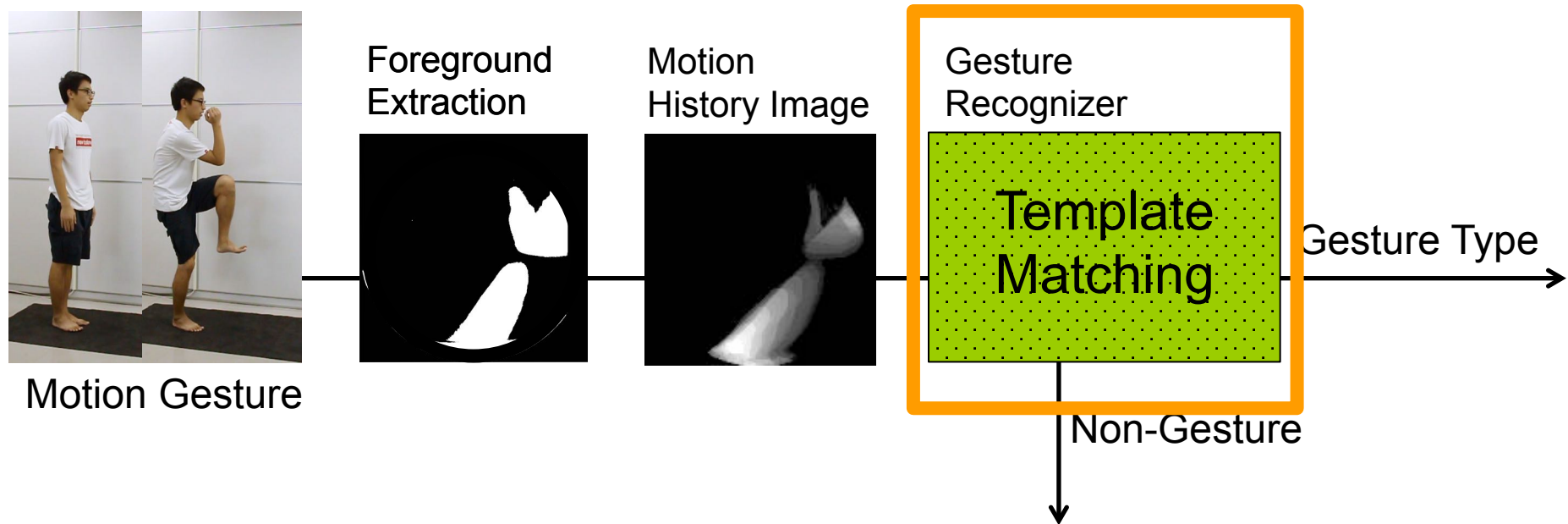


MHI

Pipeline of Body Gesture Recognition

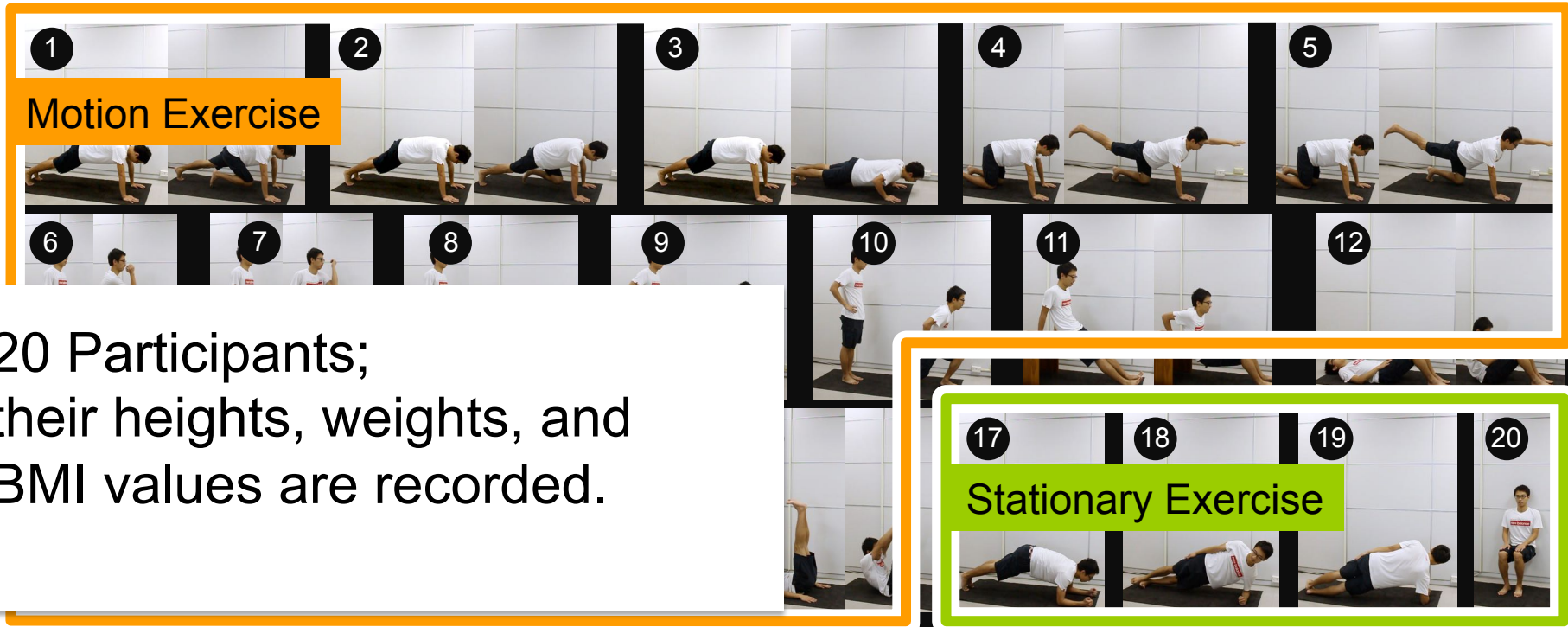


Pipeline of Body Gesture Recognition

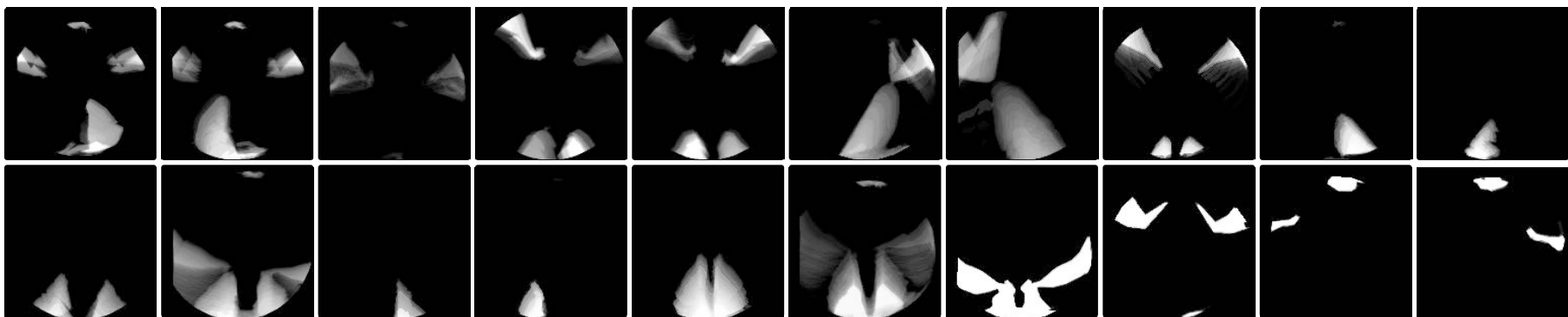


Experiment

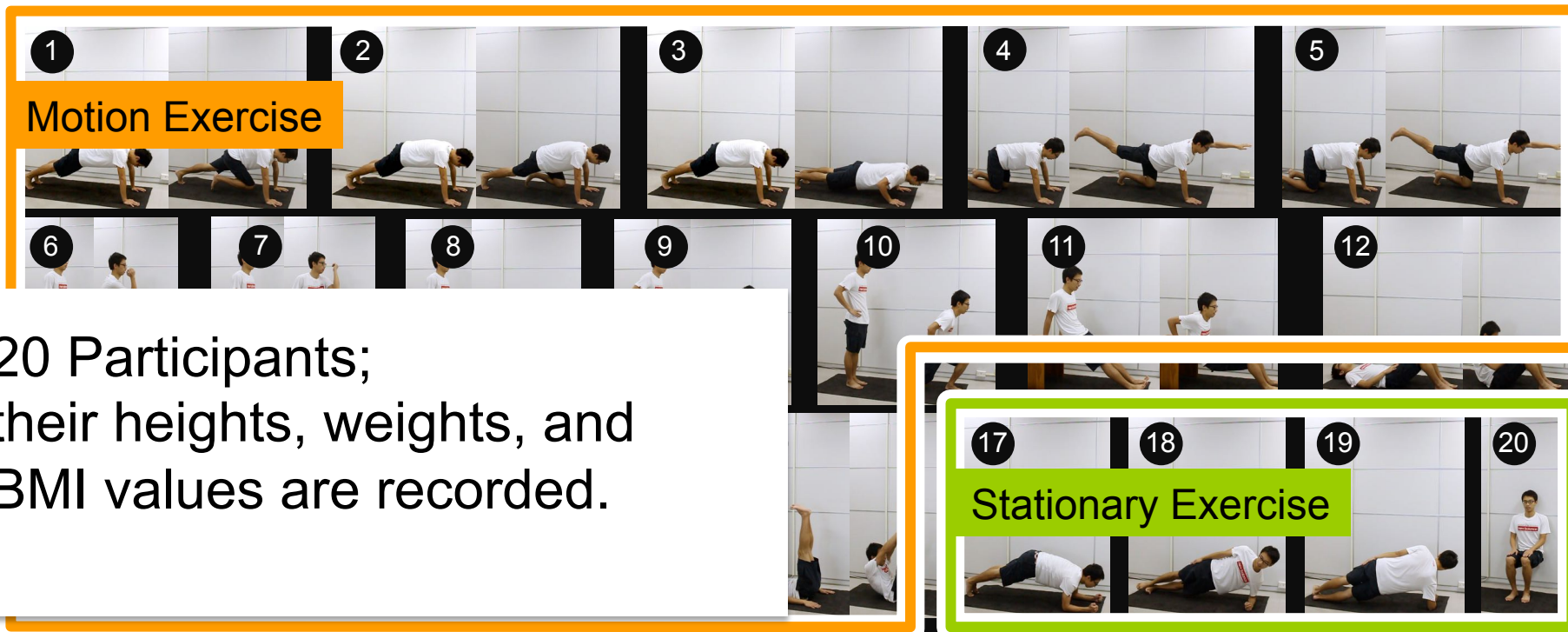
Experiment



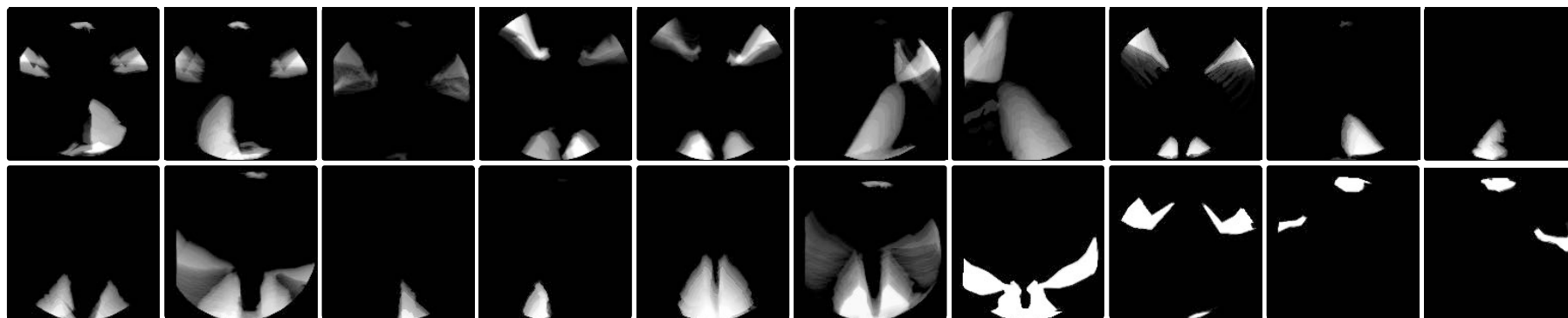
iMHI



Experiment

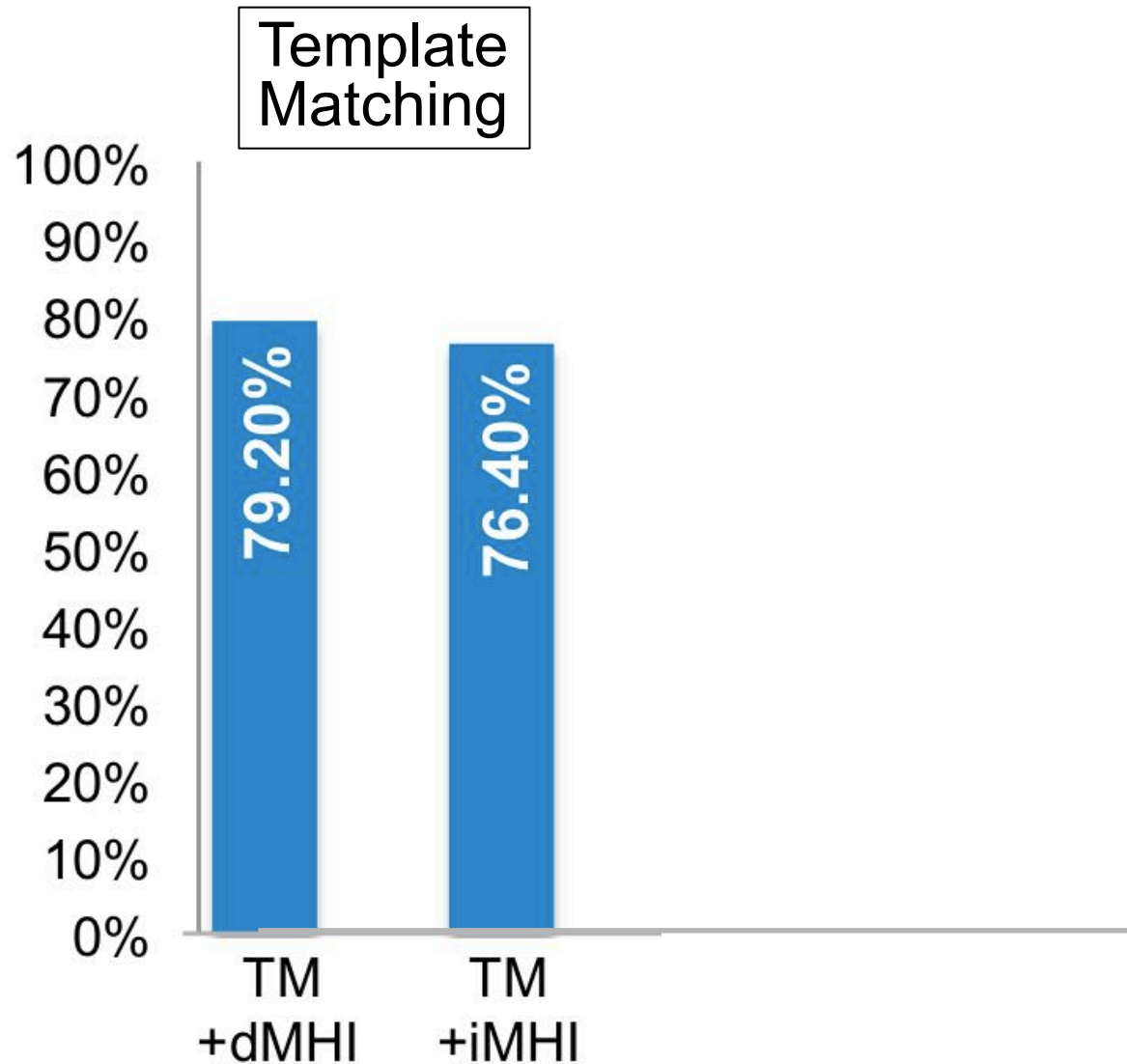


iMHI



dMHI

Experiment Result



Random Decision Forest (RDF)

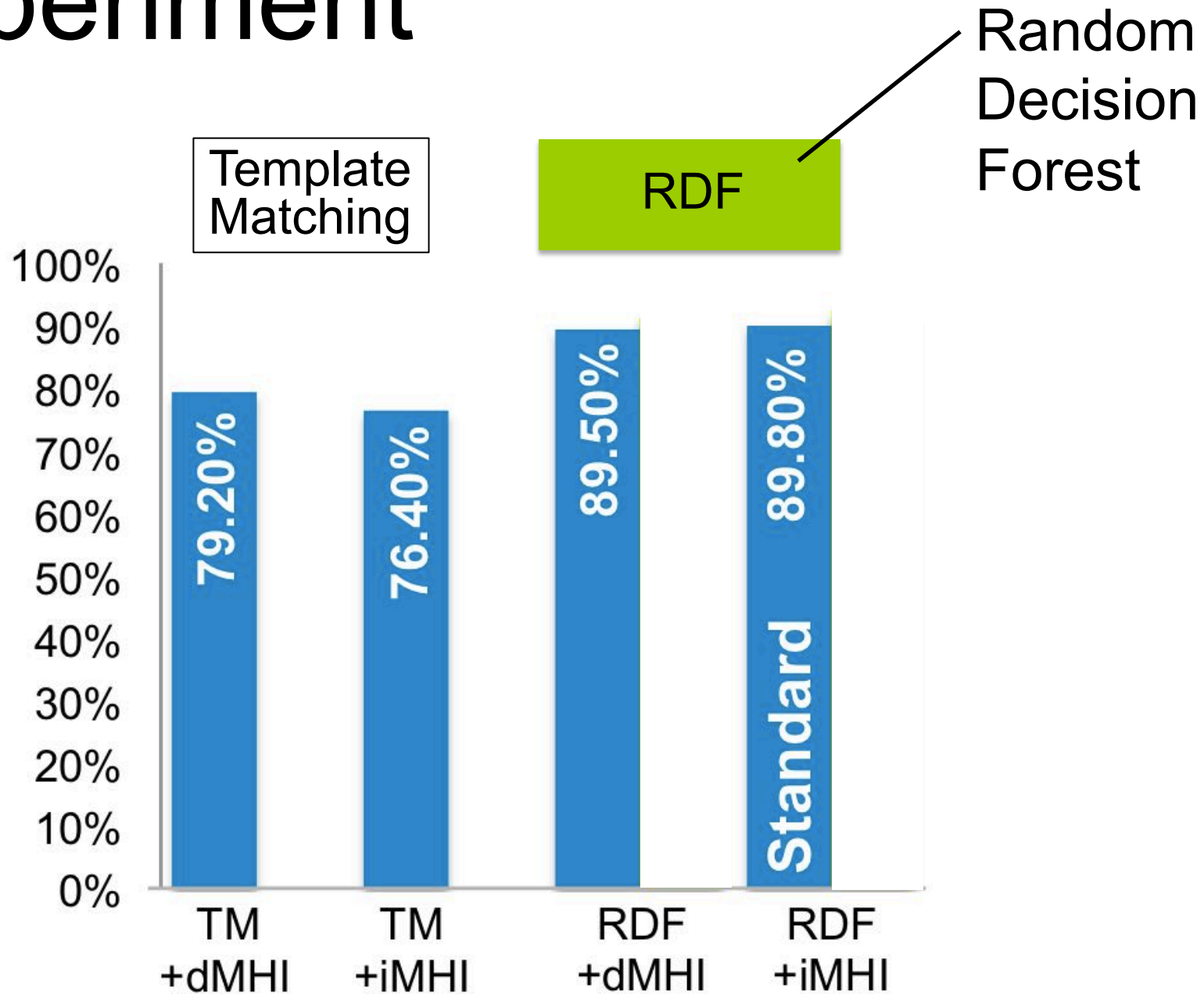
- Data-driven learning algorithm
- Notable example: Kinect
- RDF: a set of decision trees; each internal node is a weak learner

Feature response

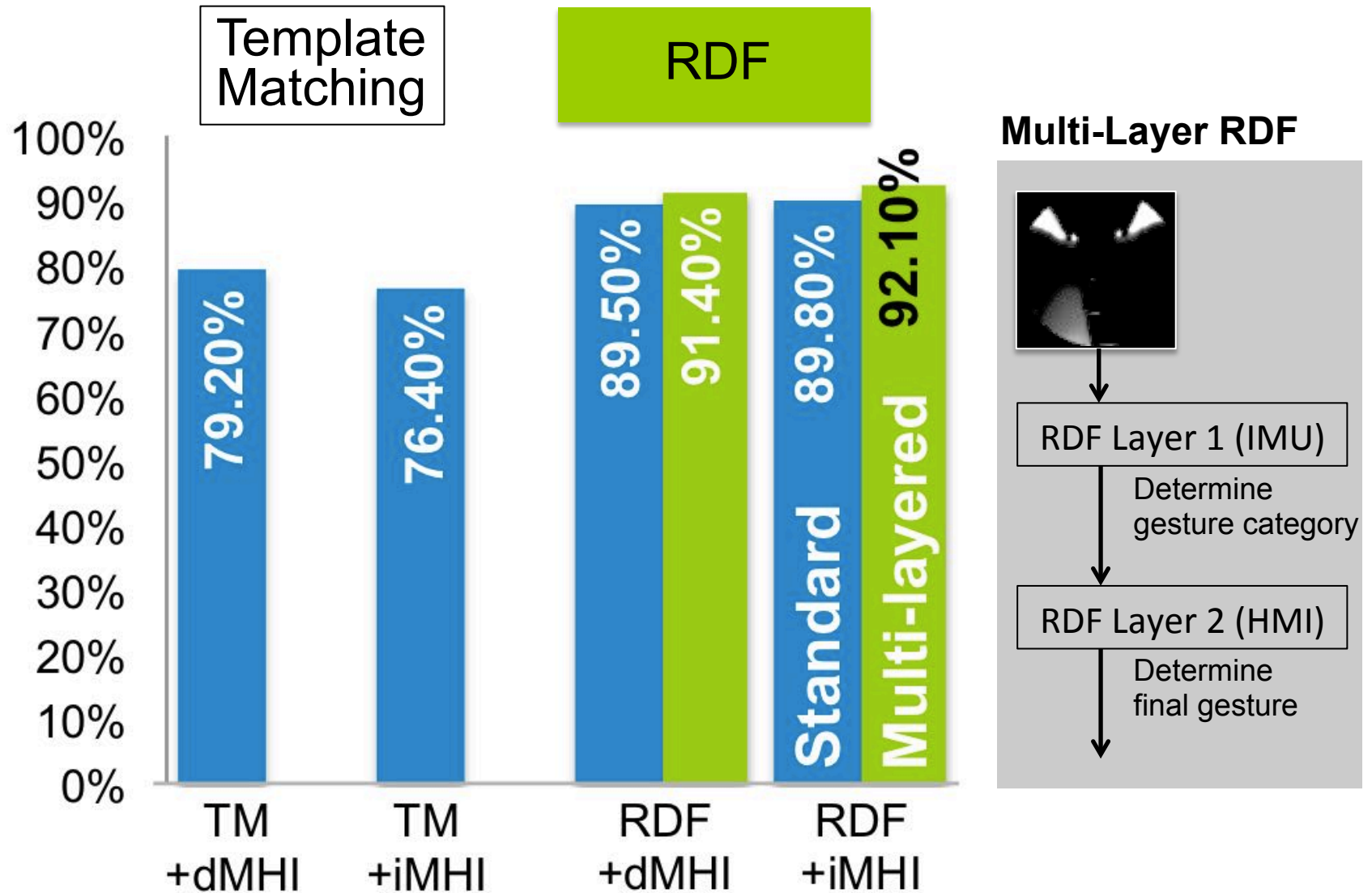
$$f(I, x) = i(x + u) - i(x + v)$$

image coordinate

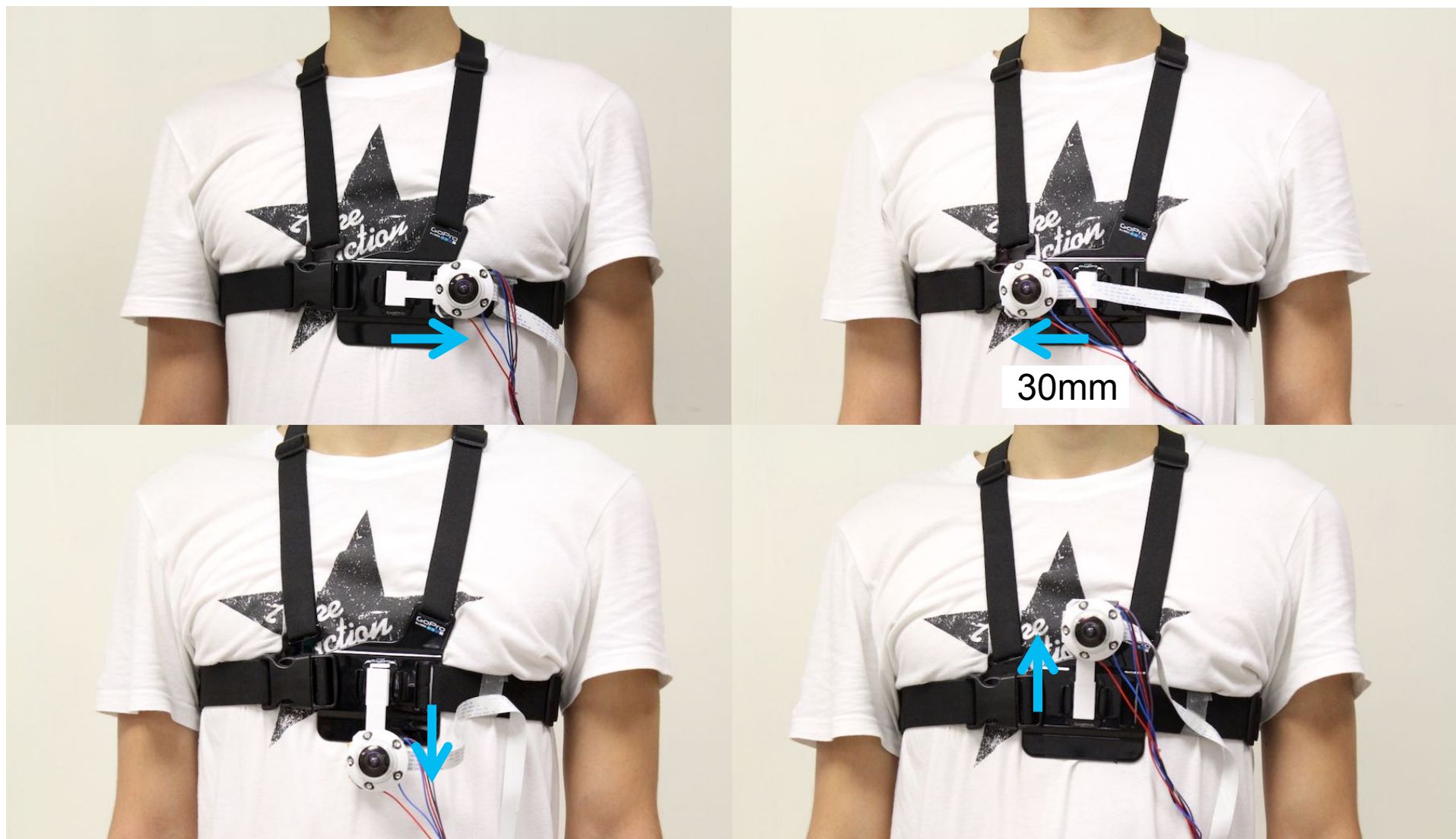
Experiment



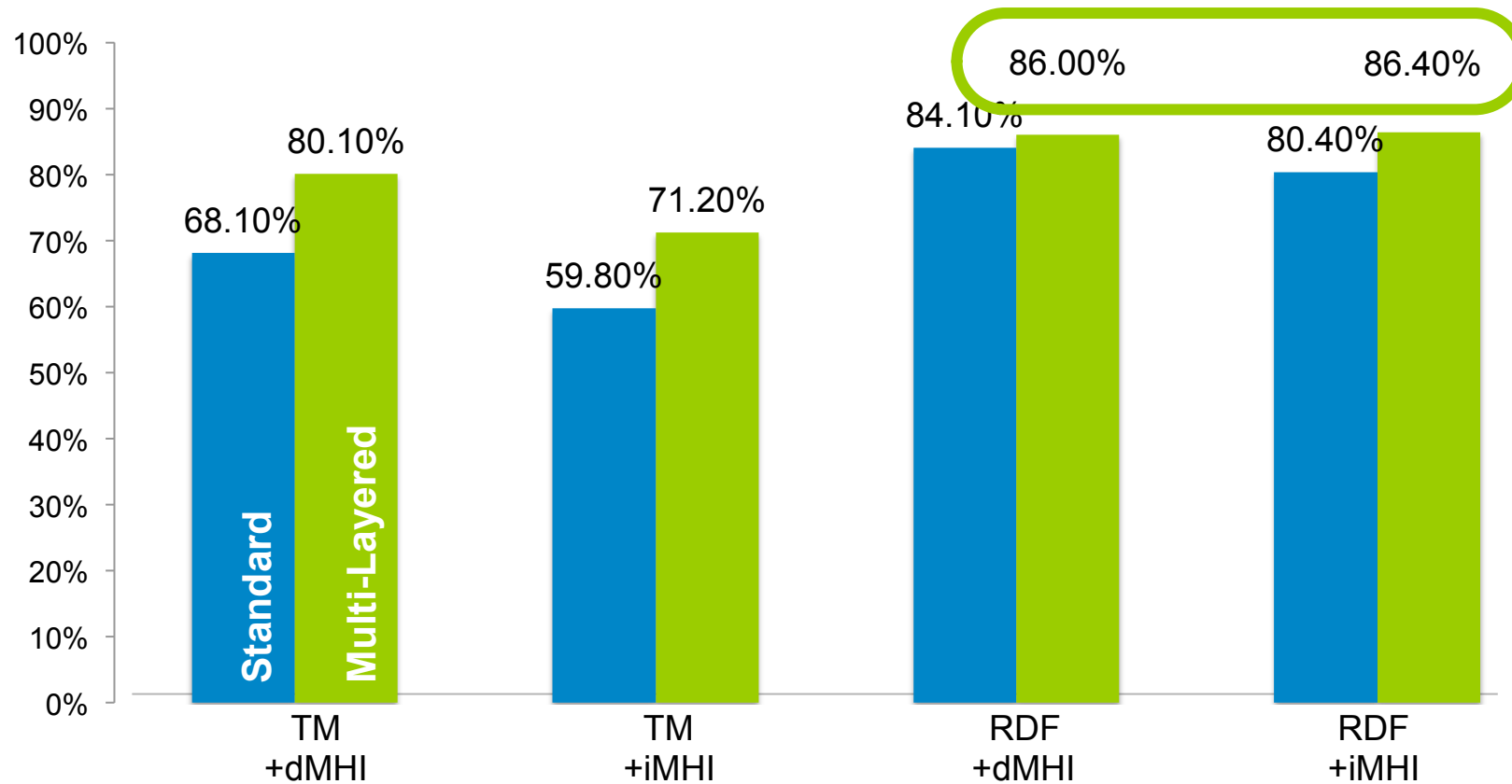
Experiment



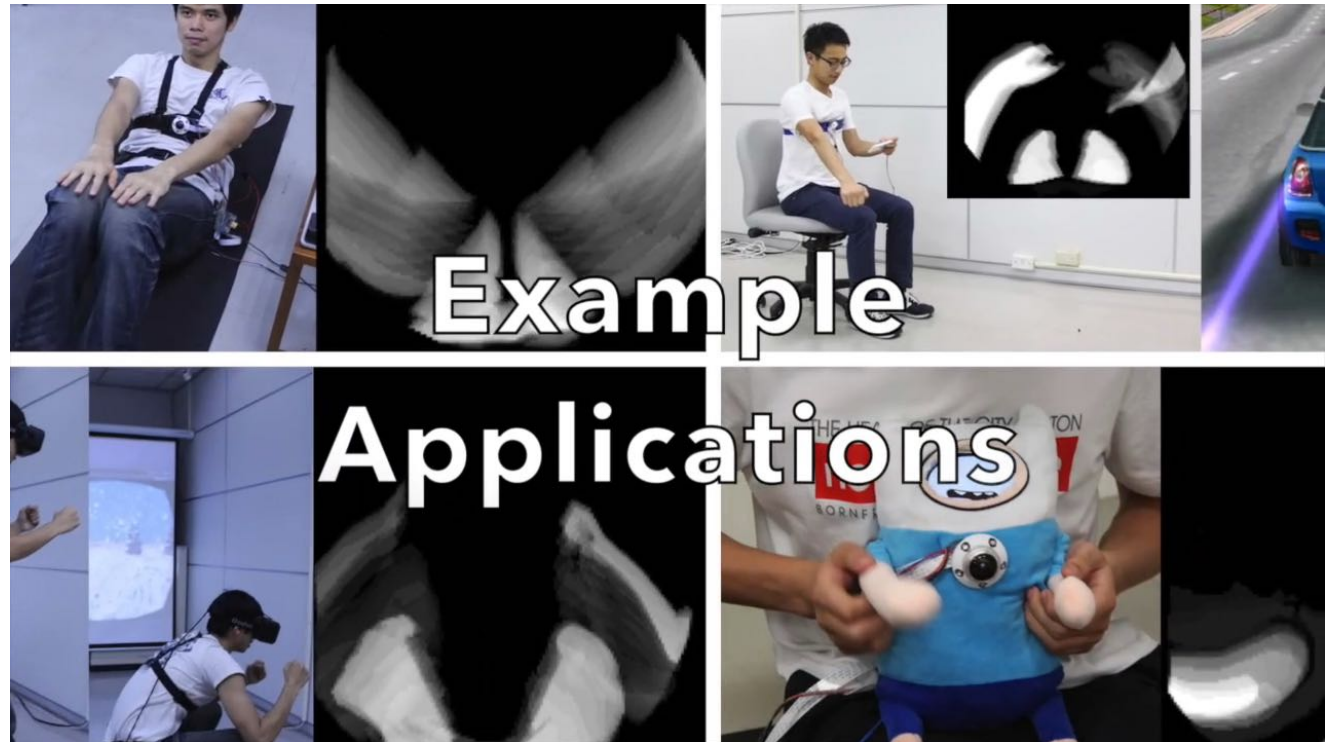
Experiment with offset

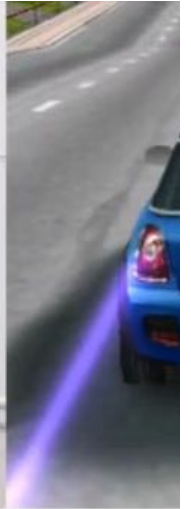
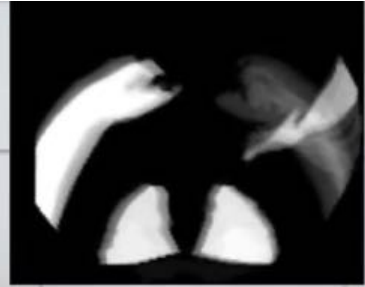
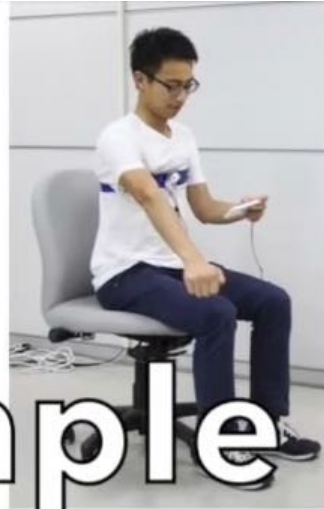
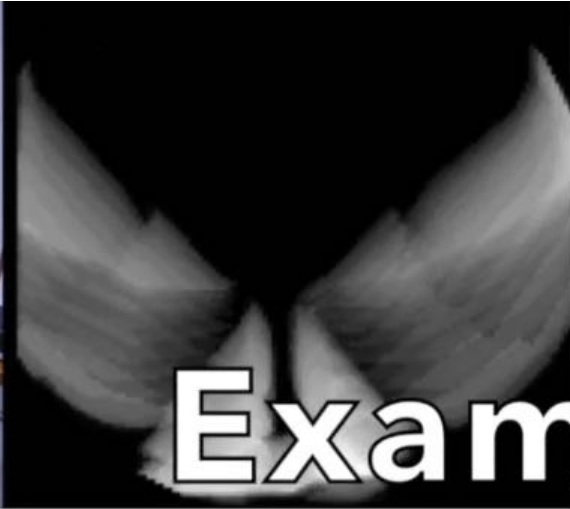


Experiment with offset

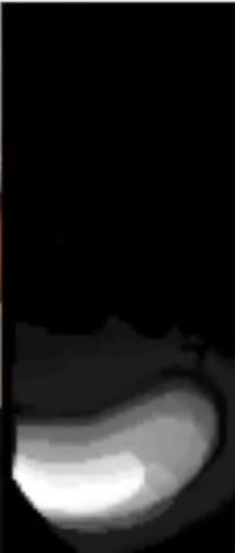


Applications





Example



Applications

Discussion

- Computer Vision Challenge
 - fisheye depth sensor
- Social Acceptance by Gender
 - further design for female users

Discussion

- Computer Vision Challenge
 - fisheye depth sensor
- Social Acceptance by Gender
 - further design for female users

Conclusion

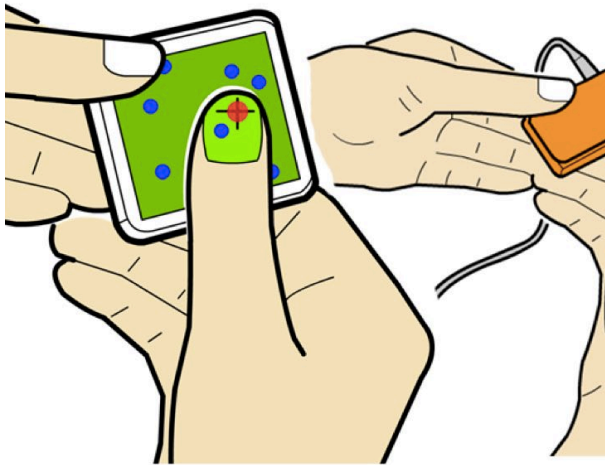
- Cyclops: a single-piece wearable device for full-body gesture input
- The main contribution:
 - the idea of determining body posture using an ego-centric perspective of the user.
- We developed a proof-of-concept device to demonstrate the feasibility of cycplos device.

Thank you.

CHI 2013

NailDisplay

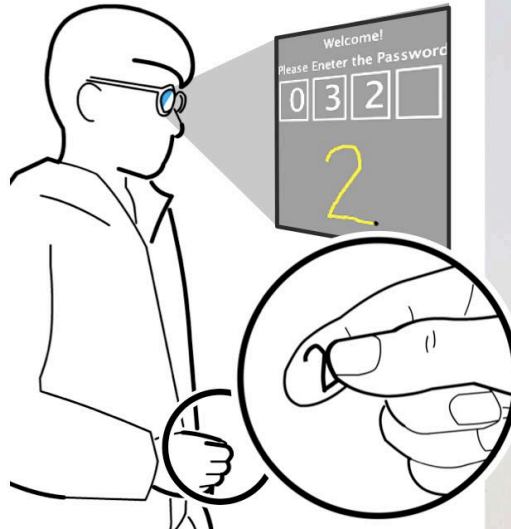
Bringing Always-Available
Visual Display to Fingertips



UIST 2013

FingerPad

Private and Subtle Interaction
Using Fingertips



CHI 2015

Cyclops

Wearable and Single-Piece
Full-Body Gesture Input Devices

