



# PuPoP: Pop-up Prop on Palm for Virtual Reality

**Shan-Yuan Teng**   Tzu-Sheng Kuo   Chi Wang   Chi-huan Chiang  
Da-Yuan Huang   Liwei Chan   Bing-Yu Chen



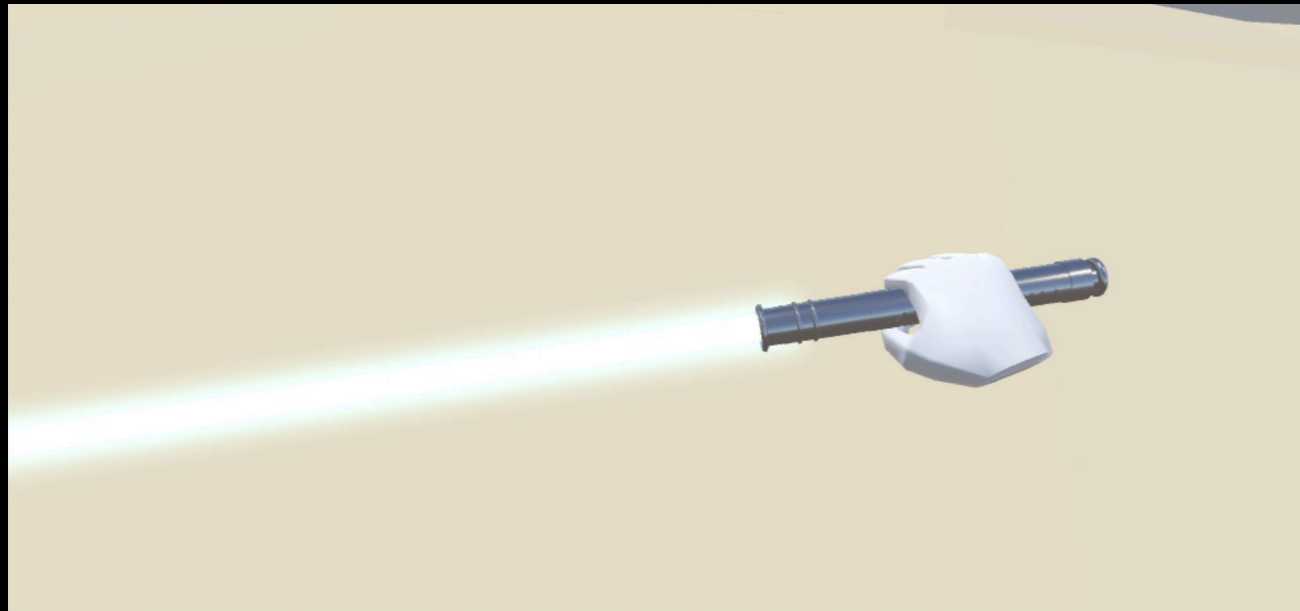
National  
Taiwan  
University



National  
Chiao Tung  
University



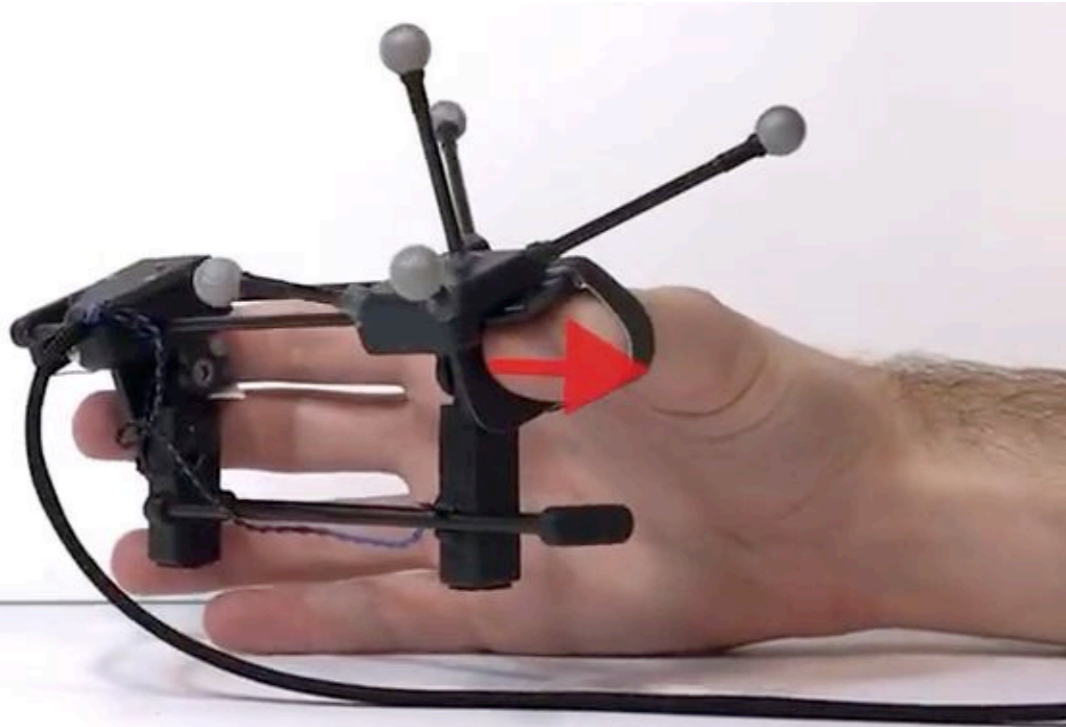
**TAIWAN  
TECH**  
NATIONAL TAIWAN UNIVERSITY OF  
SCIENCE AND TECHNOLOGY



Pick up a Lightsaber

Throw a bomb

# Related Work    Wearable Haptic Devices

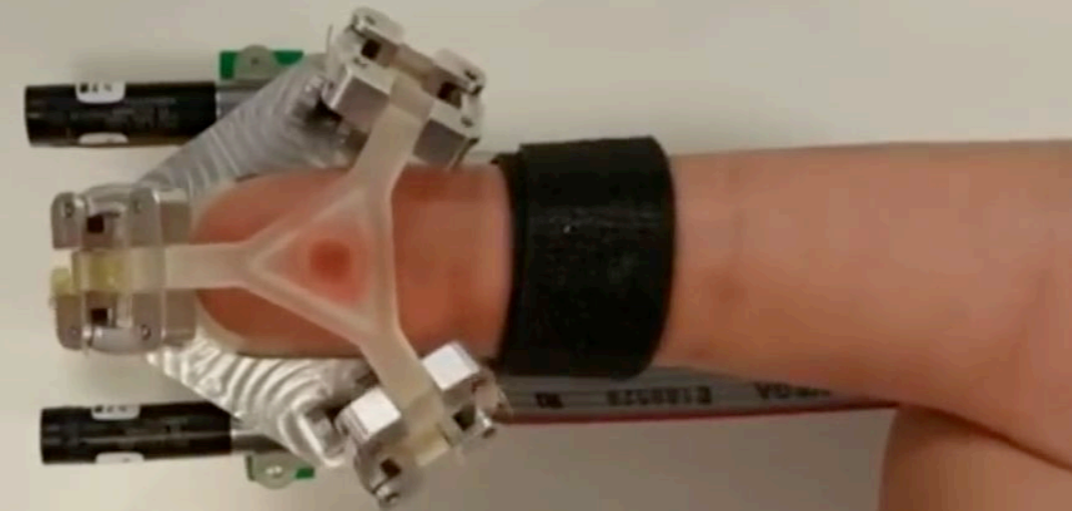


**Force Feedback**

*Choi, et al. UIST '17*

*Schorr, et al. CHI '17*

**Tactile Feedback**



# Related Work    Physical Proxy Interfaces

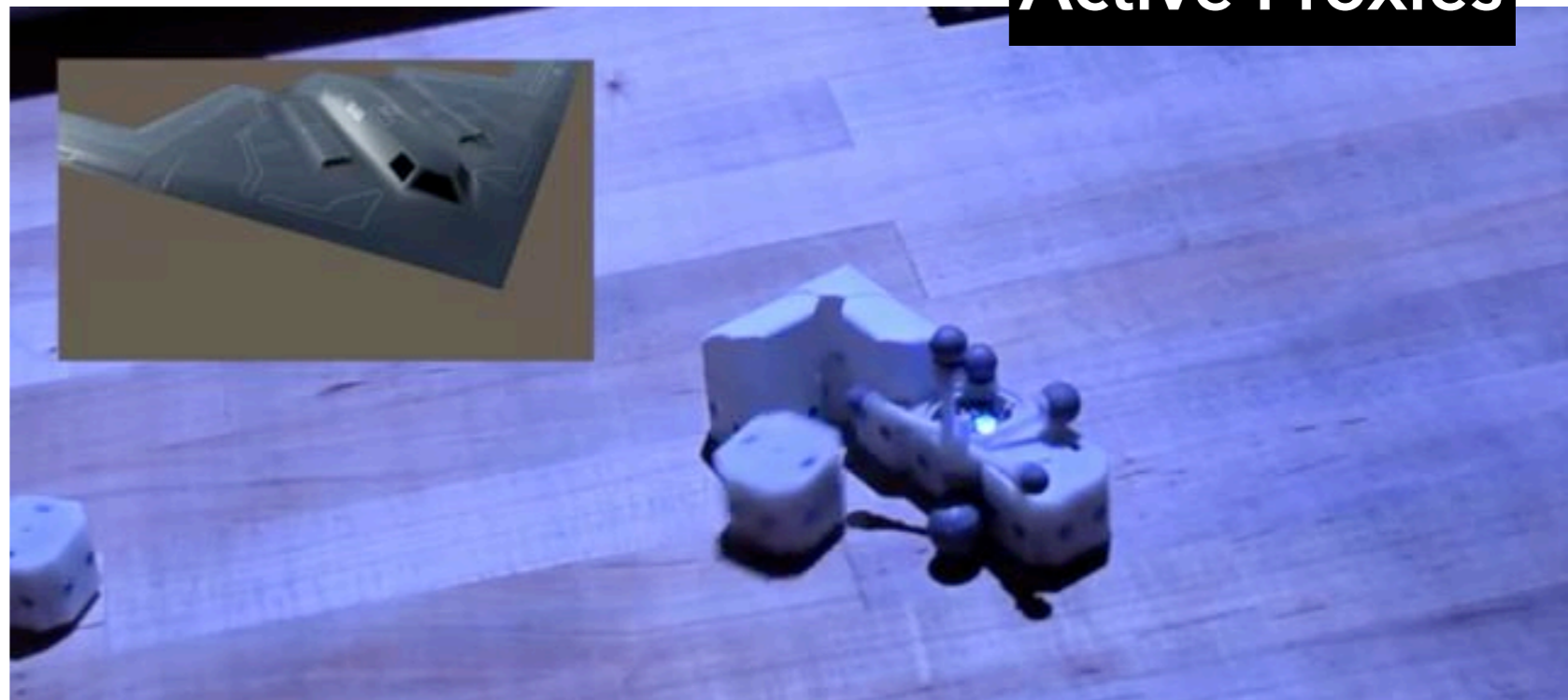
## Passive Proxies



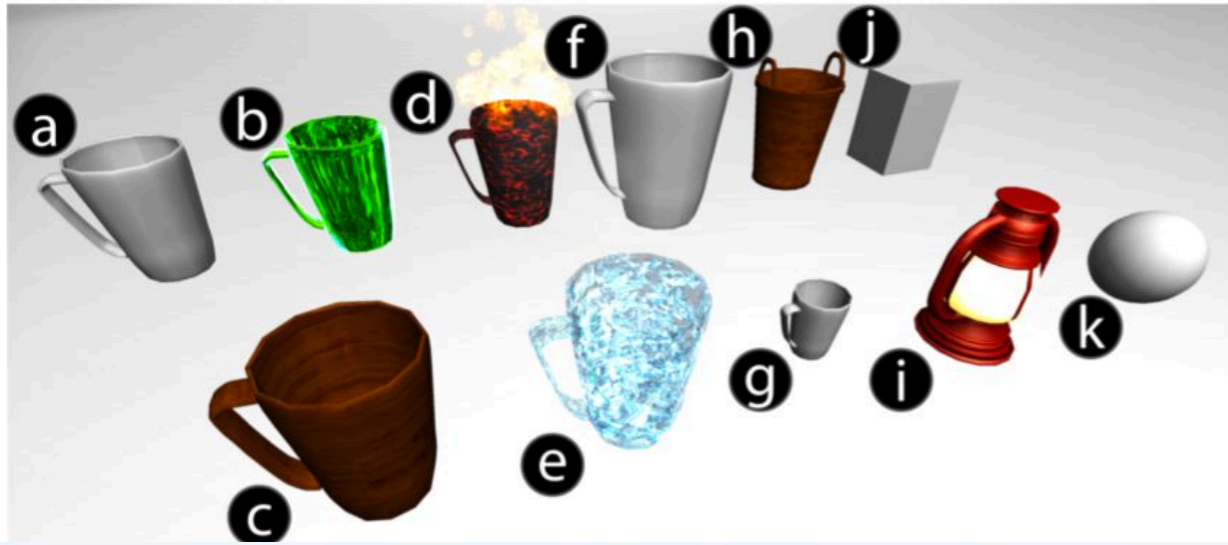
Hettiarachchi and Wigdor. CHI '16

Zhao, et al. ISS '17

## Active Proxies



# Related Work Visuo-Haptic Illusion



*Simeone, et al. CHI '15*

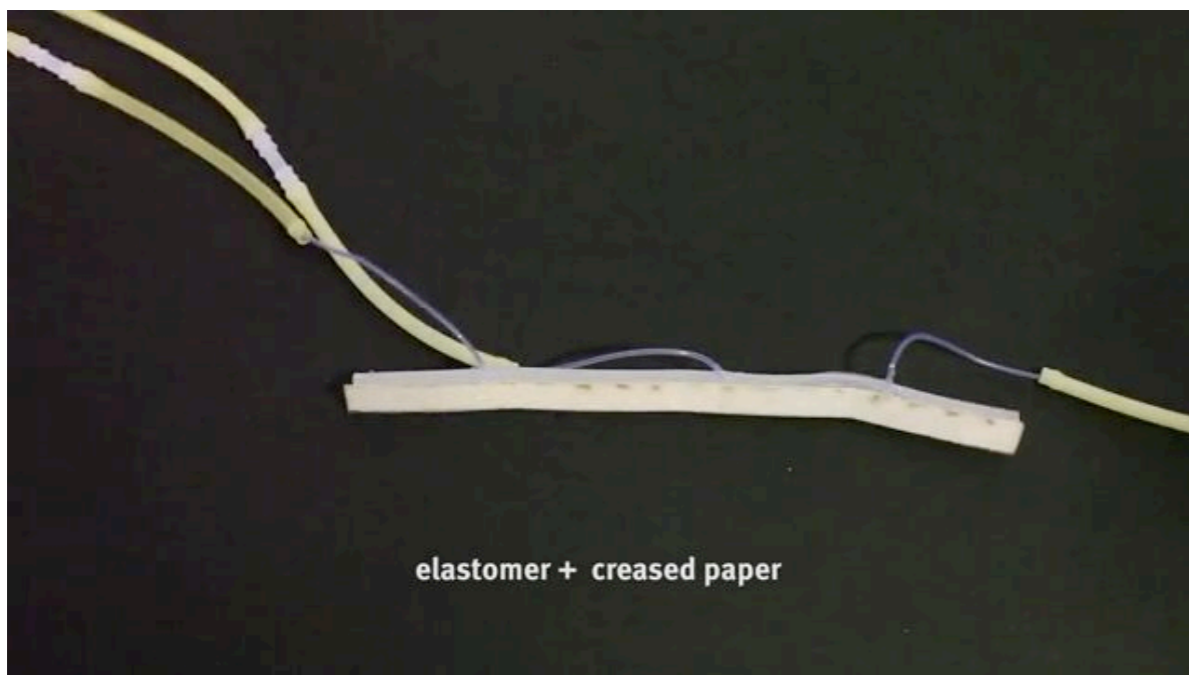


*Fujinawa, et al. VRST '17*

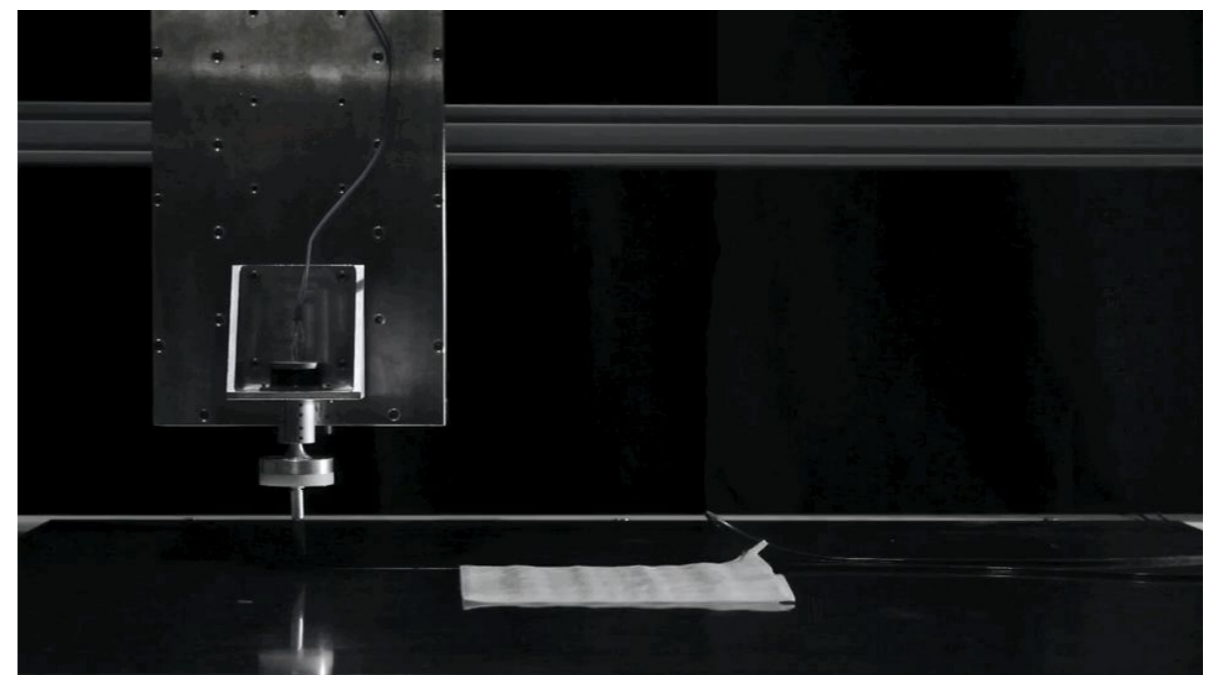
# Related Work    Pneumatic Interfaces



Harrison and Hudson. CHI '09



Yao, et al. UIST '13



Ou, et al. UIST '16

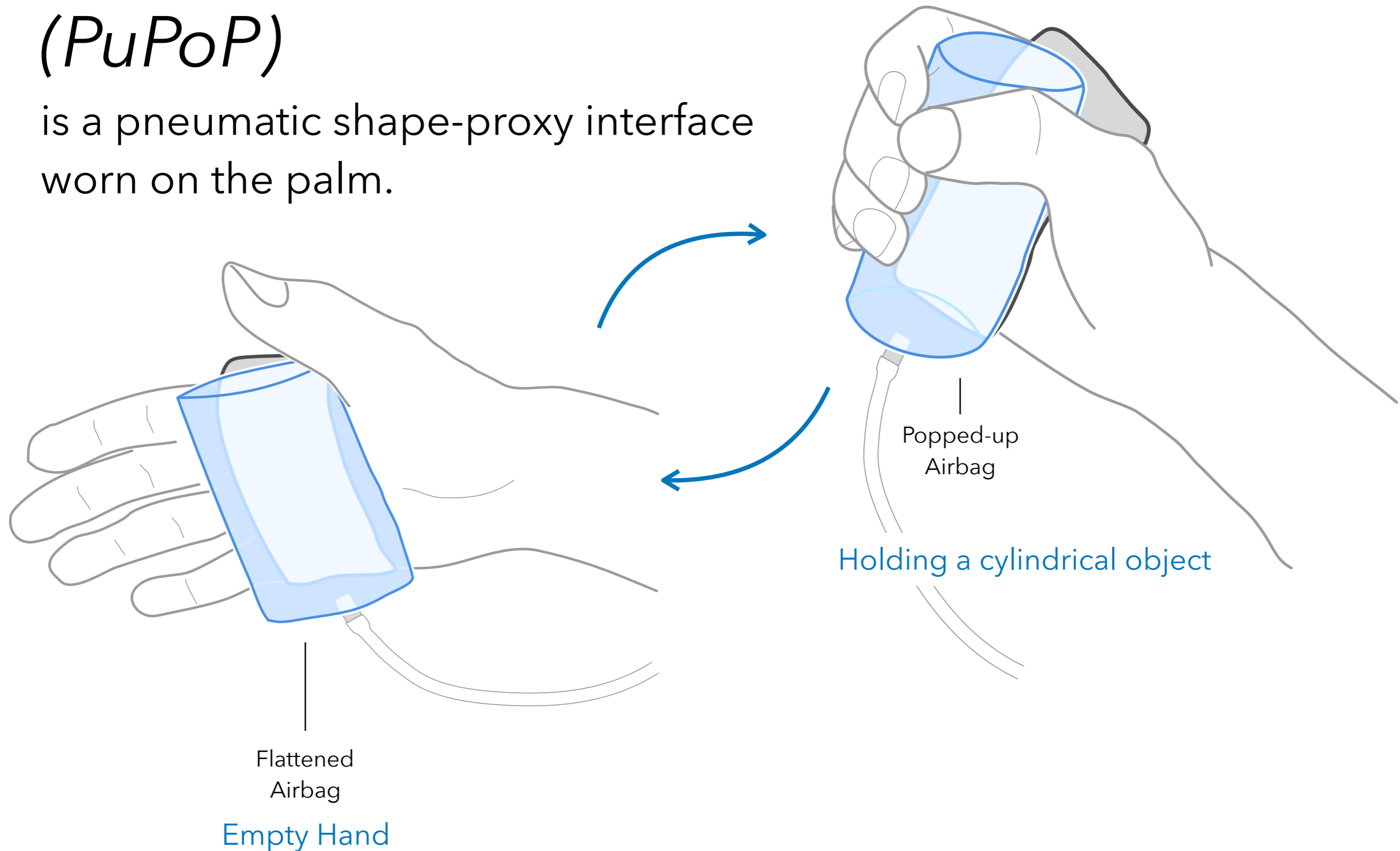
Physical Proxies



Always-available in VR

# Pop-up Prop on Palm (PuPoP)

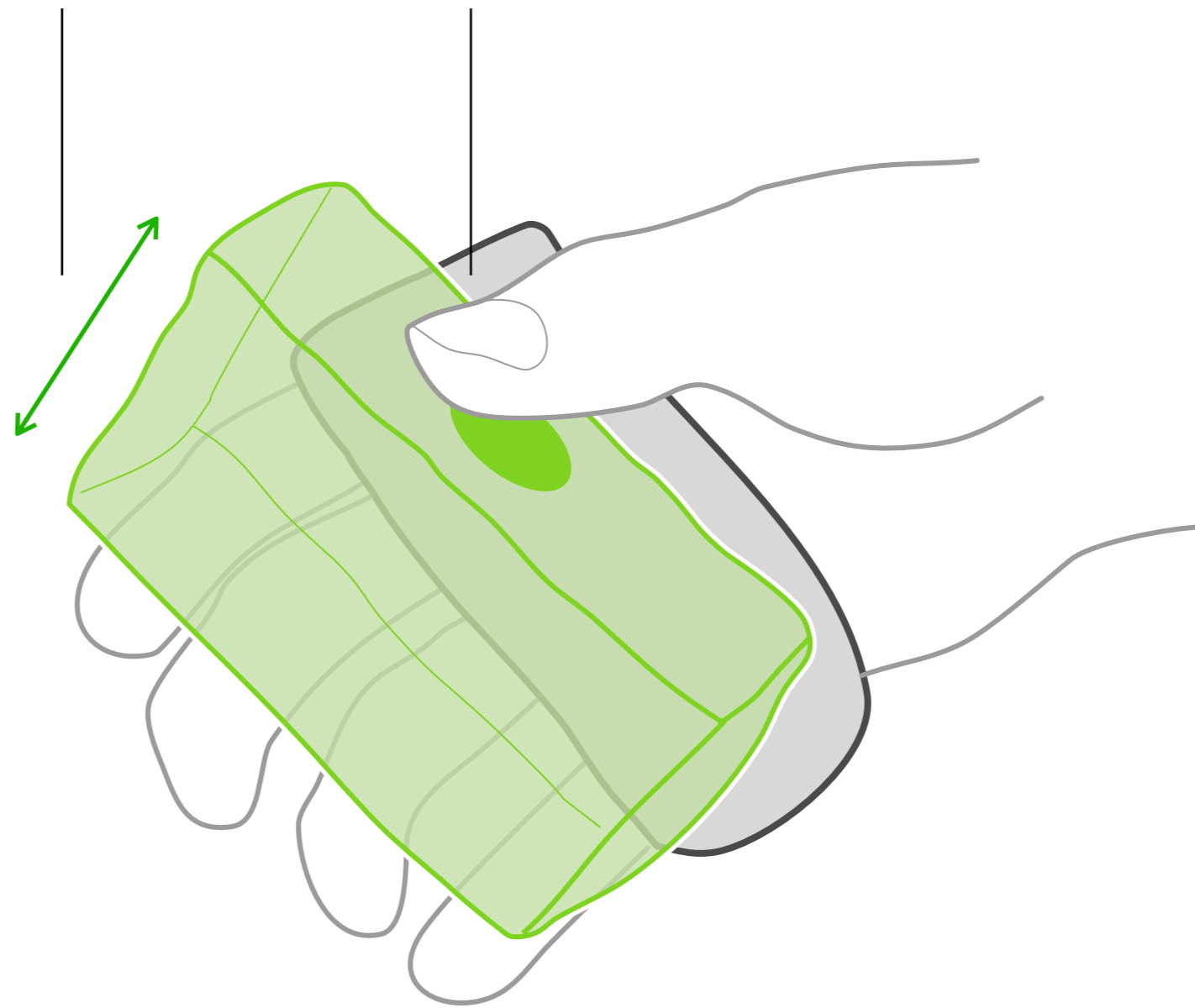
is a pneumatic shape-proxy interface worn on the palm.



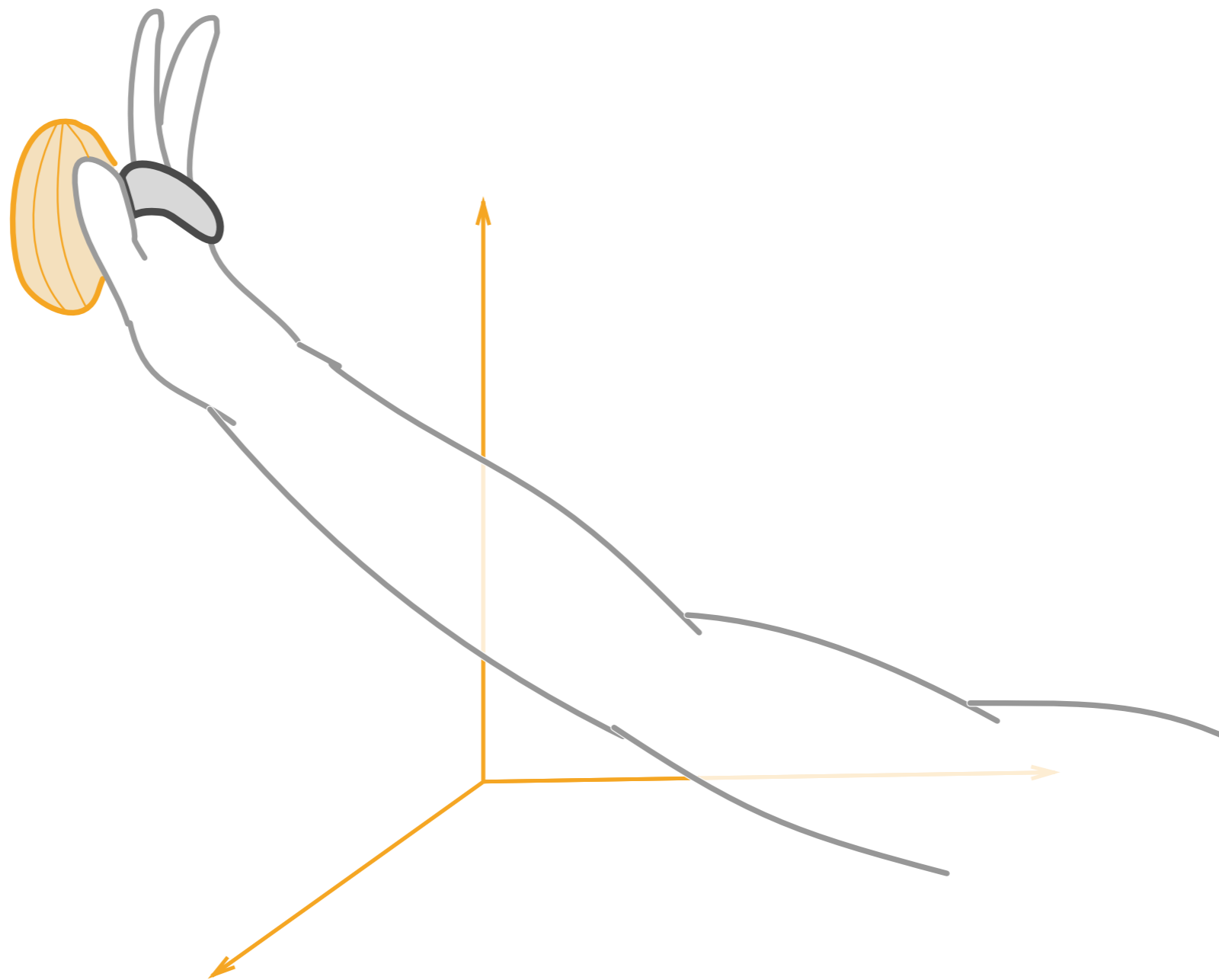


Force feedback

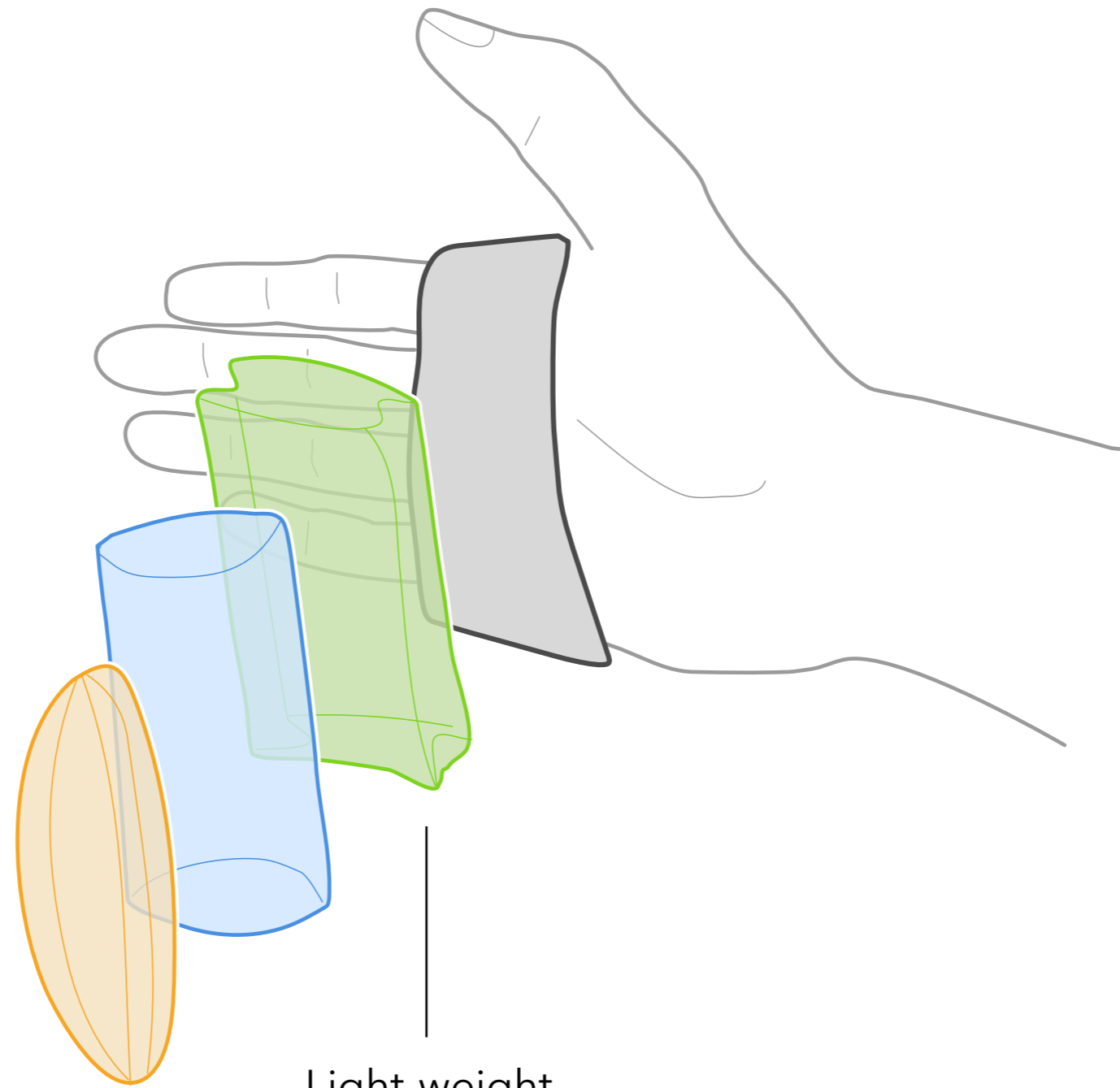
Skin tactile feedback



Natural grasping sensation.



Always available in the entire VR interaction space.



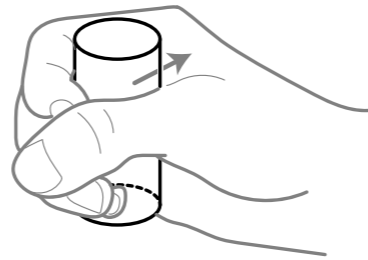
Light-weight

Easy to wear and take off.

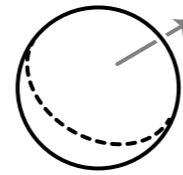
# Design & Implementation

# Design Overview

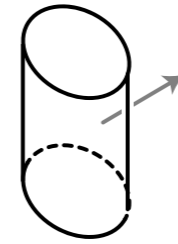
## Primitive shapes



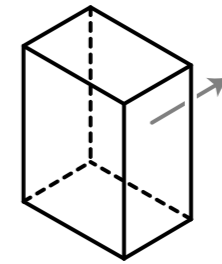
**Power  
grasp**



*Sphere*

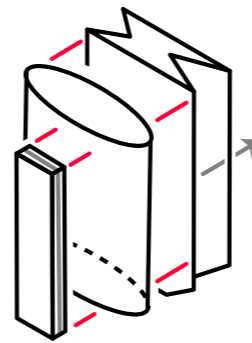


*Cylinder*

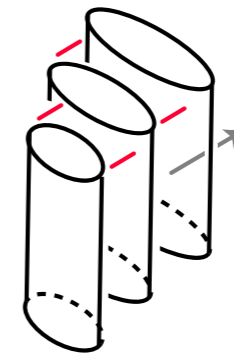


*Box*

## Prop stacking

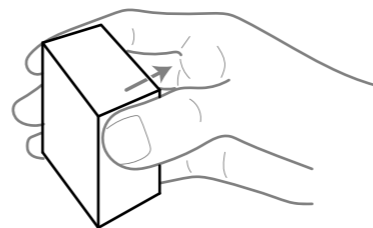


*Shape stacking*

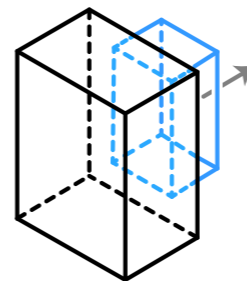


*Size stacking*

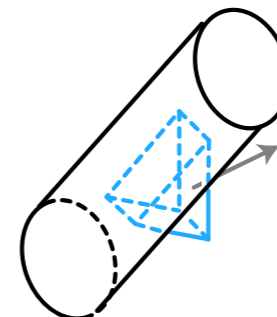
## Prop extension



**Precision  
grasp**



*Parallel extension*



*Tilt extension*

# Pneumatic Control System

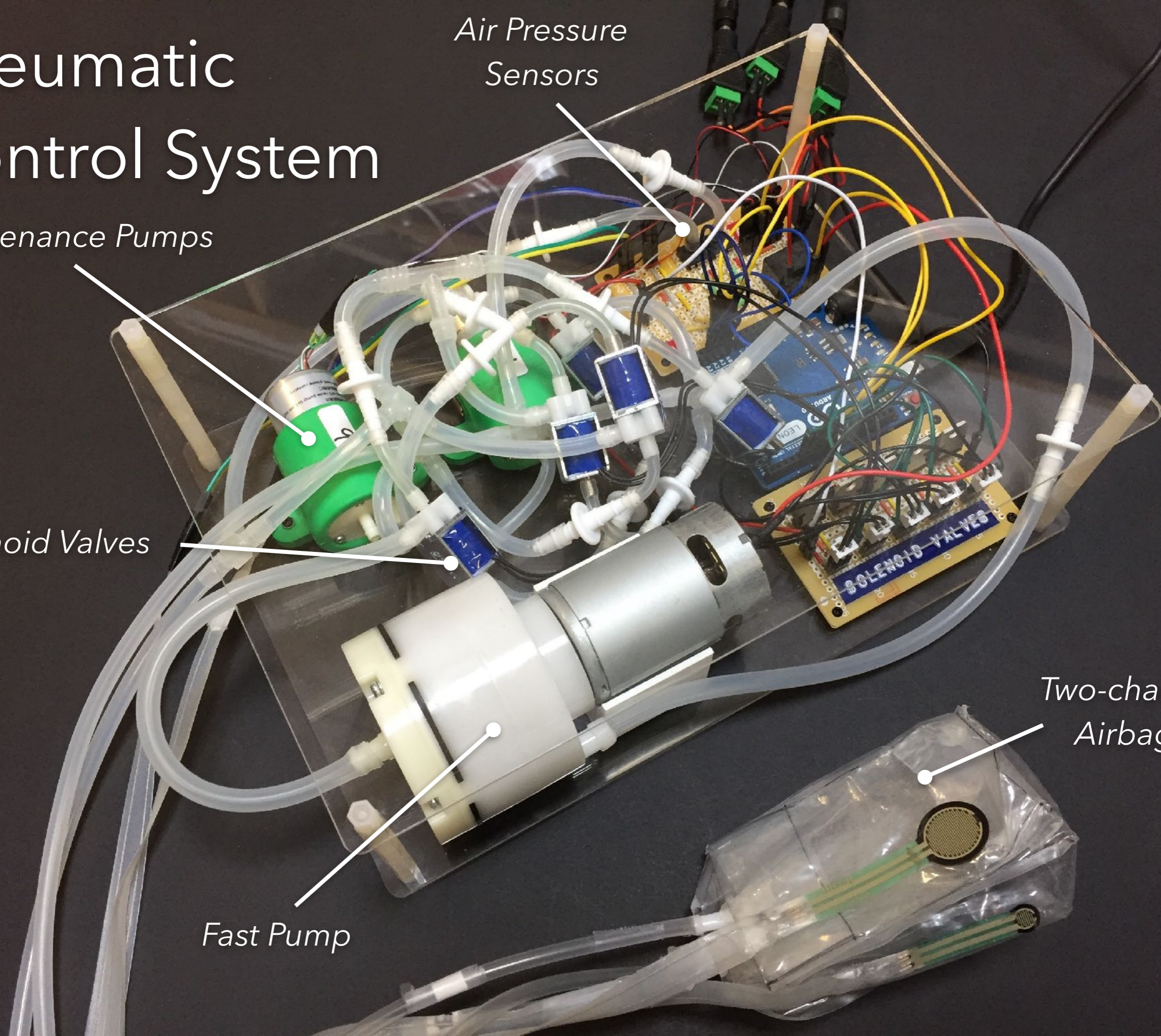
Air Pressure Sensors

Maintenance Pumps

Solenoid Valves

Fast Pump

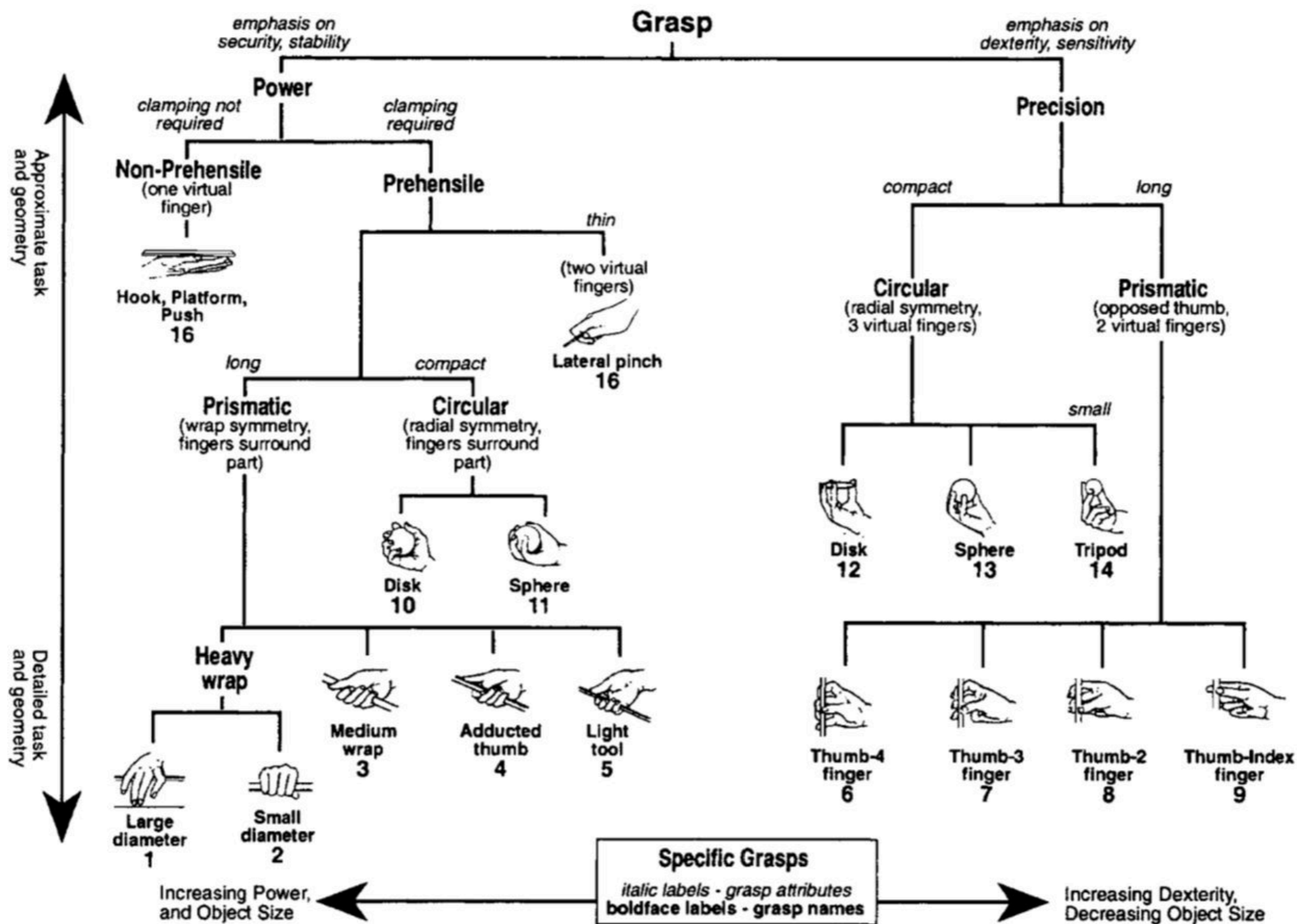
Two-channel Airbags



# Identify Primitive Shapes

## Grasp Taxonomy

*Cutkosky and Howe, 1990.*



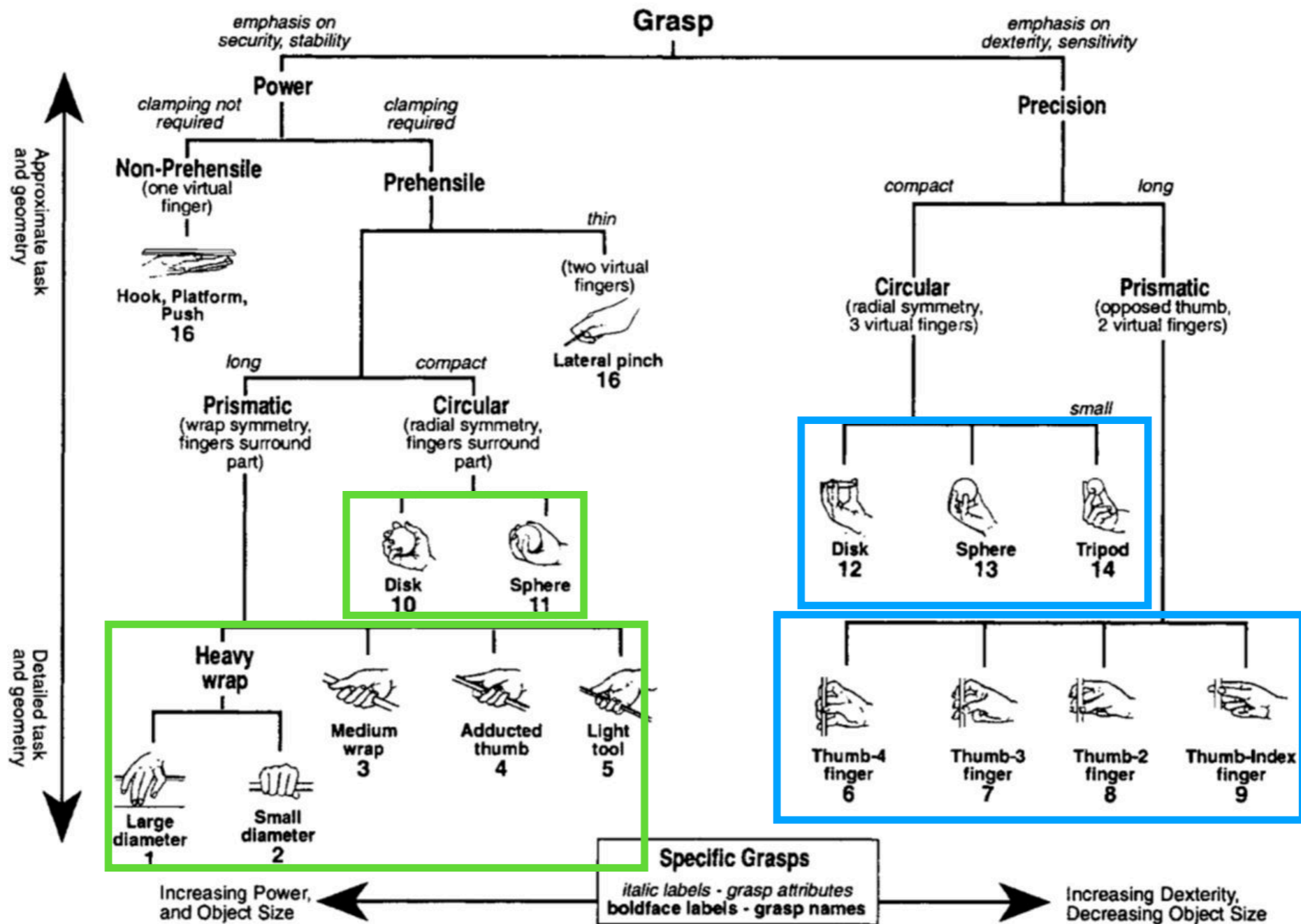
# Identify Primitive Shapes

## Grasp Taxonomy

**Power Grasp**

*Cutkosky and Howe, 1990.*

**Precision Grasp**





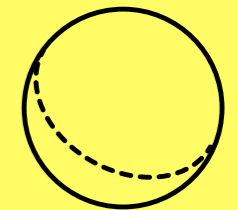
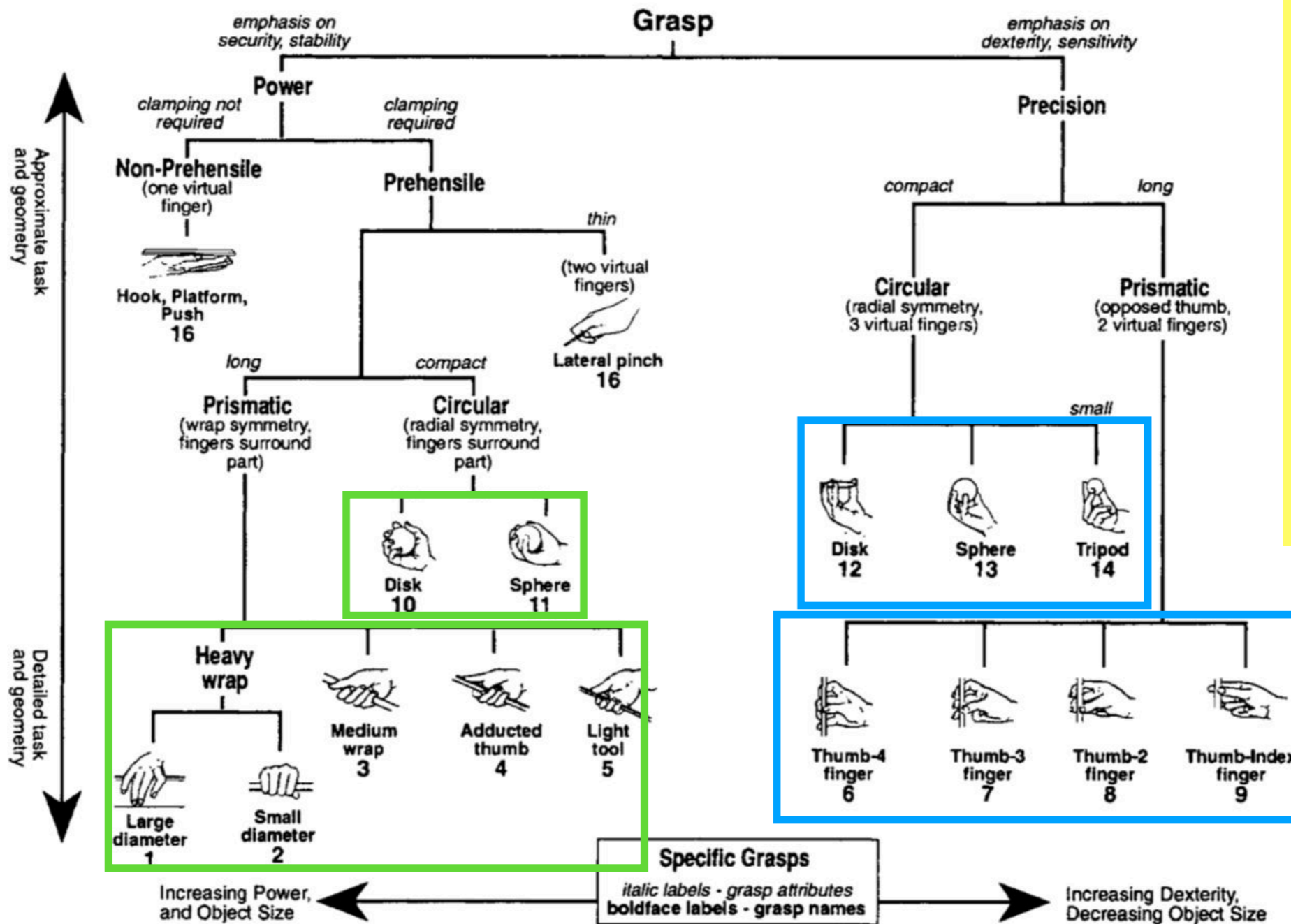
# Identify Primitive Shapes

## Grasp Taxonomy

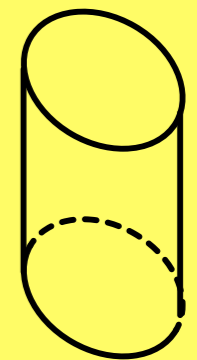
**Power Grasp**

*Cutkosky and Howe, 1990.*

**Precision Grasp**



Sphere



Cylinder

# Identify Primitive Shapes

## VR Game Objects

*111 hand-held objects found in 20 game trailers.*

**Sphere** balls in sports, snowballs, bombs, and grenades, etc.

**Cylinder** rackets, bottles, hammers, and swords, etc.

**Box** sandwiches, books, milk package, and camera, etc.

**Disk** Frisbee

**Cone** carrot

**Hemisphere** bowl

**Others** scissors, clothes, chain, fish, cat, etc.

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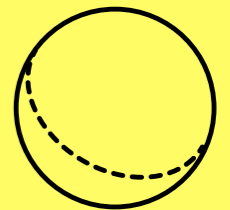
**Box** sandwiches, books, milk package, and camera, etc.

**Disk** Frisbee

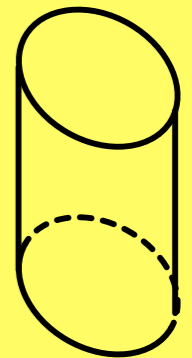
**Cone** carrot

**Hemisphere** bowl

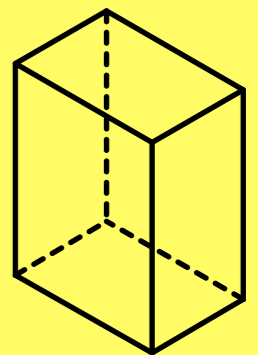
**Others** scissors, clothes, chain, fish, cat, etc.



Sphere



Cylinder

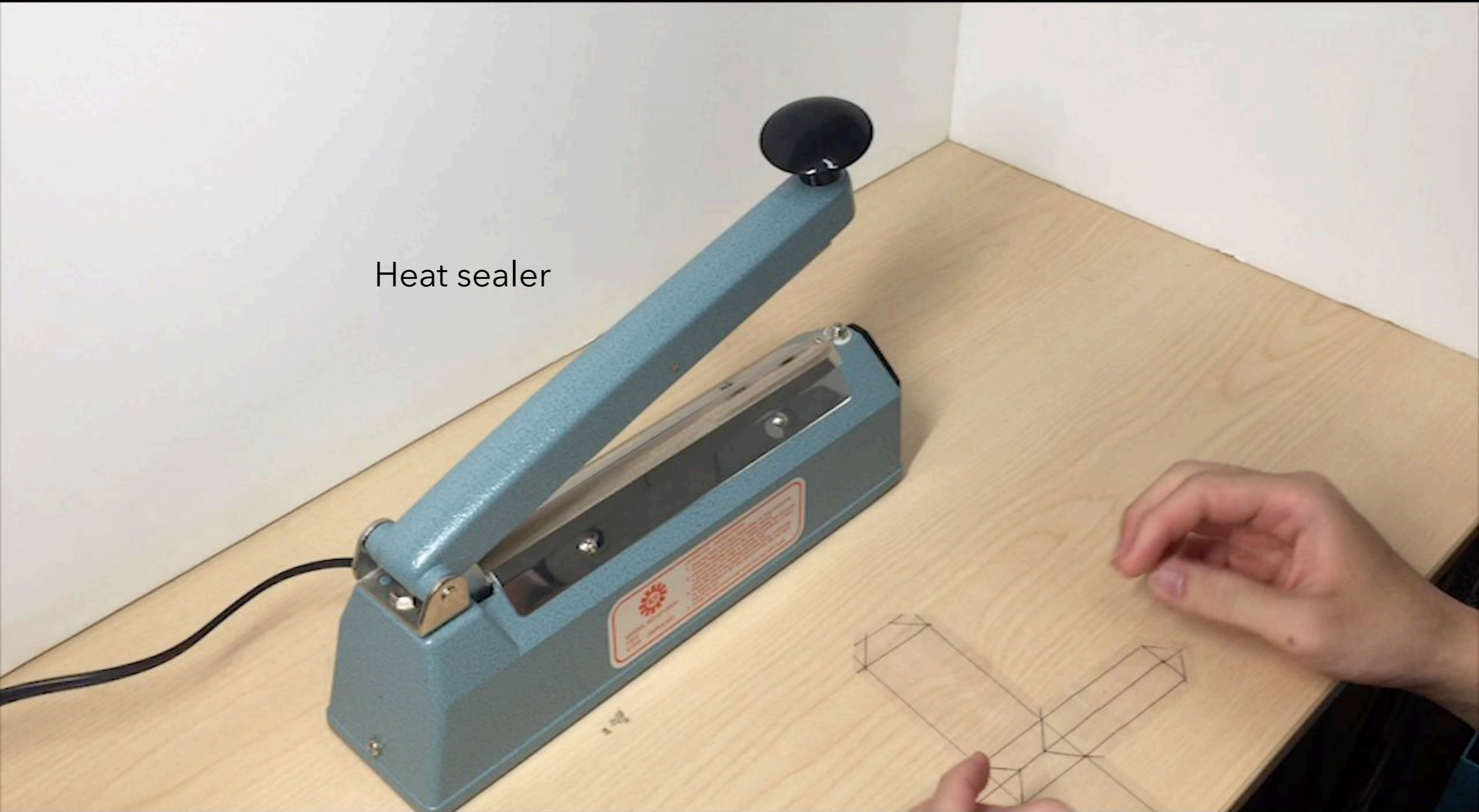


Box

# Material

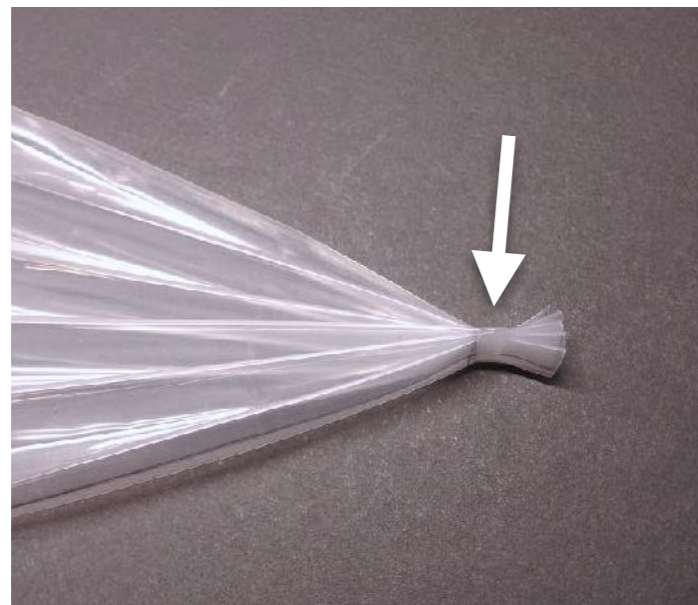
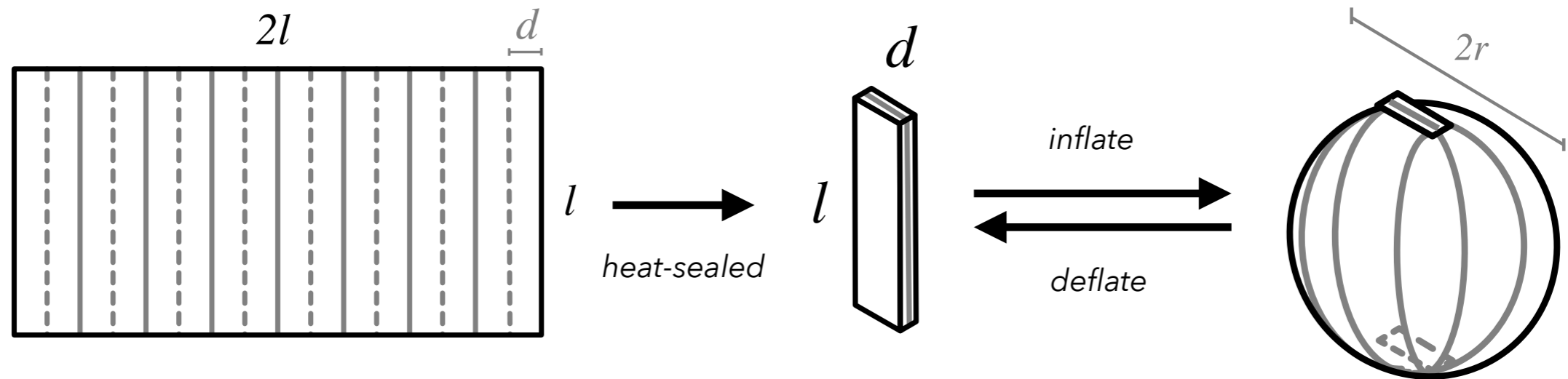
Heat sealer

PE sheet



# Shape Folding Structures

## Sphere

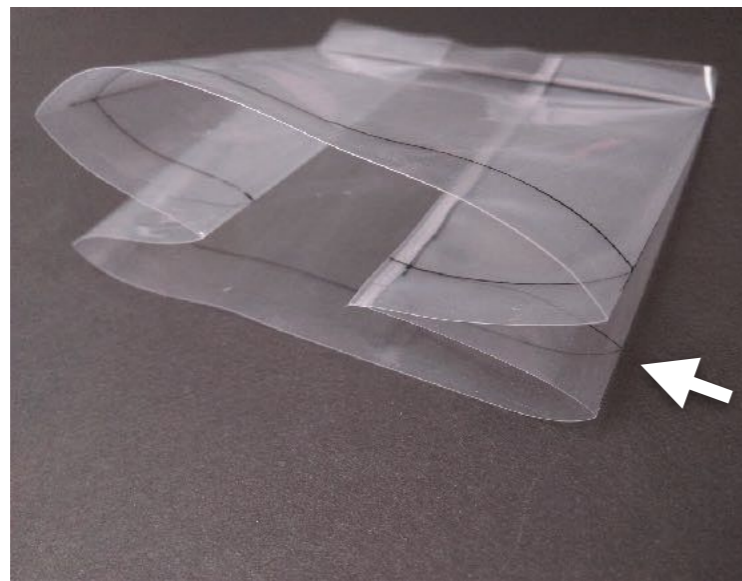
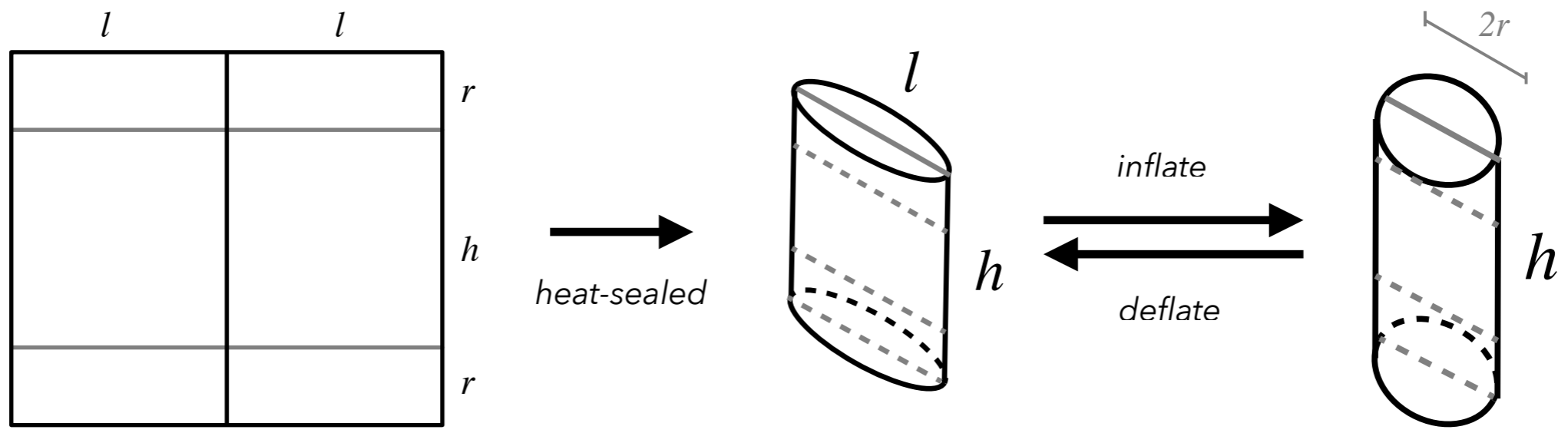


Fabrication detail



Inflation video

# Cylinder

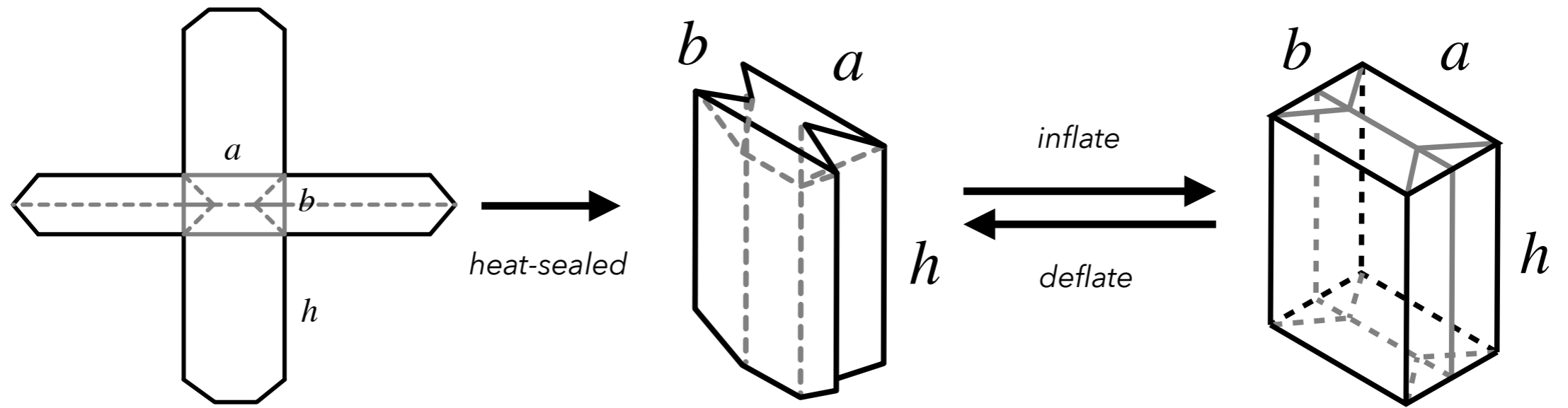


Fabrication detail

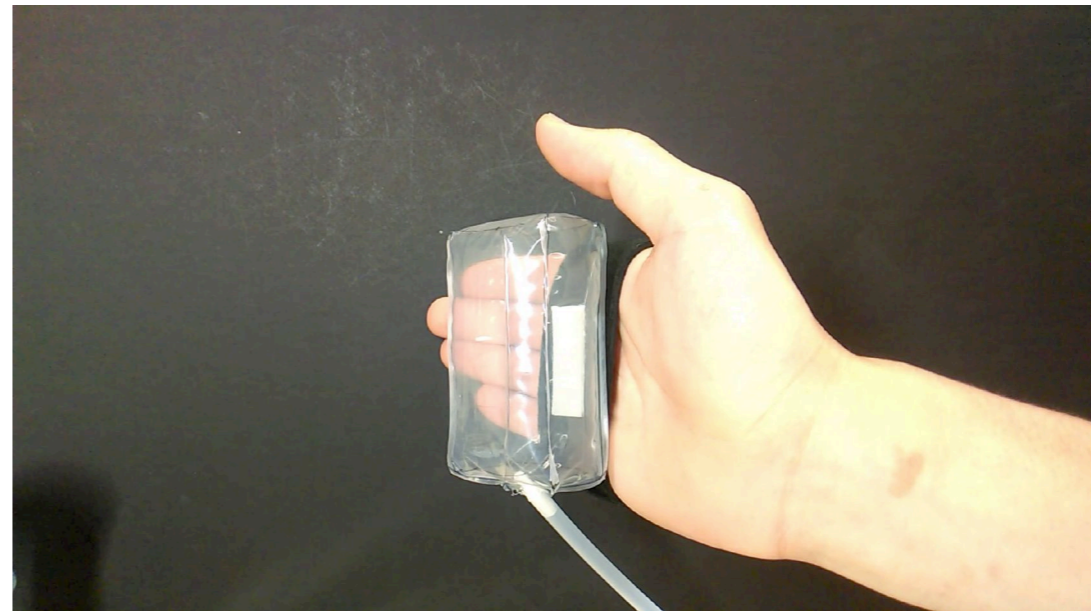


Inflation video

# Rectangular Box



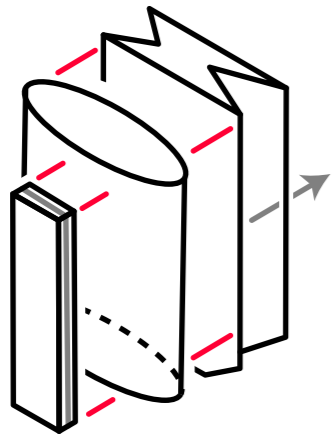
Fabrication detail



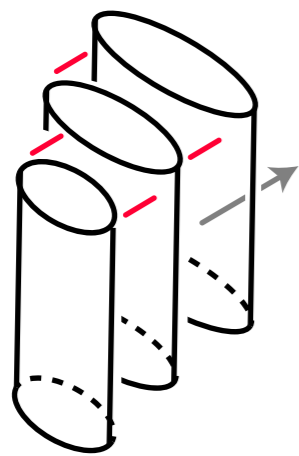
Inflation video

# Props on Palm

## Prop Stacking



Shape Stacking

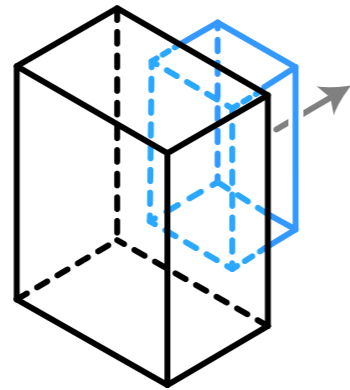


Size Stacking

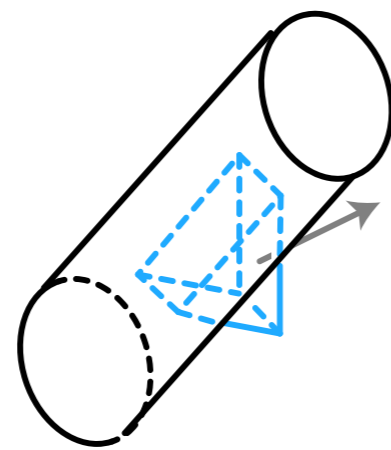




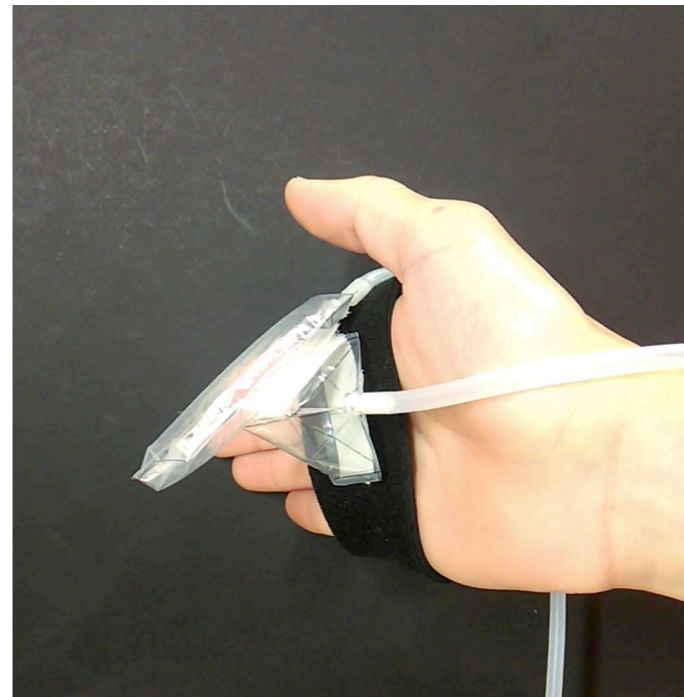
# Prop Extension



Parallel Extension



Tilt Extension

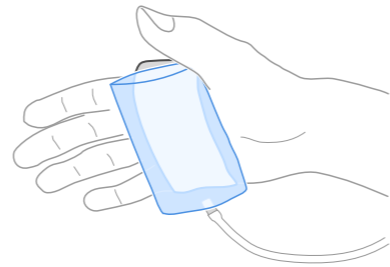


# Prop Sensing

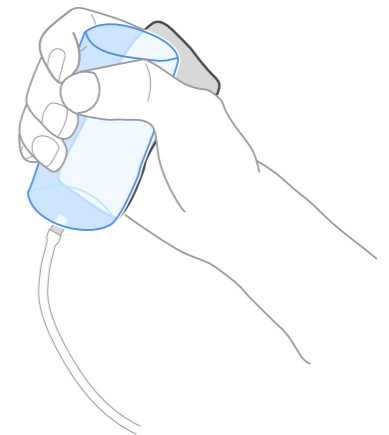
## Finger Operation



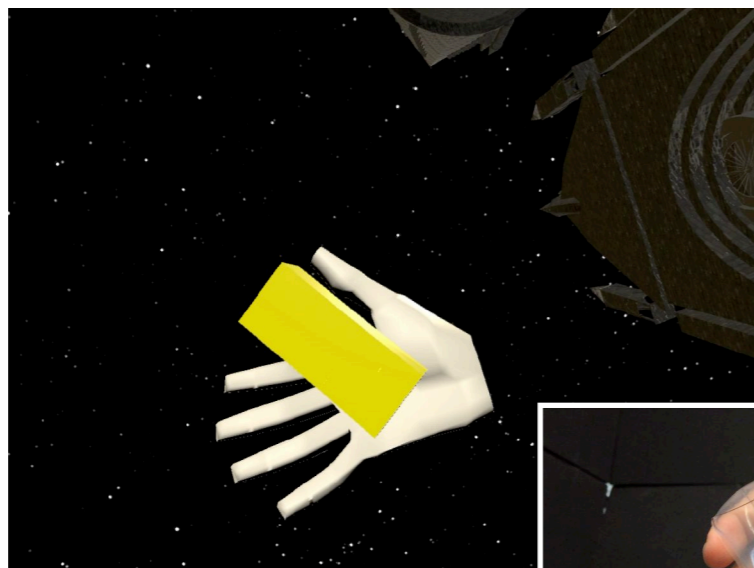
Leap Motion



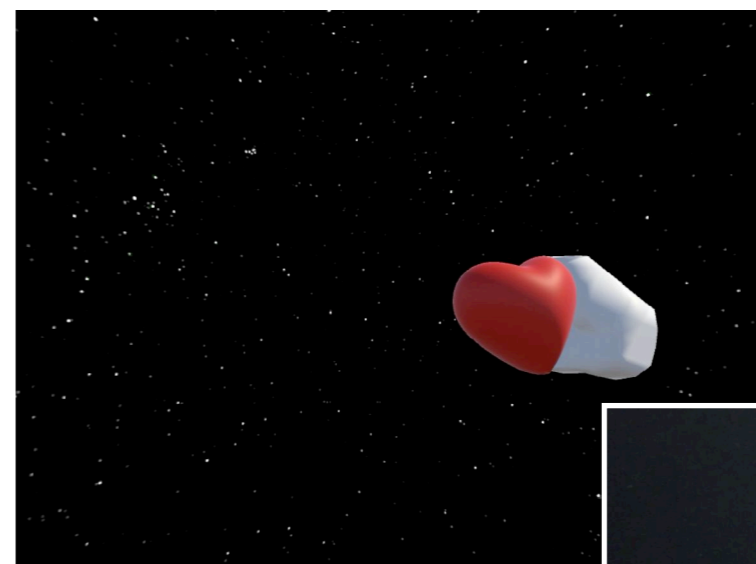
Force-Sensitive Resisters (FSRs)



## Object Properties Emulation



Elasticity



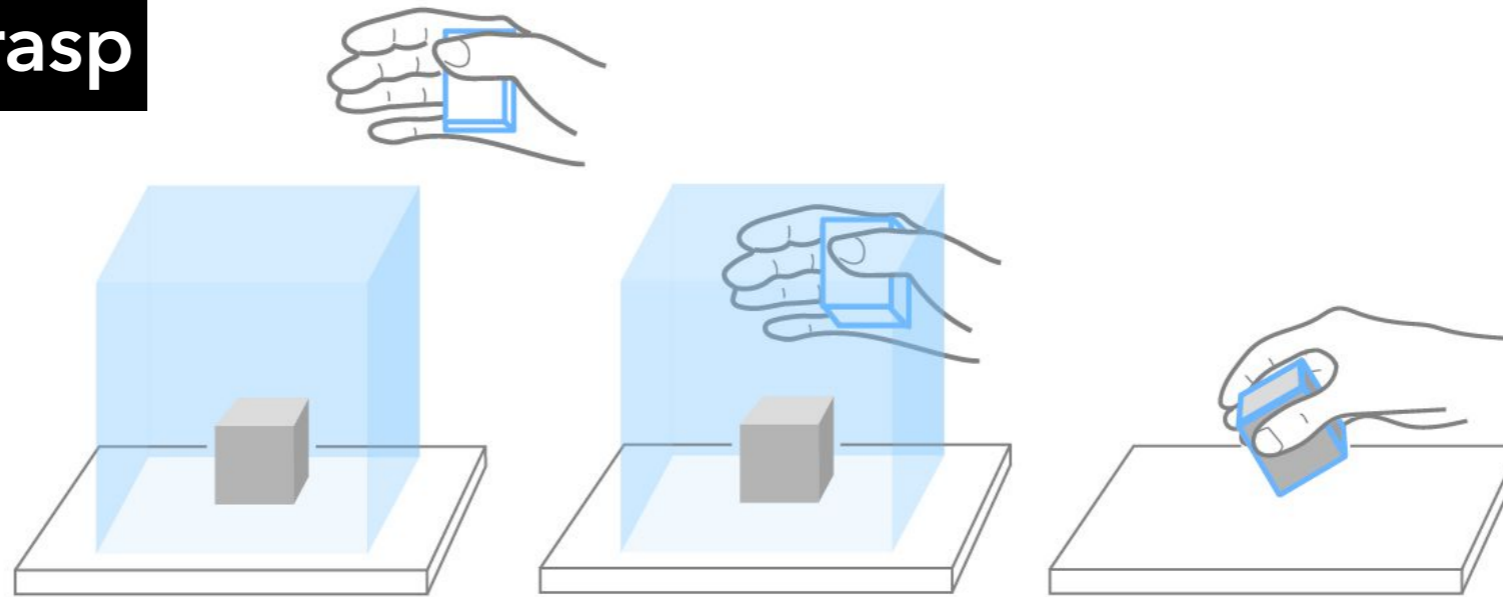
Heartbeat



# Incorporation into VR

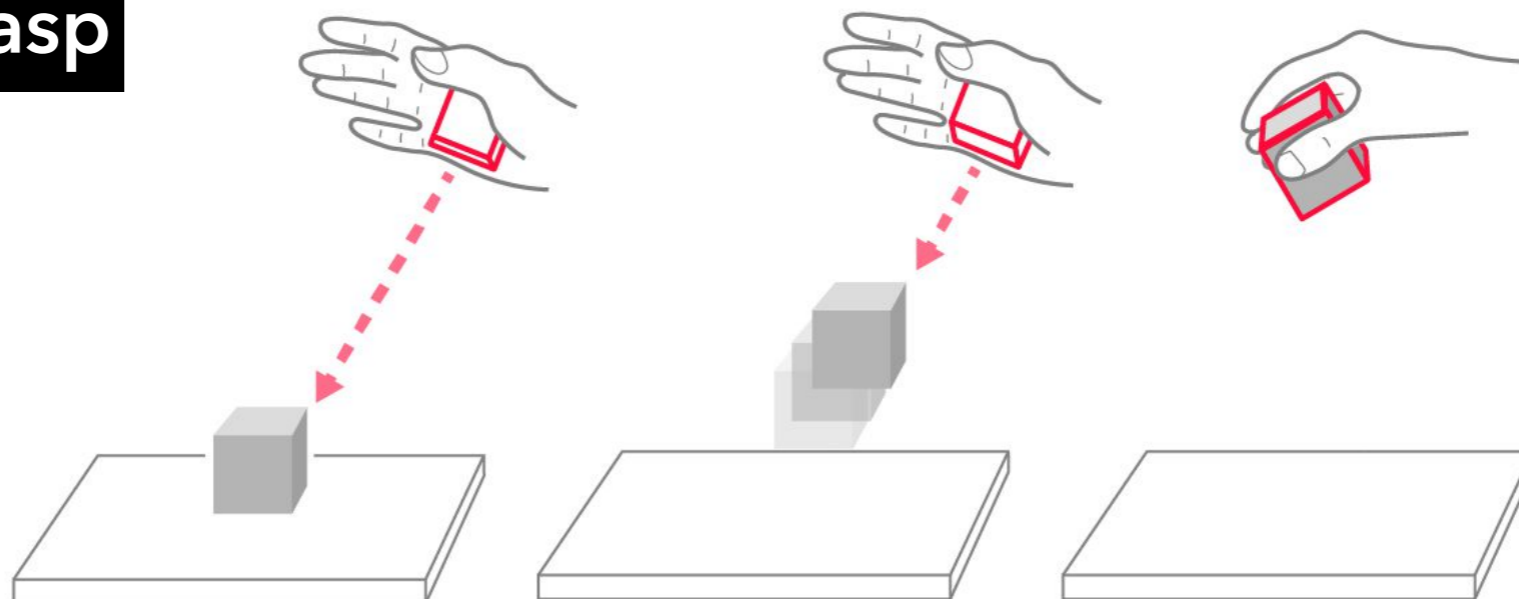
## Natural Grasp

*Grasp in place.*



## Magic Grasp

*"Summoning."*

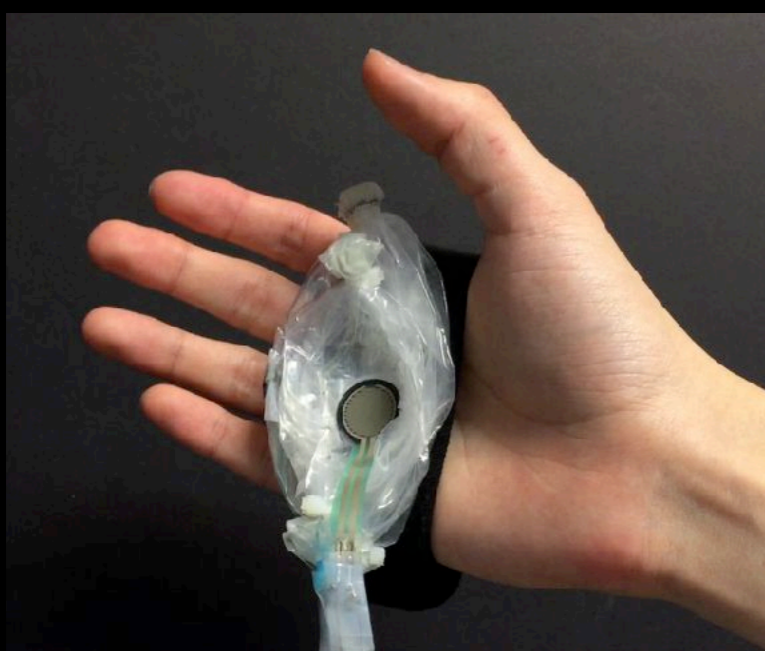


# Demo Applications

# Demo Application

## Quidditch Sports Training





Flat State



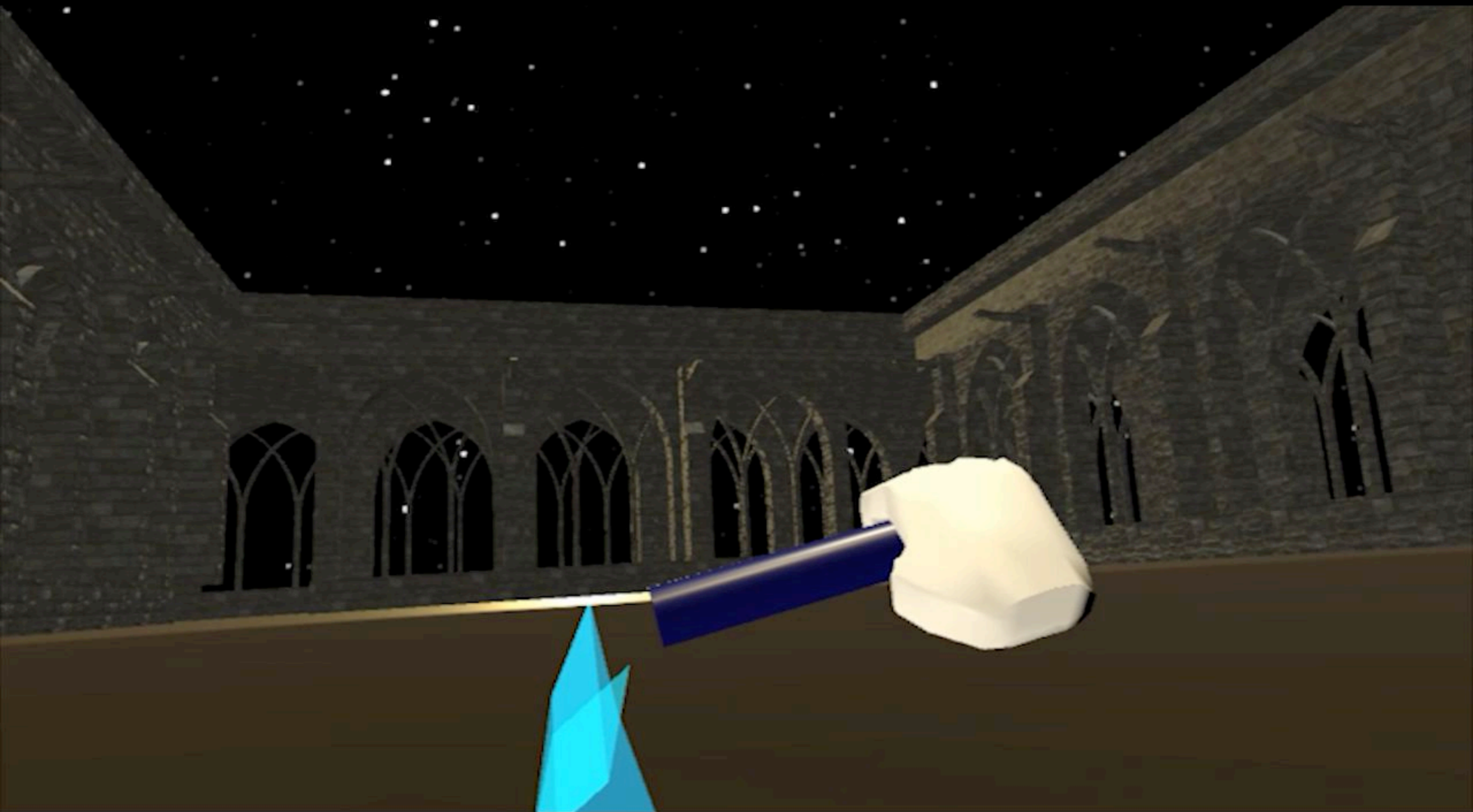
Ball (Large Sphere)

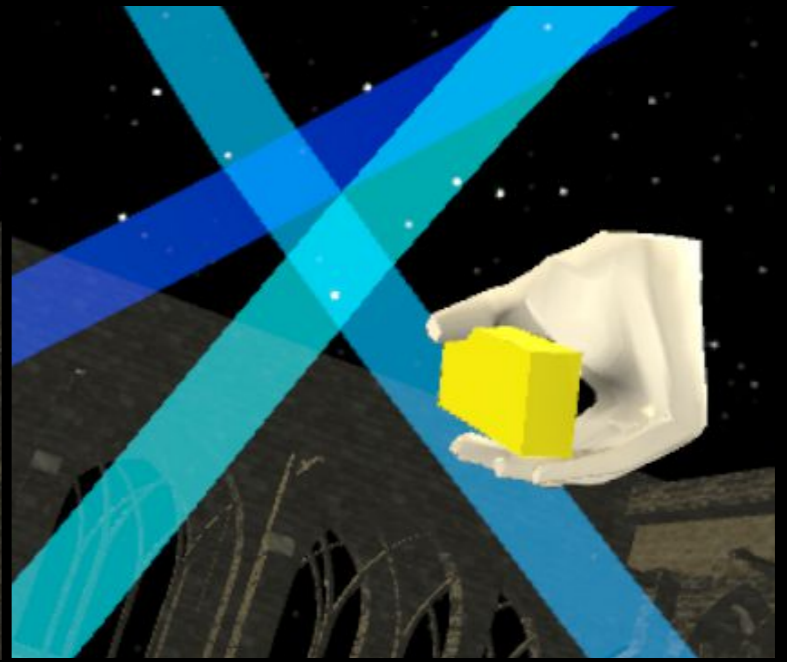
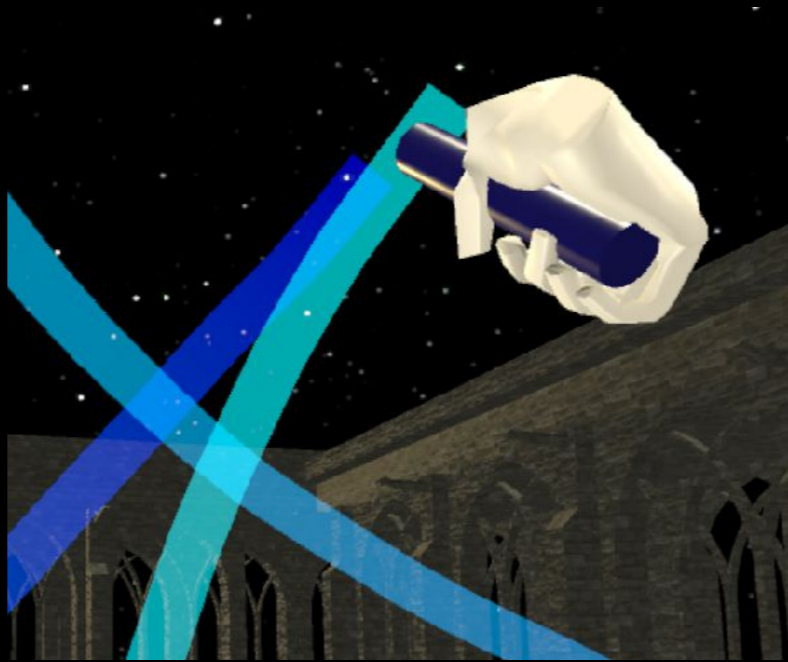
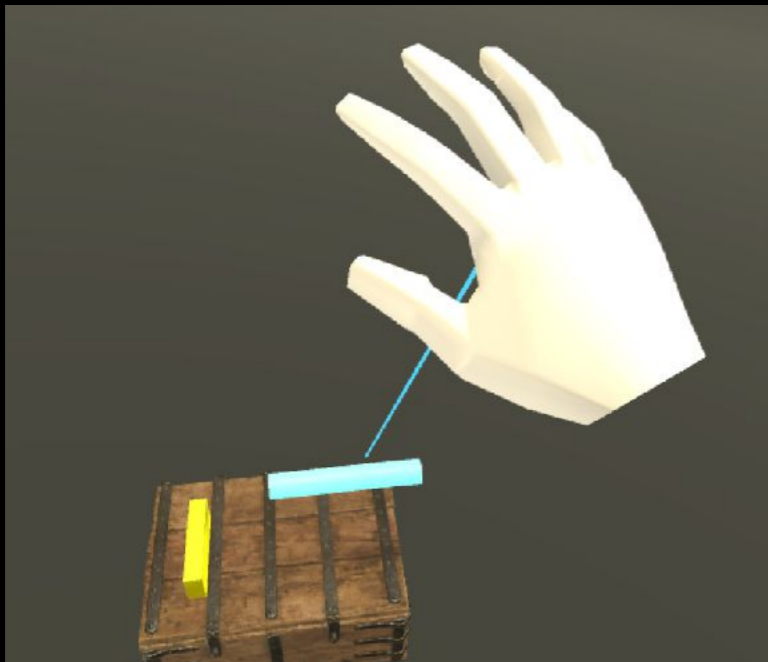


Snitch (Small Sphere)

# Demo Application

## Magic Brush Painting





Flatten State

Brush (Cylinder)

Eraser (Extended Box)



# User Studies

# User Study 1

## Visual Size Acceptance Range

Can PuPoP leverage visual dominance effect to allow a single prop to represent a range of similar visual sizes?



*Physical Prop*

≈

*Acceptance Range*



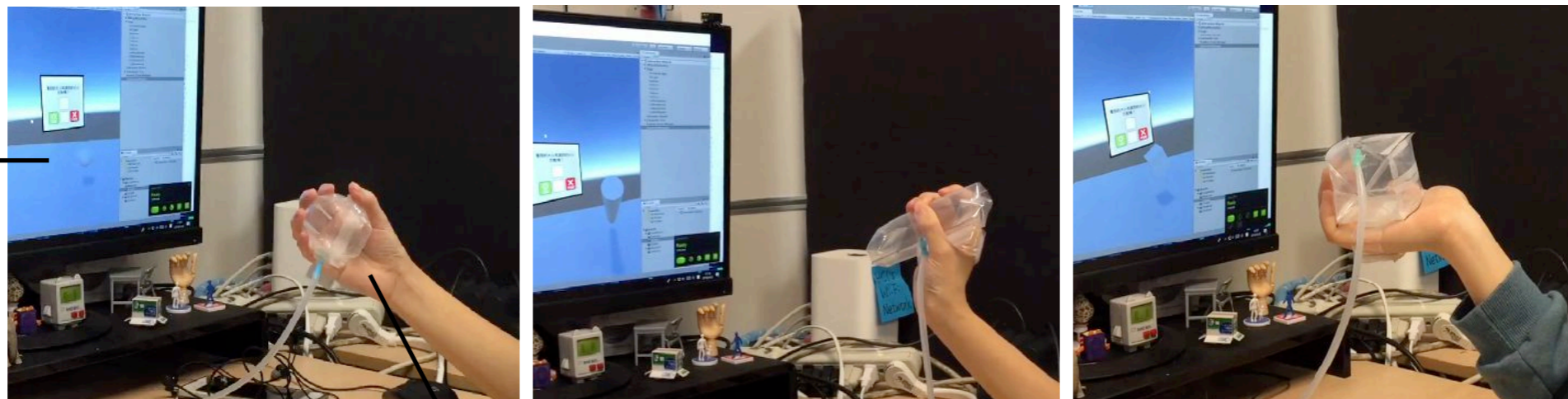
*Visual Counterpart*

# User Study 1

## Visual Size Acceptance Range

Can PuPoP leverage visual dominance effect to allow a single prop to represent a range of similar visual sizes?

Visual  
(mirrored from  
the VR headset)



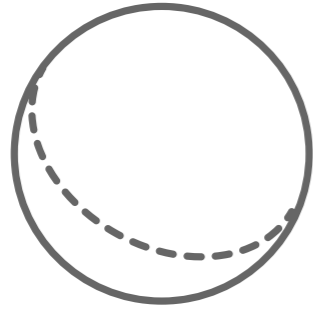
Sphere

Prop

Cylinder

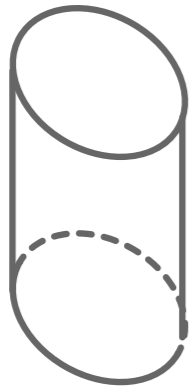
Box

Using one-up-one-down adaptive staircase method.  
Participants answered YES or NO on whether the visual size matches the physical one.



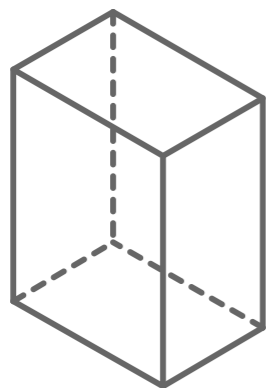
**Sphere**

Physical Size	<b>Small</b>	<b>Medium</b>	<b>Large</b>
<i>Visual Size Upper Bound</i>	63.2	75.5	95.3
<i>Visual Size Lower Bound</i>	46.0	60.5	73.4



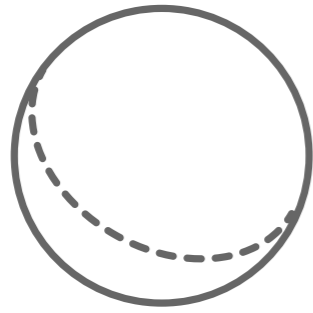
**Cylinder**

Physical Size	<b>Small</b>	<b>Medium</b>	<b>Large</b>
<i>Visual Size Upper Bound</i>	38.0	54.4	70.8
<i>Visual Size Lower Bound</i>	28.7	42.4	54.1



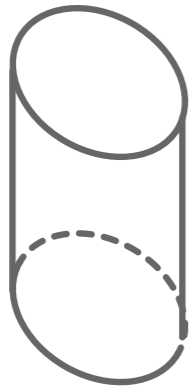
**Box**

Physical Size	<b>Small</b>	<b>Medium</b>	<b>Large</b>
<i>Visual Size Upper Bound</i>	59.2	69.7	88.7
<i>Visual Size Lower Bound</i>	43.7	53.4	68.2



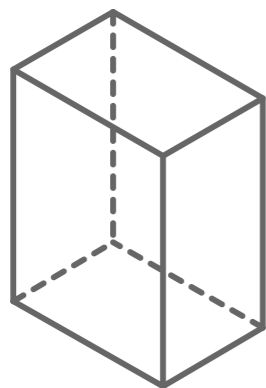
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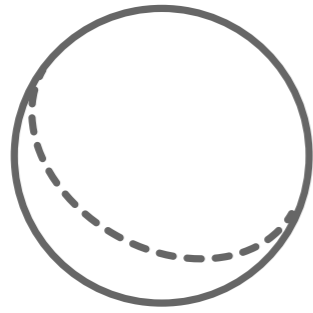
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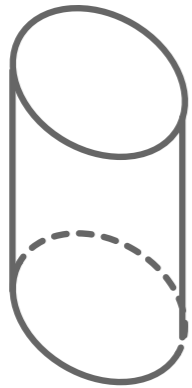
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*Average Upper Bound*

**36.2%**

Larger than the physical size

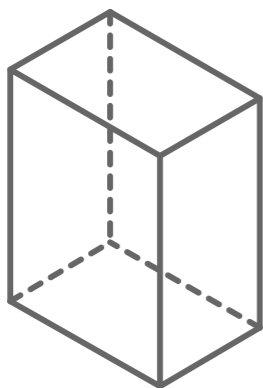


**Cylinder**

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*Average*

*Lower Bound*



**Box**

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The physical size

# User Study 2

## VR Enjoyment & Object Realism

What is effect of PuPoP on VR application enjoyment and object realism, compared to other interfaces?

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## VR Enjoyment & Object Realism

What is effect of PuPoP on VR application enjoyment and object realism, compared to other interfaces?



PuPoP

Controller  
(HTC VIVE)

Free-hand Manipulation  
(Leap Motion)

Participants rated enjoyment and object realism in a continuous 7-point Likert Scale.



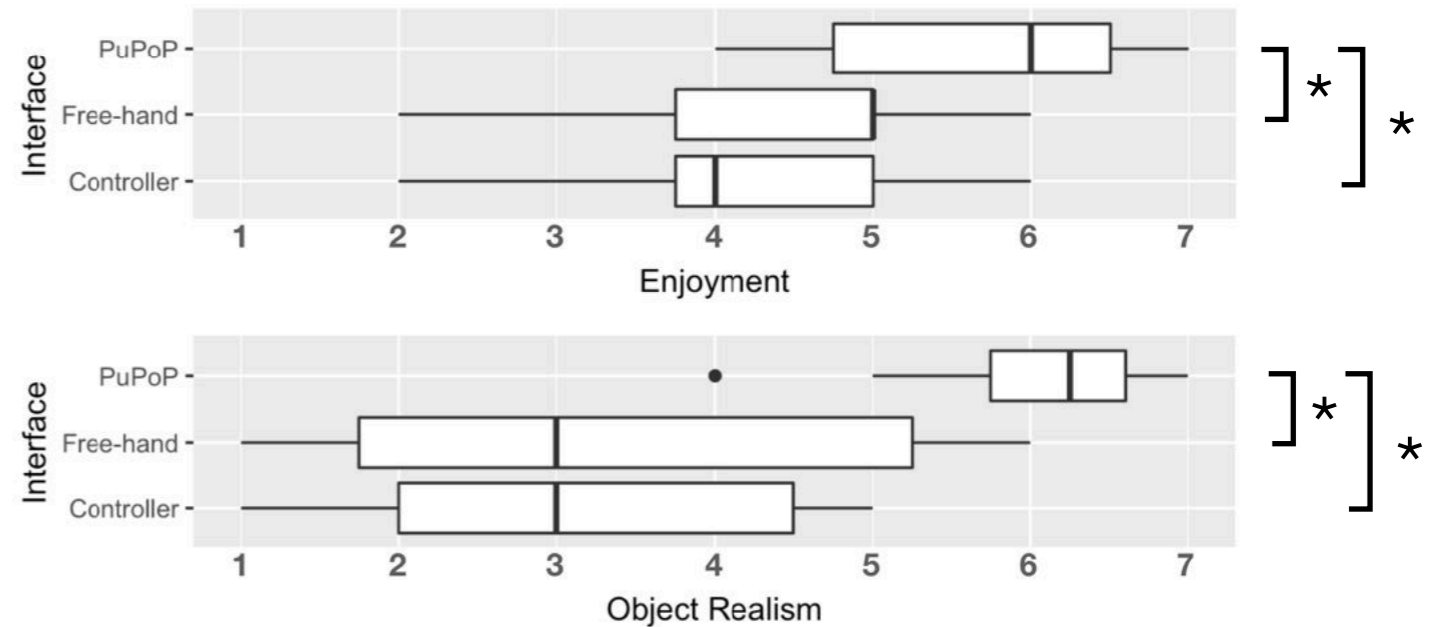
# VR Enjoyment & Object Realism

## Quidditch

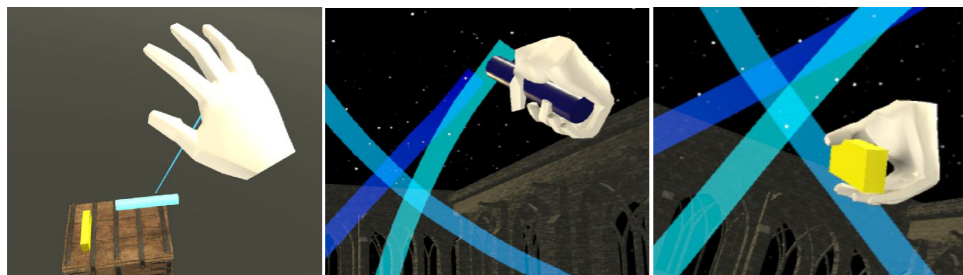


"I felt like throwing a real ball!"

"I could physically catch the Snitch!"

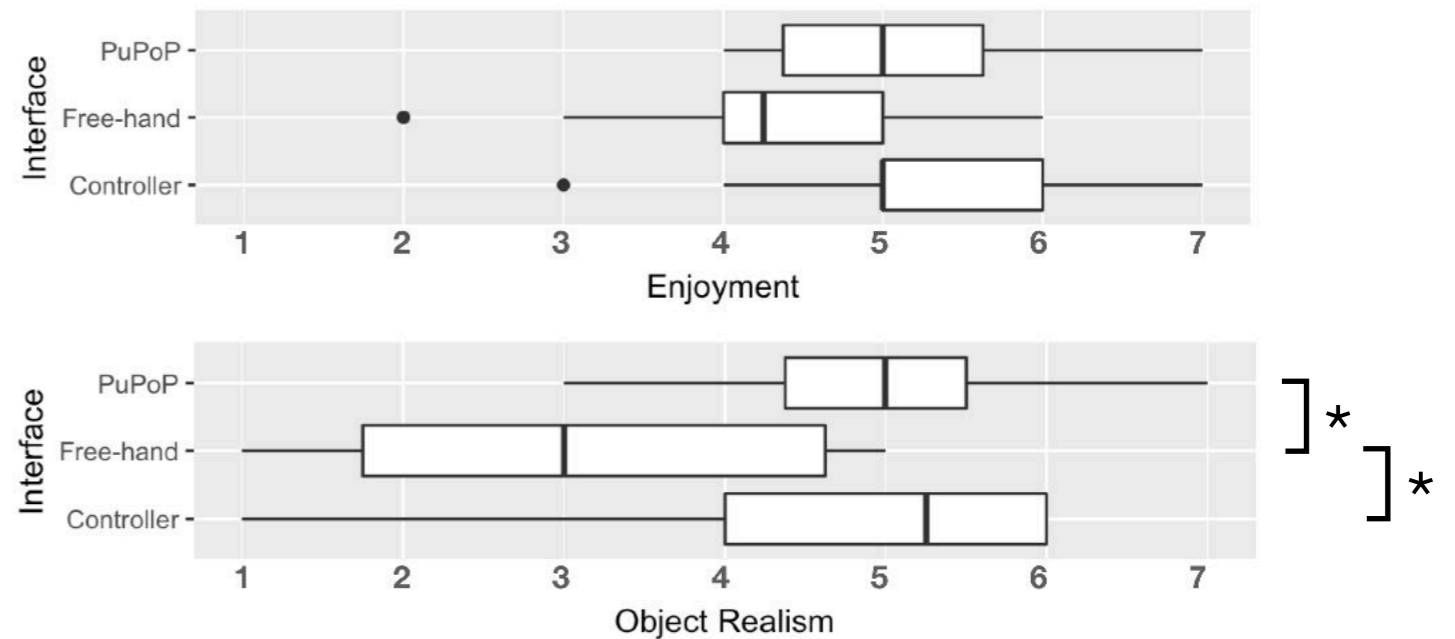


## Painting



"The brush felt too soft." 🥲

"The eraser was definitely an eraser!"



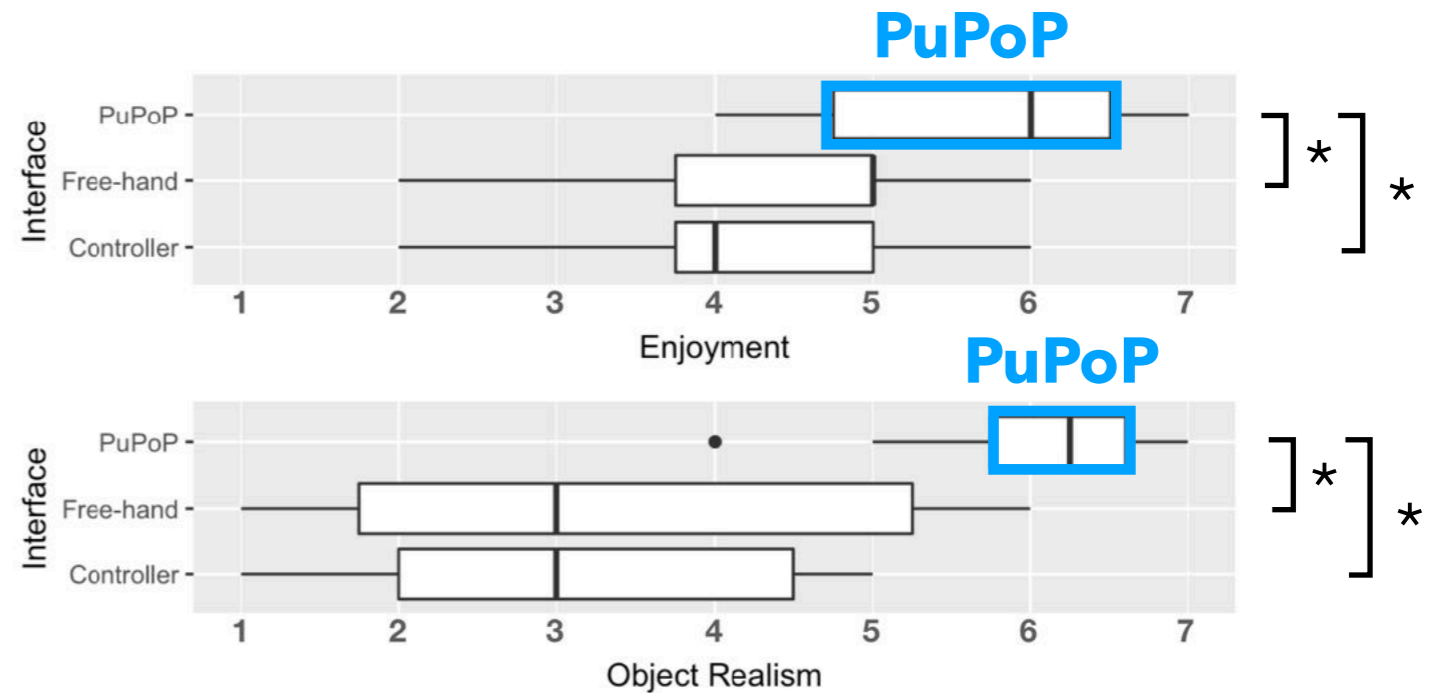
# VR Enjoyment & Object Realism

## Quidditch

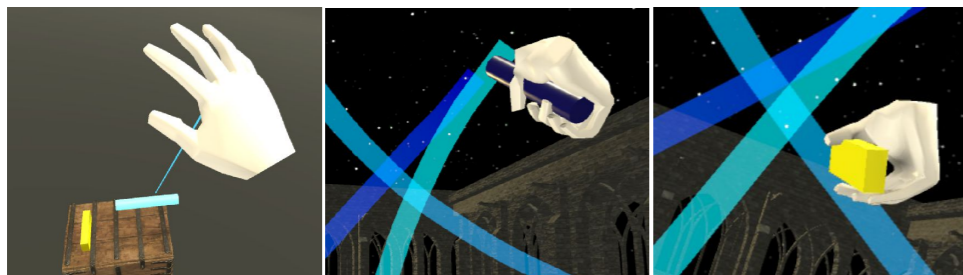


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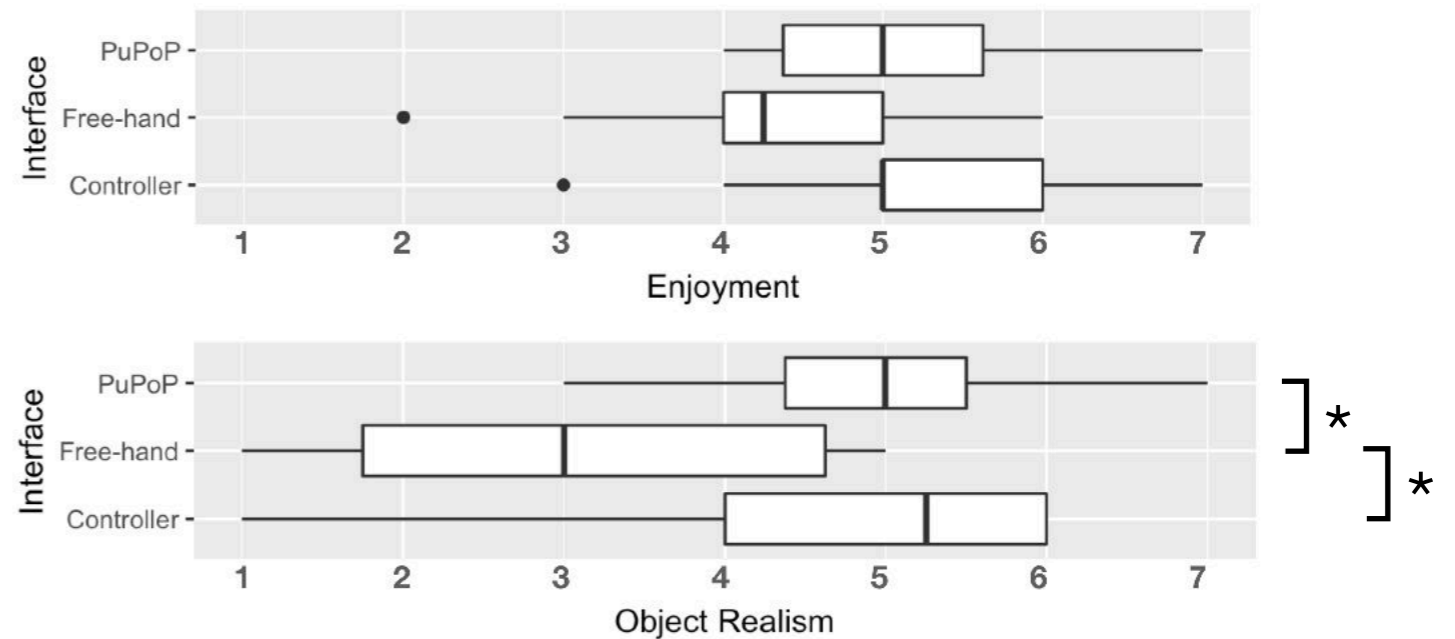


## Painting



"The brush felt too soft." 🥲

"The eraser was definitely an eraser!"



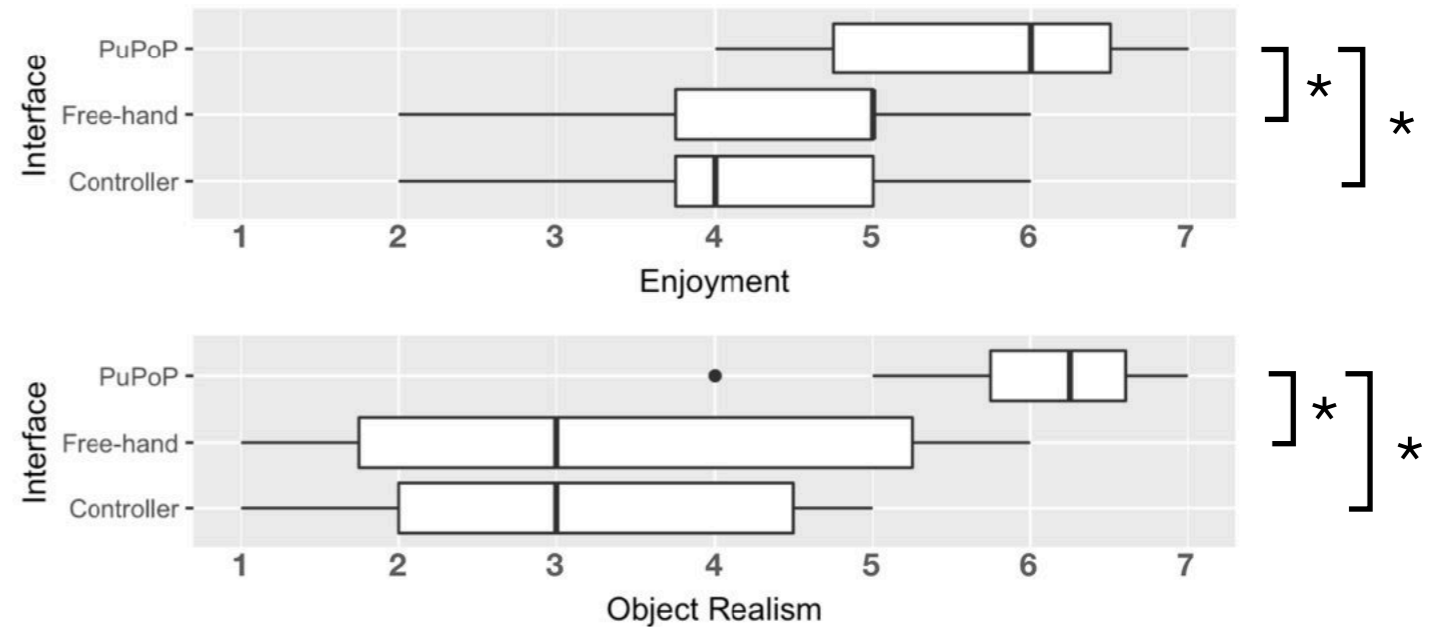
# VR Enjoyment & Object Realism

## Quidditch

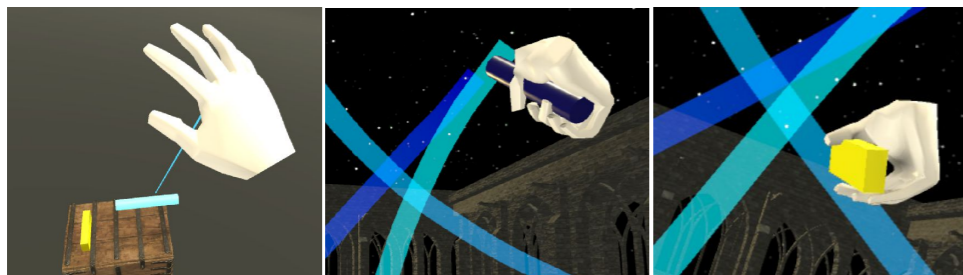


"I felt like throwing a real ball!"

"I could physically catch the Snitch!"

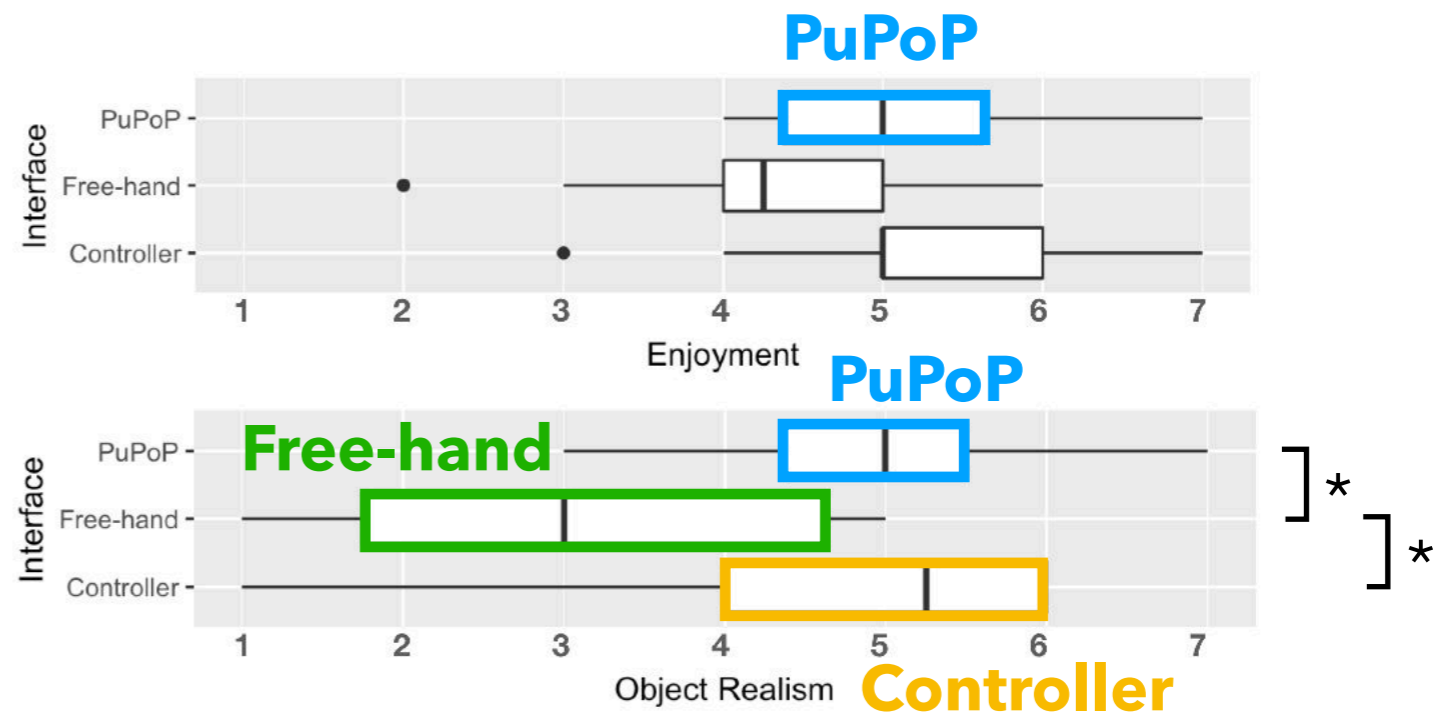


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# Limitations & Future Work

1. Grounding.
2. Illusion.
3. Portability & Inflation time.
4. Stiffness.
5. Complex shapes.

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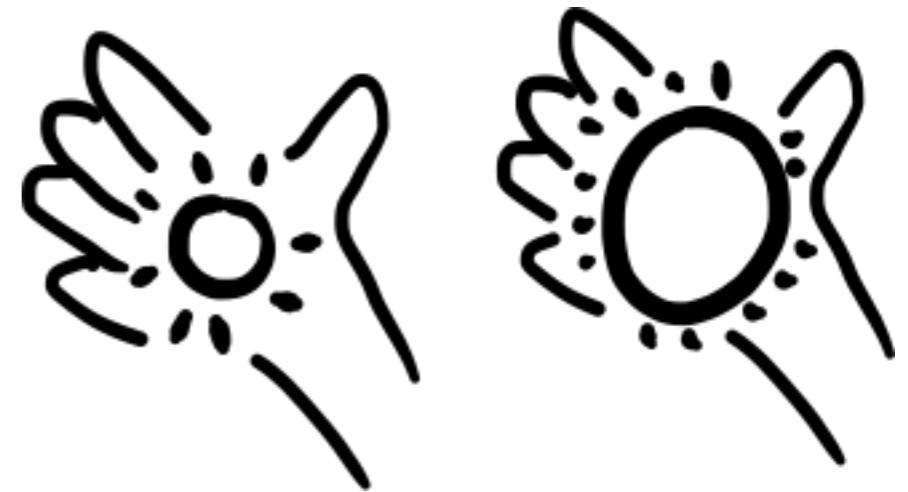
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# Conclusions

1. The concept of a light-weight wearable Pop-up Prop on Palm (PuPoP) for VR.
2. The design and implementation of a set of PuPoP shape structures, including stacking, extension and sensing.
3. Two user studies to understand visual size acceptance range of PuPoP and evaluate the interface.

